

# Deep Learning for Data Science

## DS 542

<https://dl4ds.github.io/fa2025/>

Deep Neural Networks



# Deep neural networks

- Composing two networks
- Combining the two networks into one
- Hyperparameters
- Notation change and general case
- Shallow vs. deep networks

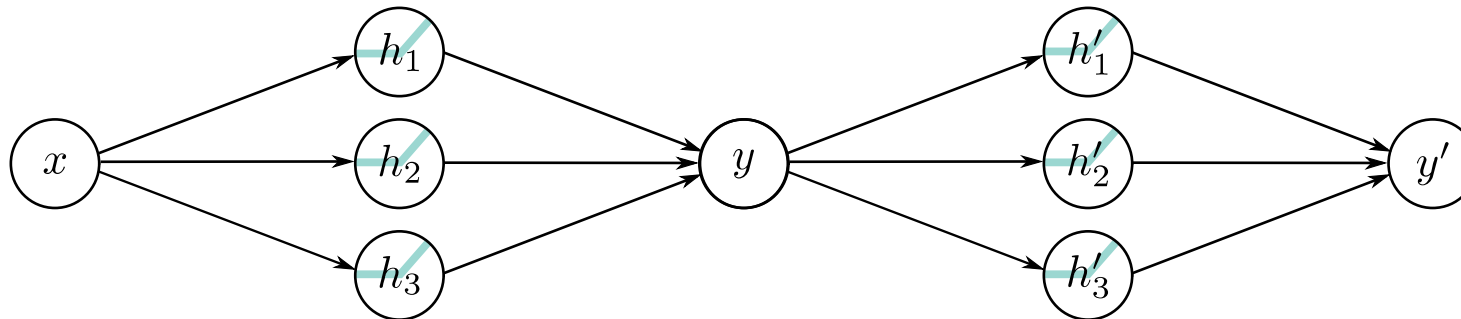
# Composing two networks.

Network 1:

$$\begin{aligned}h_1 &= a[\theta_{10} + \theta_{11}x] \\h_2 &= a[\theta_{20} + \theta_{21}x] \\h_3 &= a[\theta_{30} + \theta_{31}x]\end{aligned}$$
$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

Network 2:

$$\begin{aligned}h'_1 &= a[\theta'_{10} + \theta'_{11}y] \\h'_2 &= a[\theta'_{20} + \theta'_{21}y] \\h'_3 &= a[\theta'_{30} + \theta'_{31}y]\end{aligned}$$
$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$

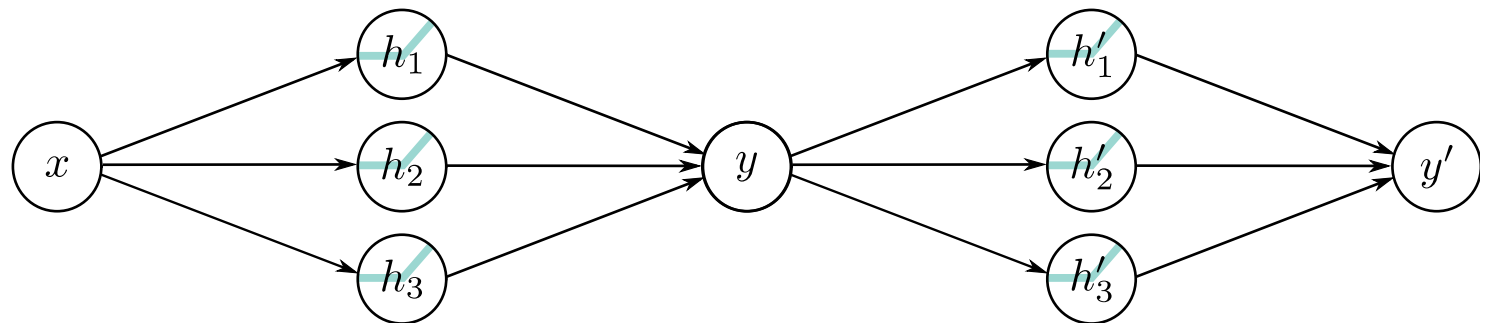
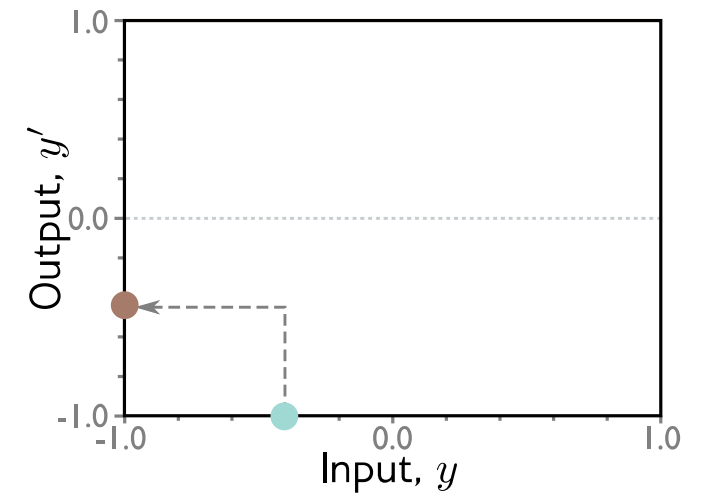
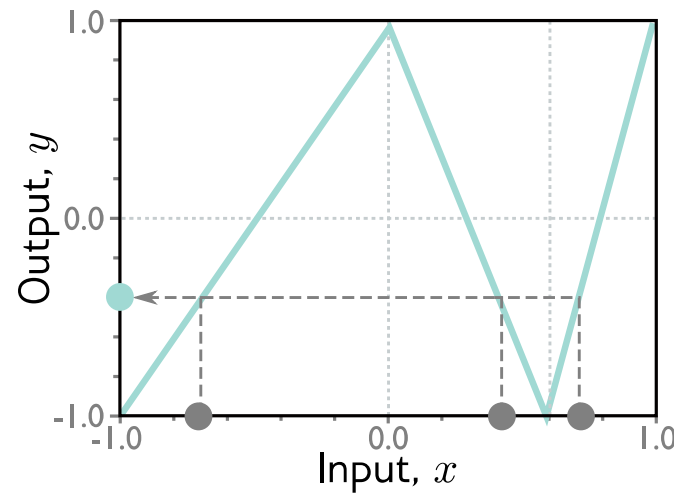


# Composing two networks: Example

Assume:

- ReLU Activation
- Slopes and Intercepts as shown
- 3 hidden units in each

Example: Pick parameters so that  
 $x \in [-1,1]$  maps to  
 $y \in [-1,1]$  with alternating slope



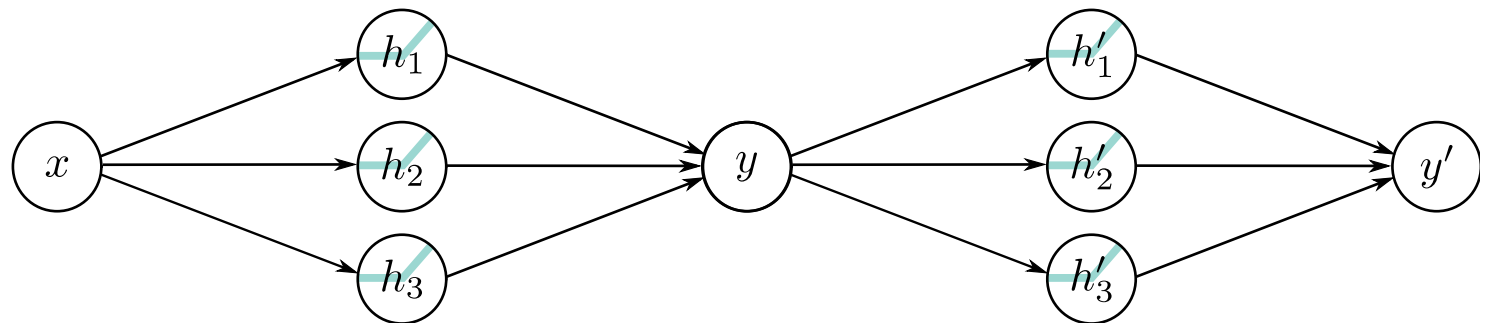
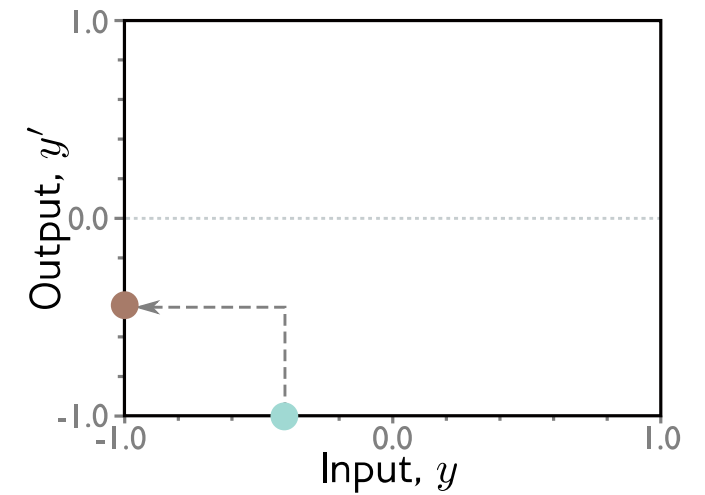
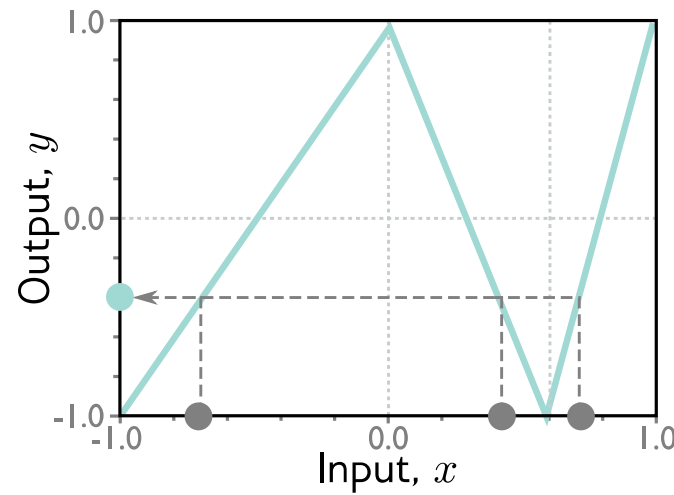
# Composing two networks: Example

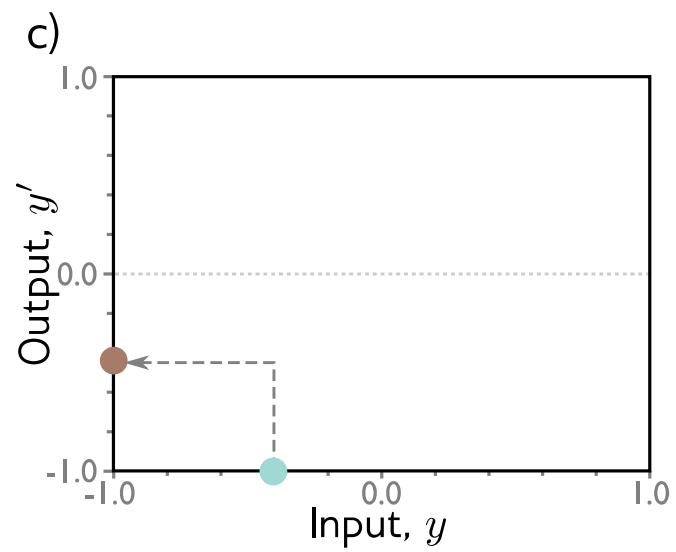
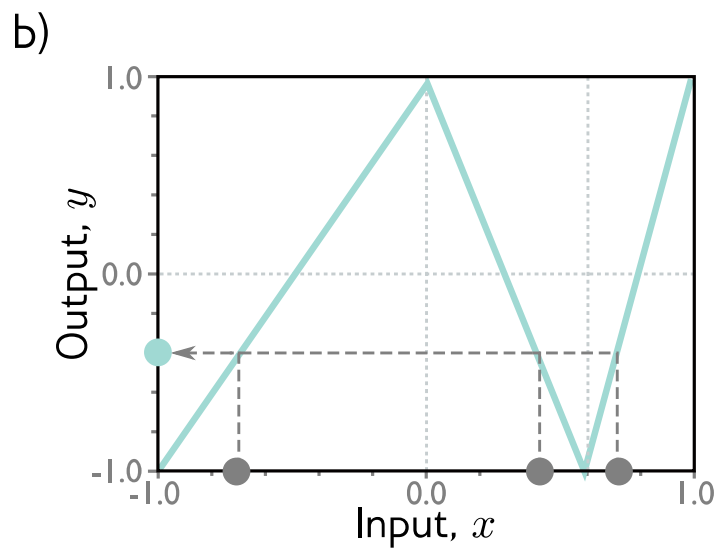
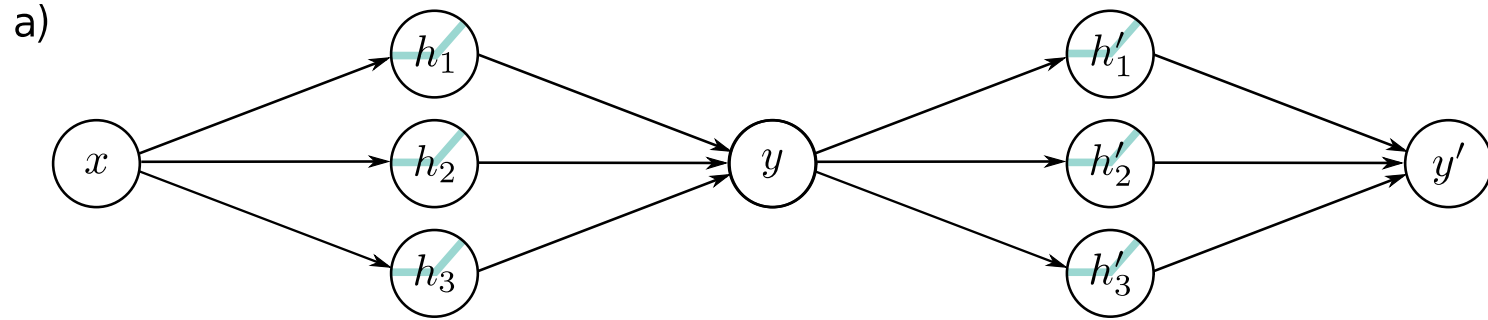
Assume:

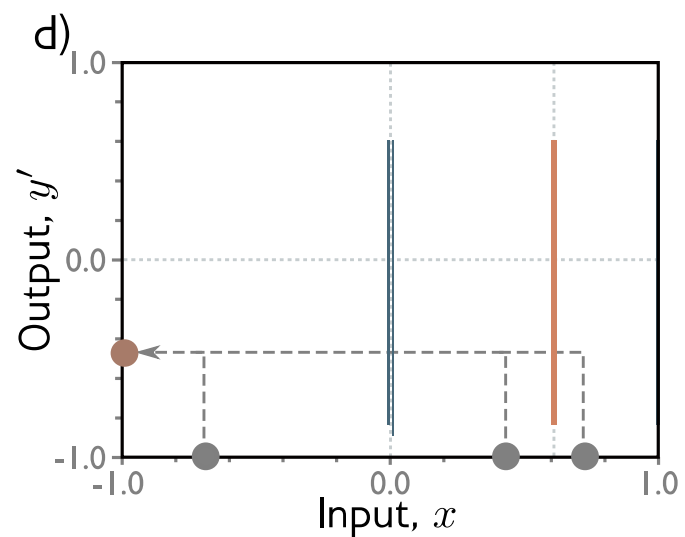
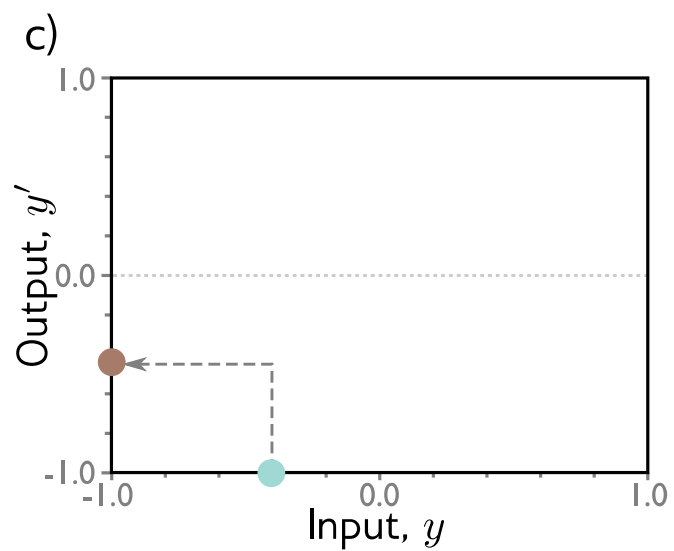
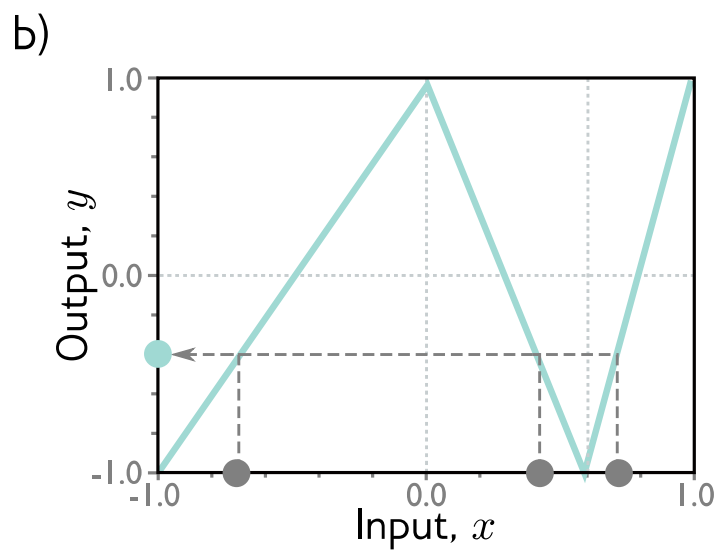
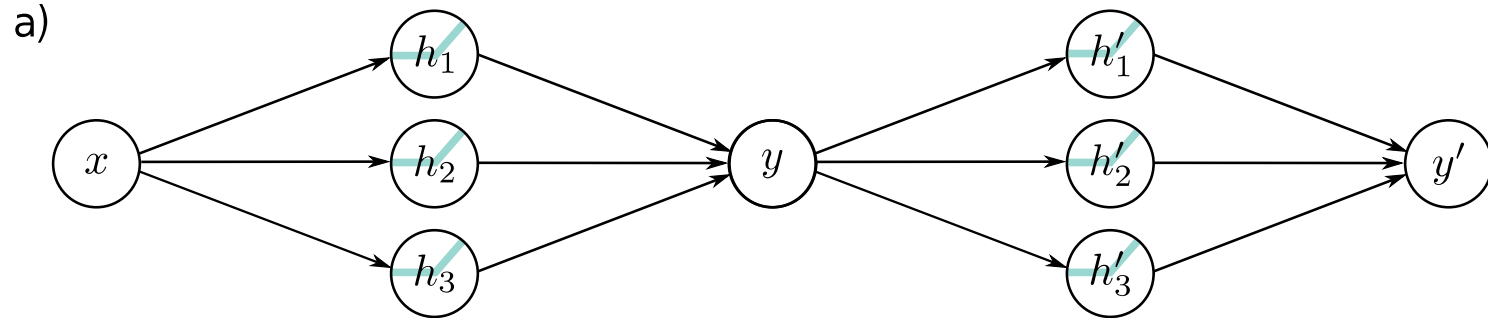
- ReLU Activation
- Slopes and Intercepts as shown
- 3 hidden units in each

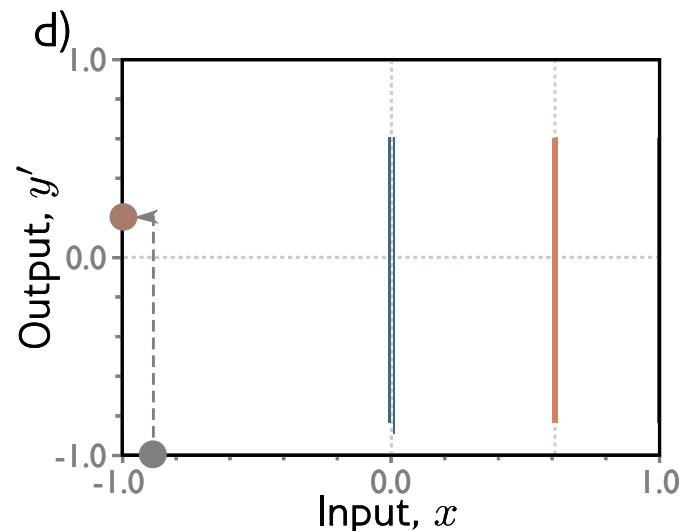
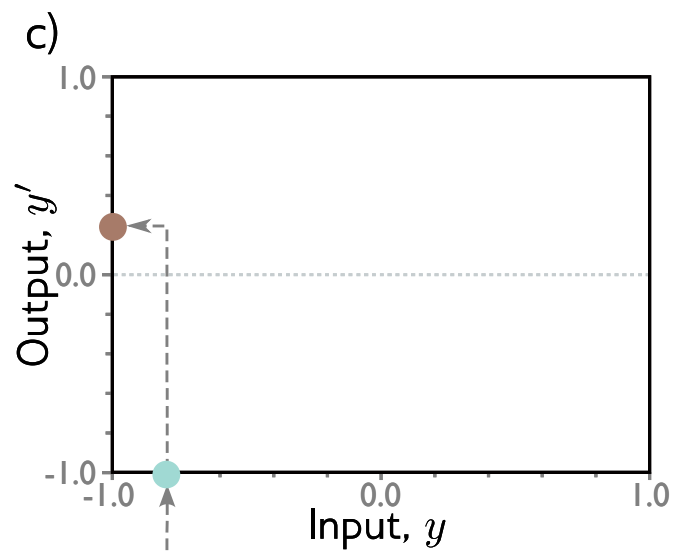
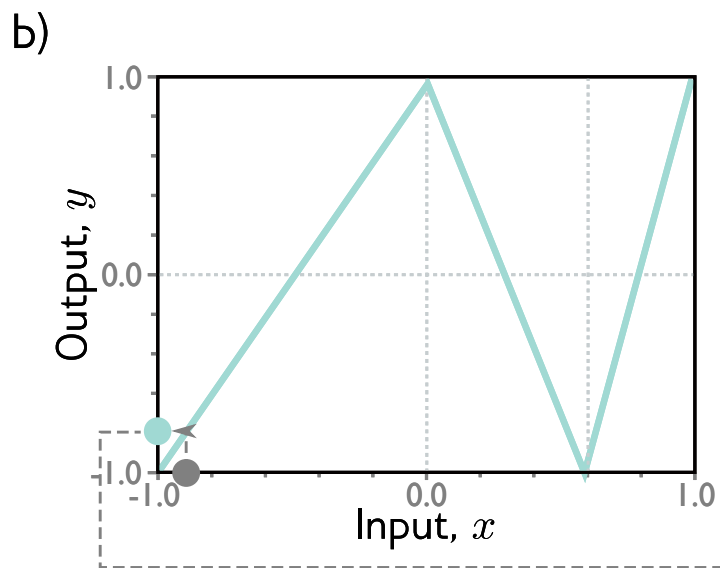
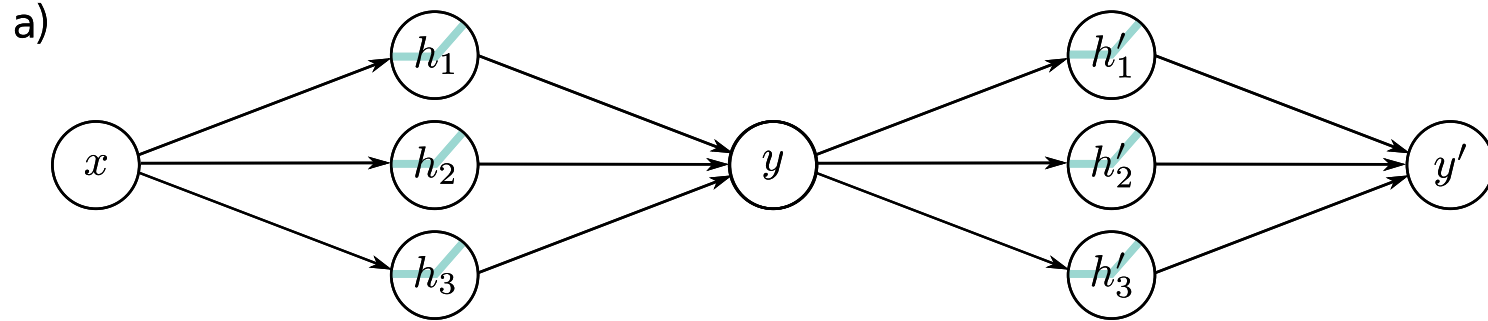
Let's see what happens when we map  
 $x \rightarrow y \rightarrow y'$

Example: Pick parameters so that  
 $x \in [-1,1]$  maps to  
 $y \in [-1,1]$  with alternating slope

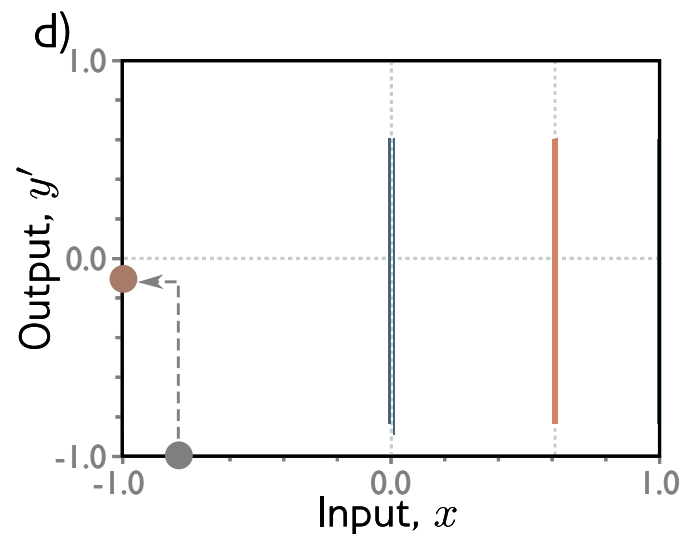
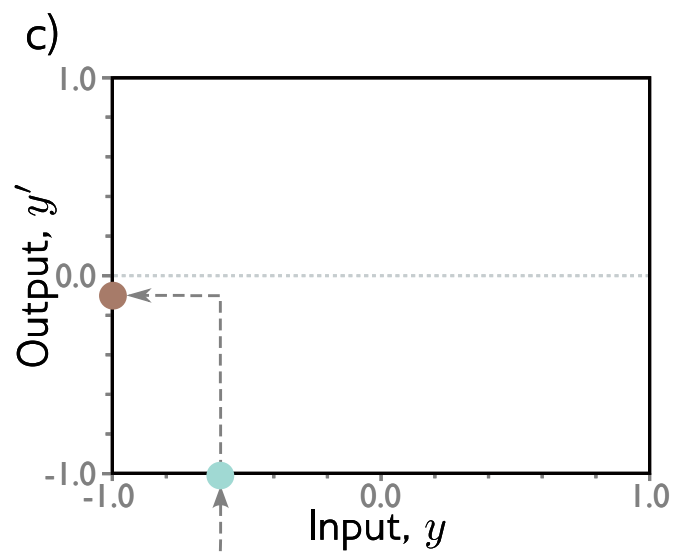
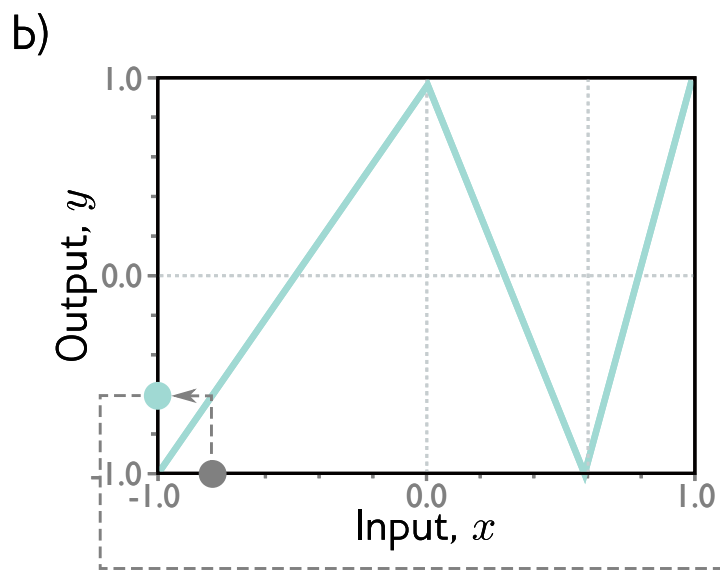
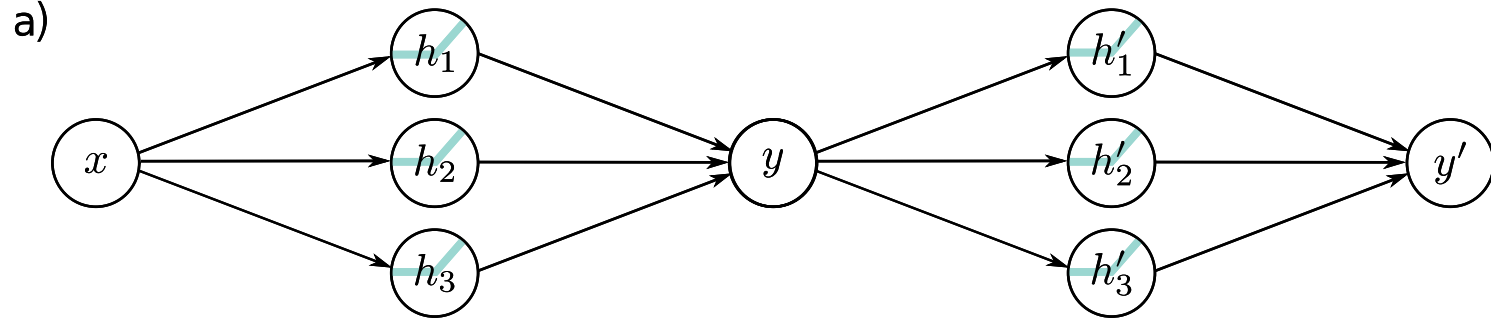


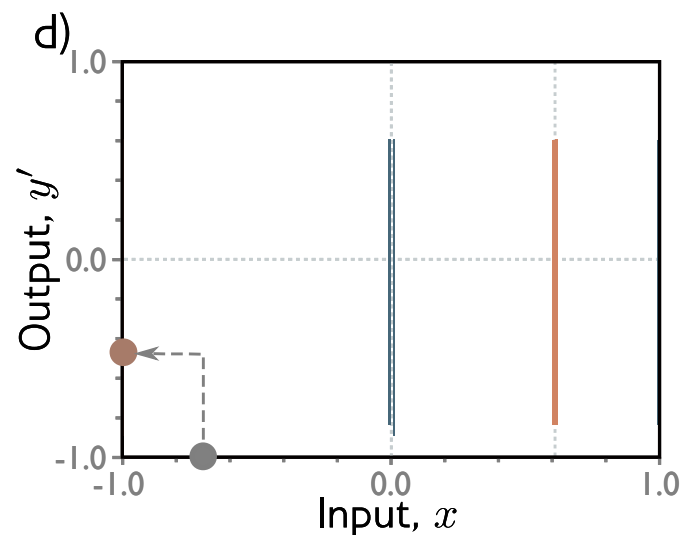
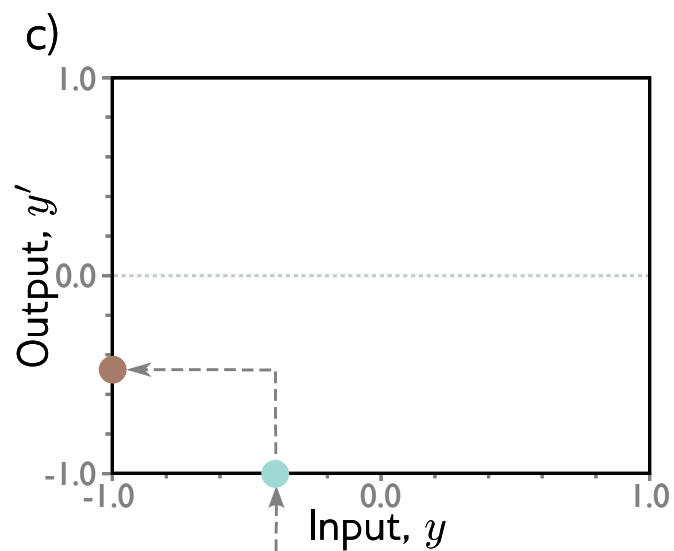
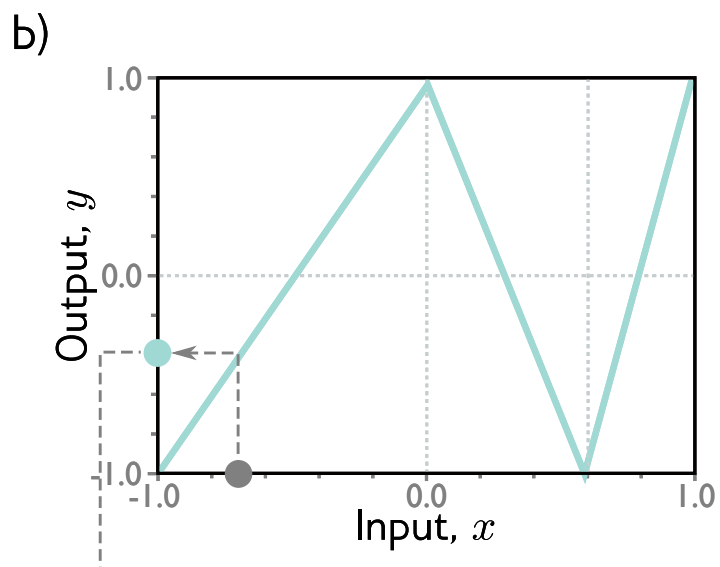
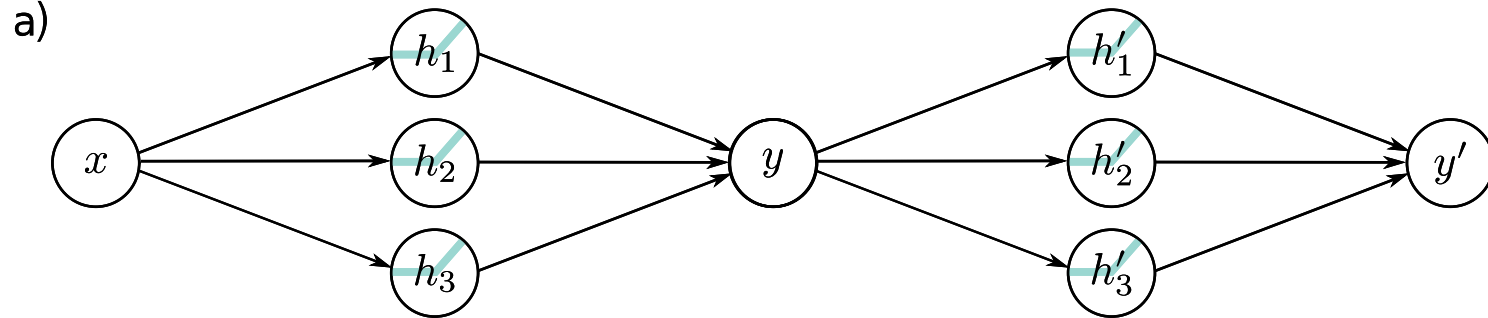


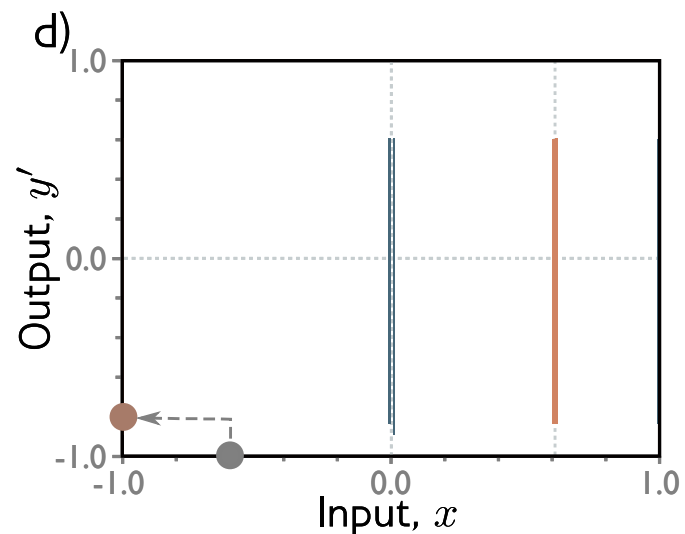
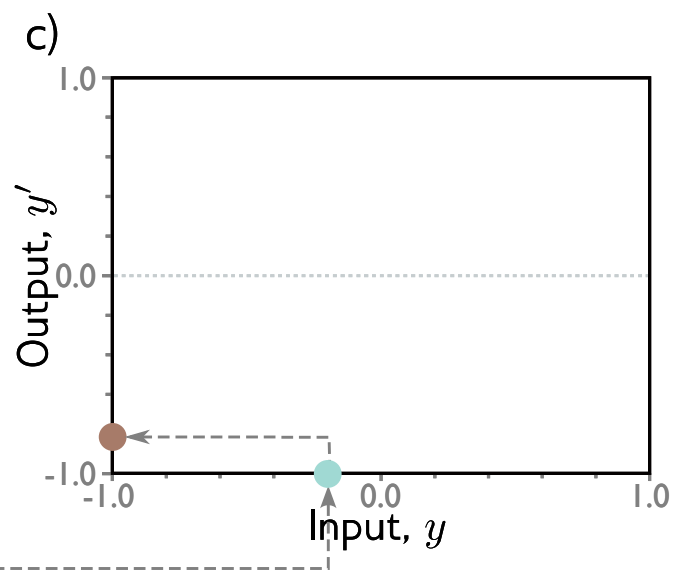
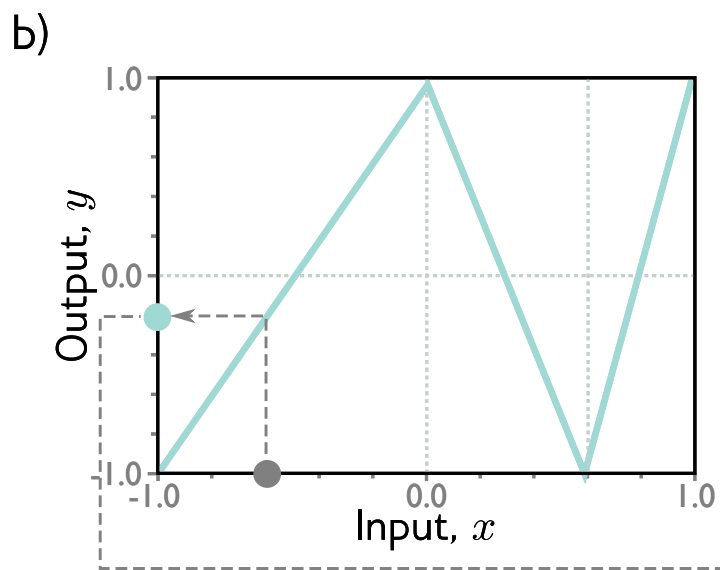
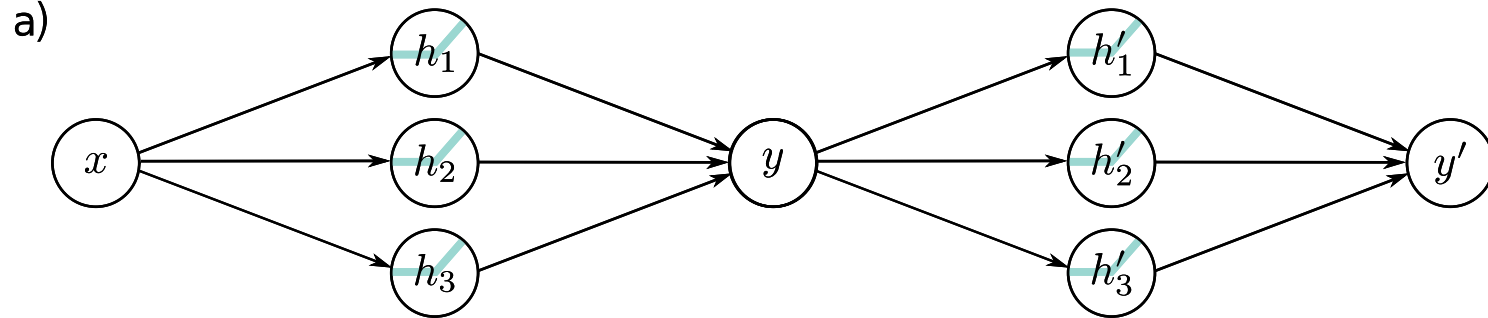


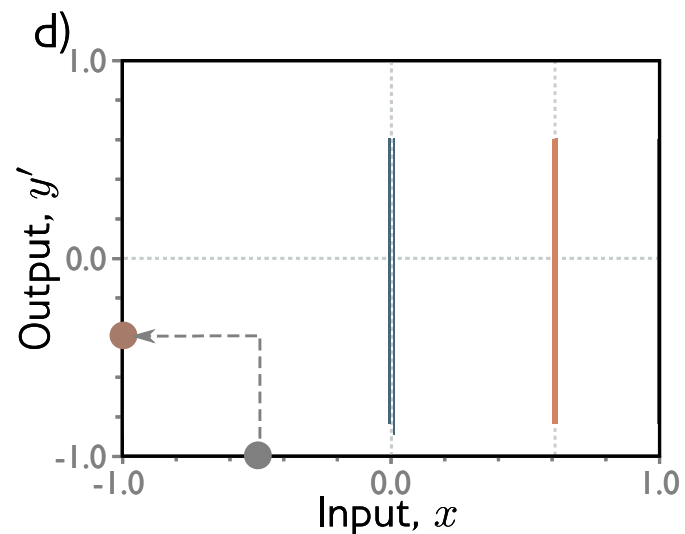
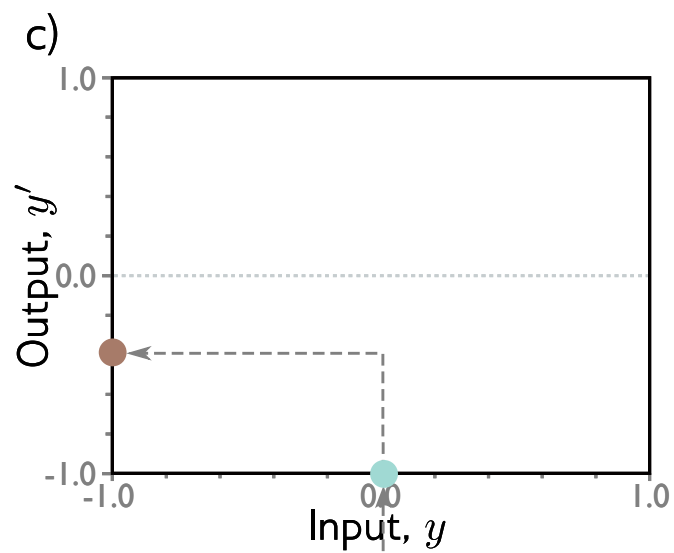
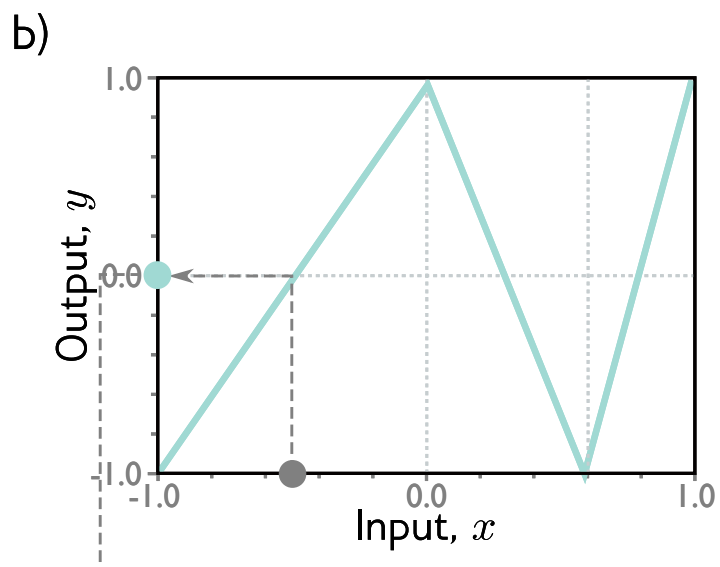
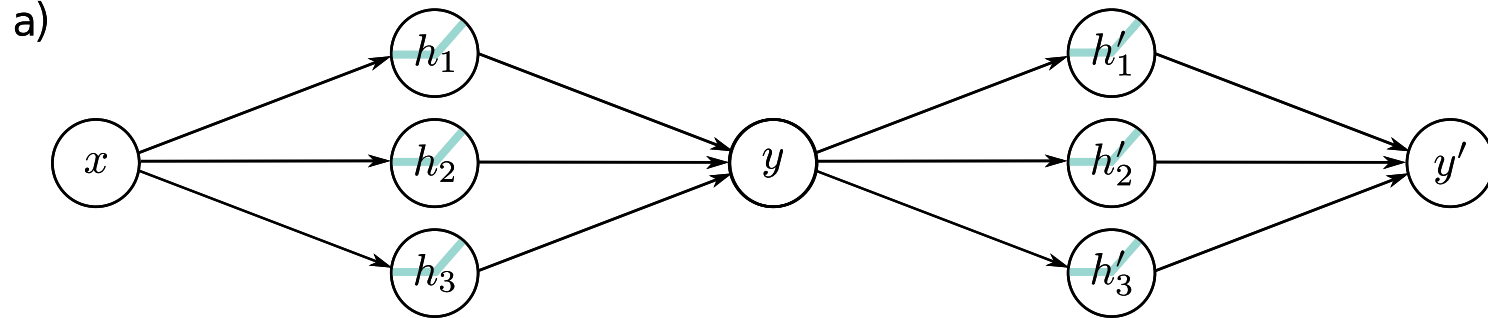


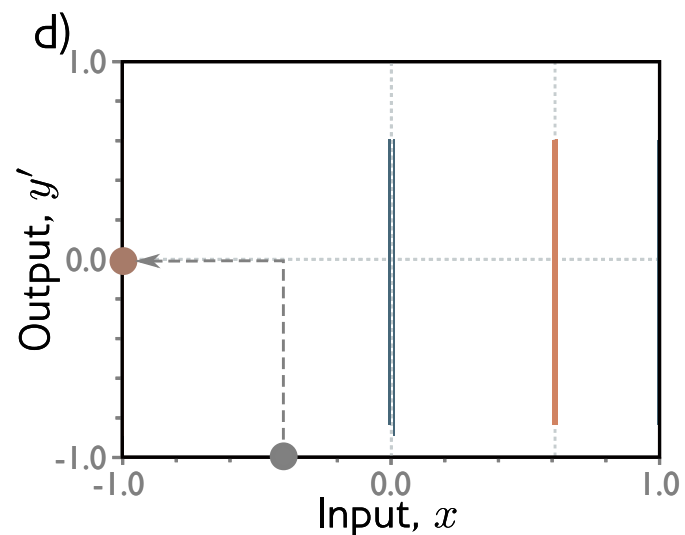
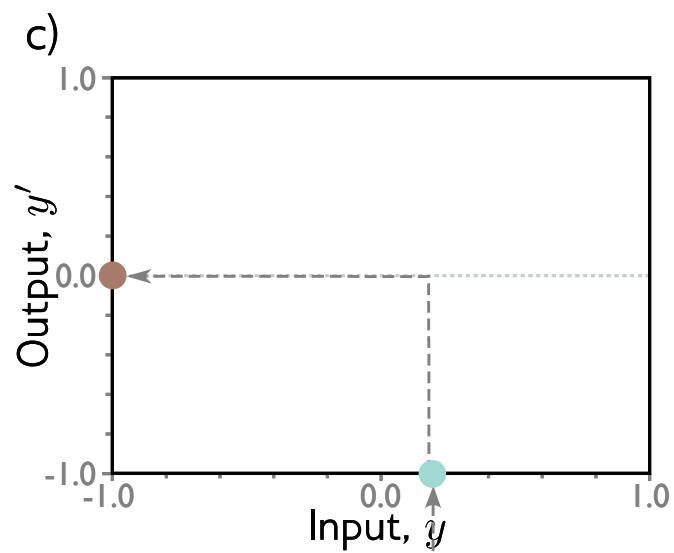
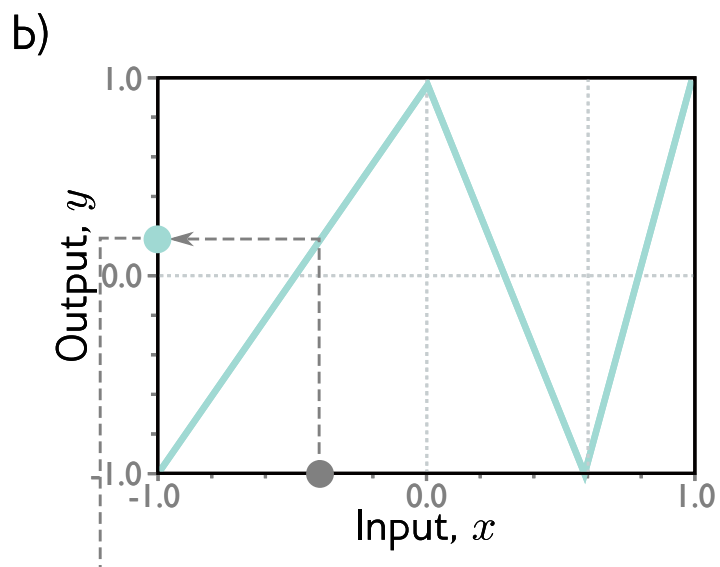
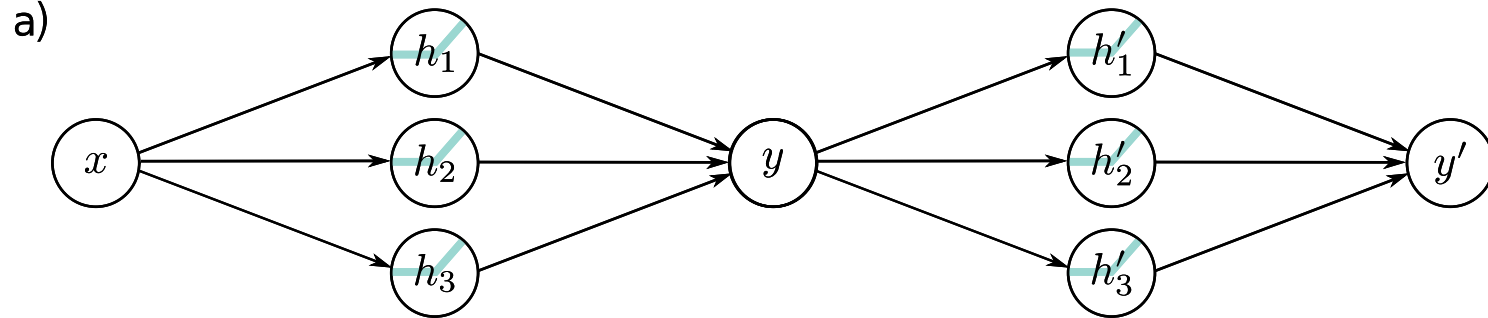


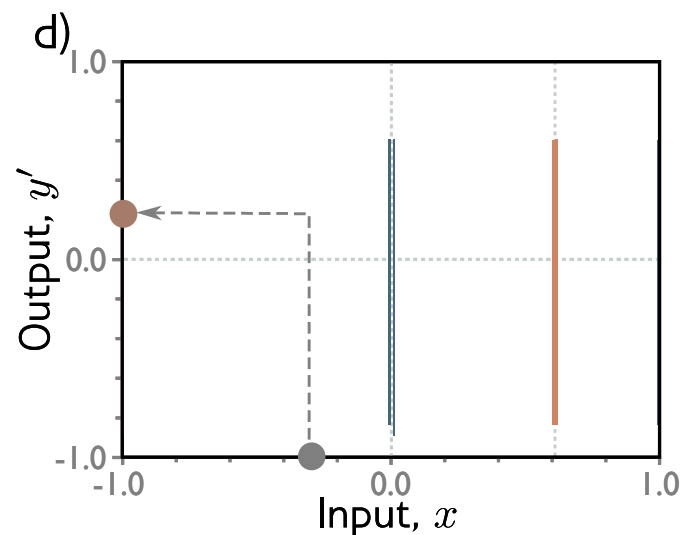
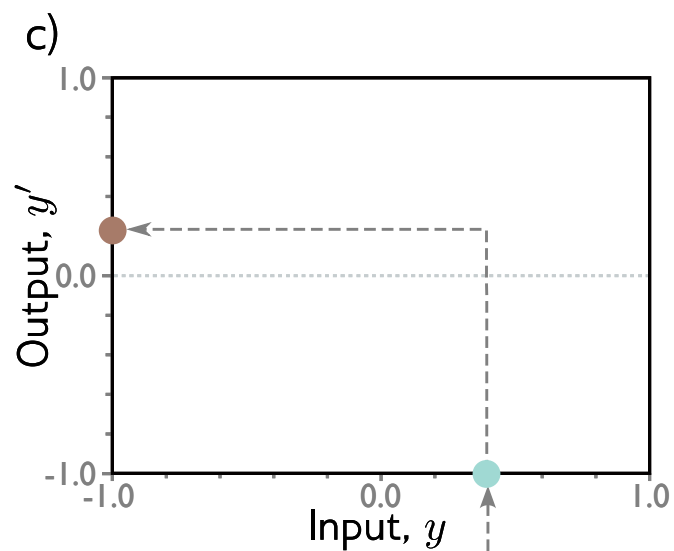
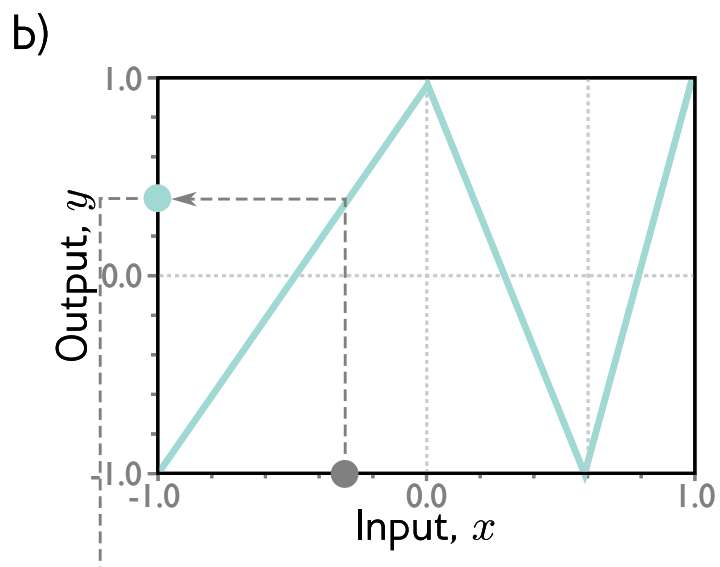
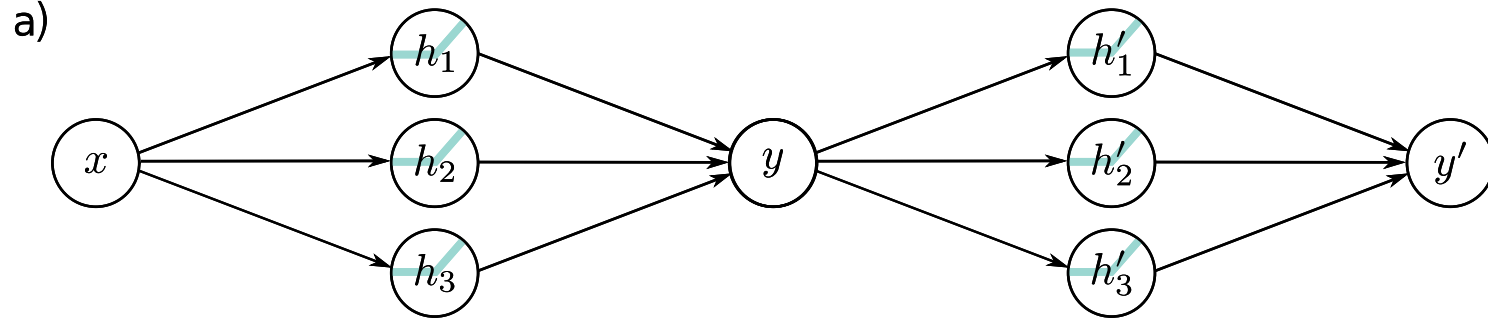


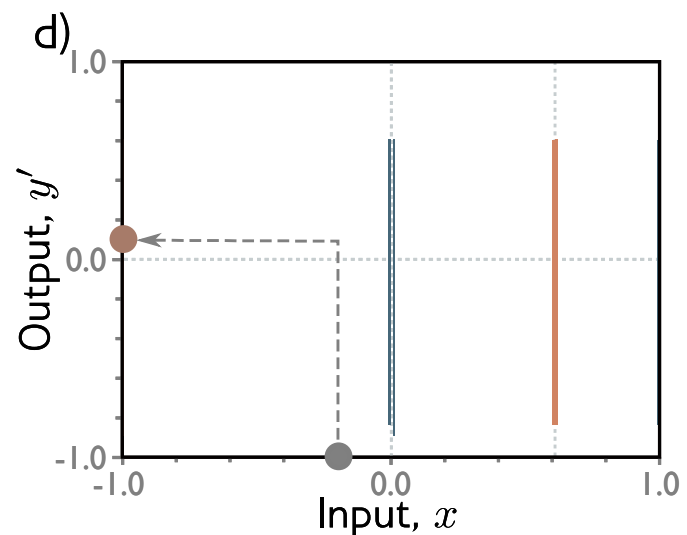
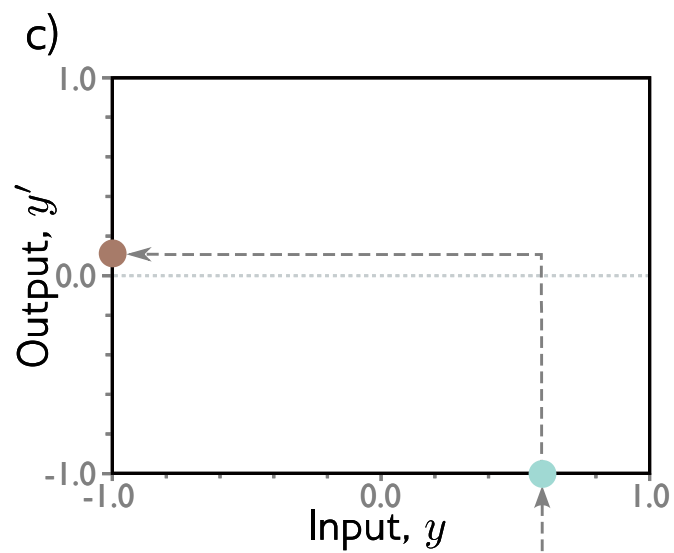
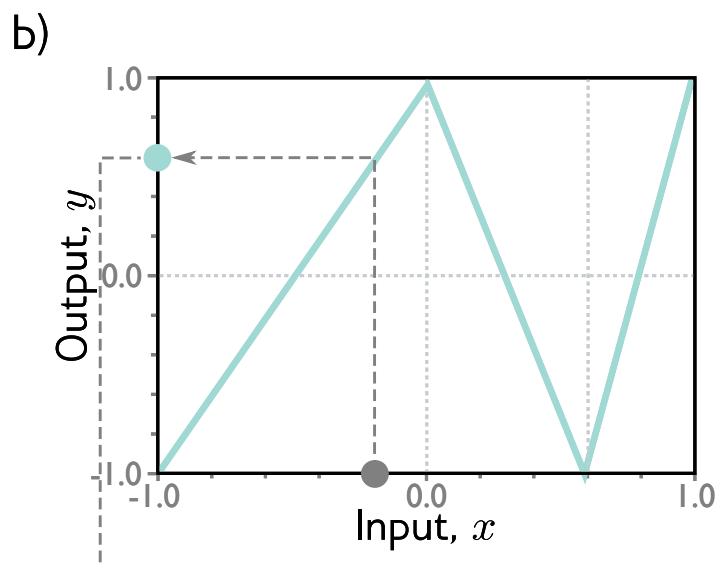
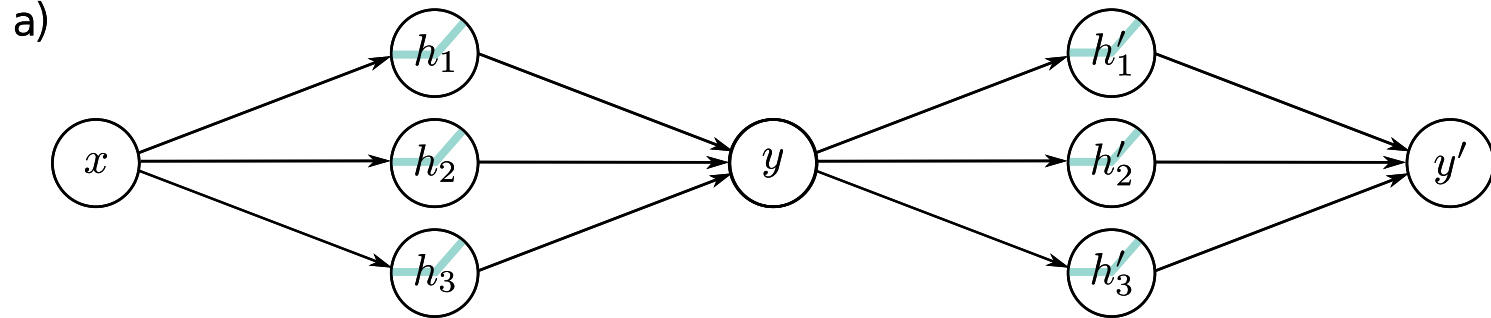


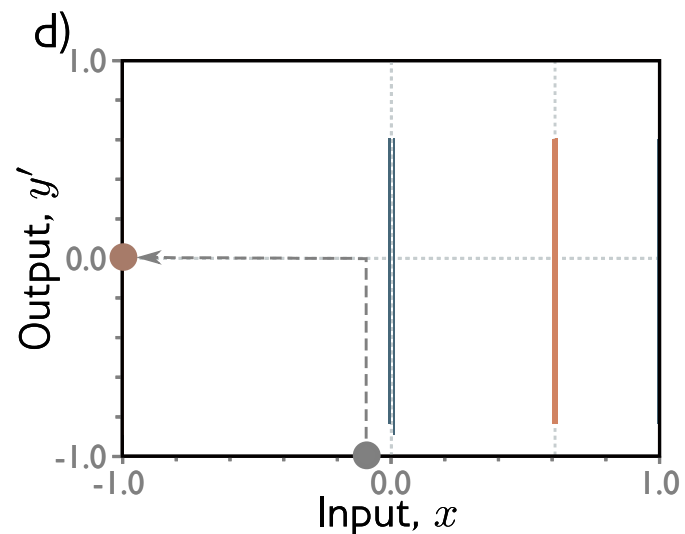
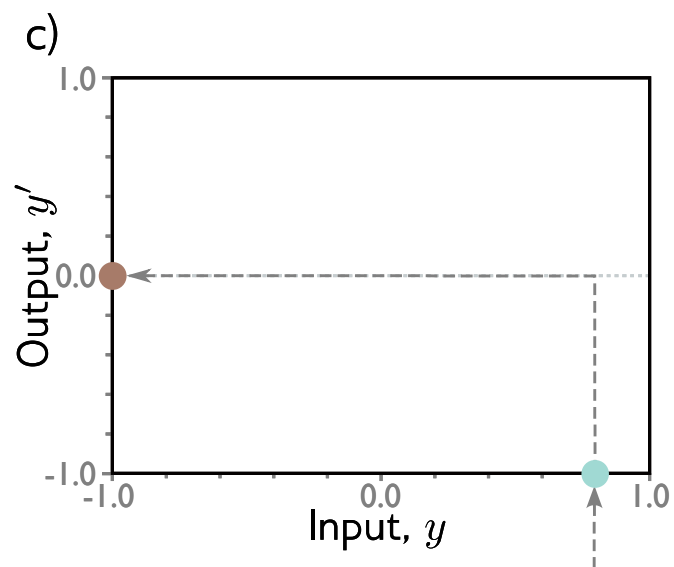
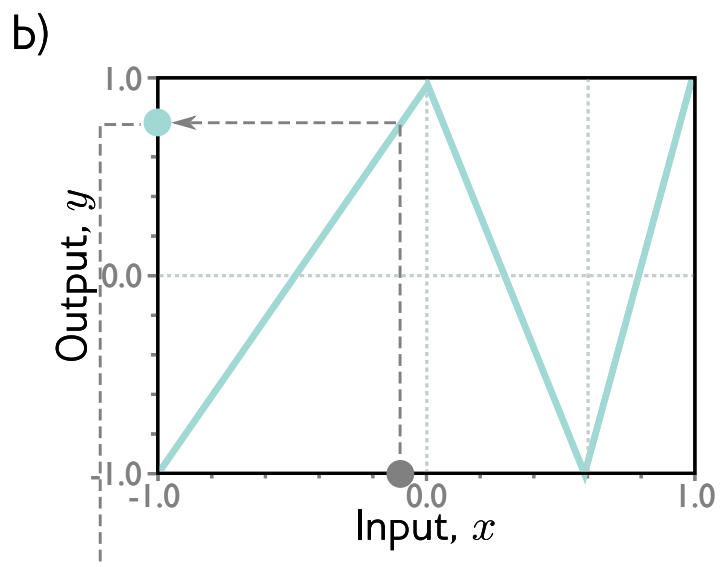
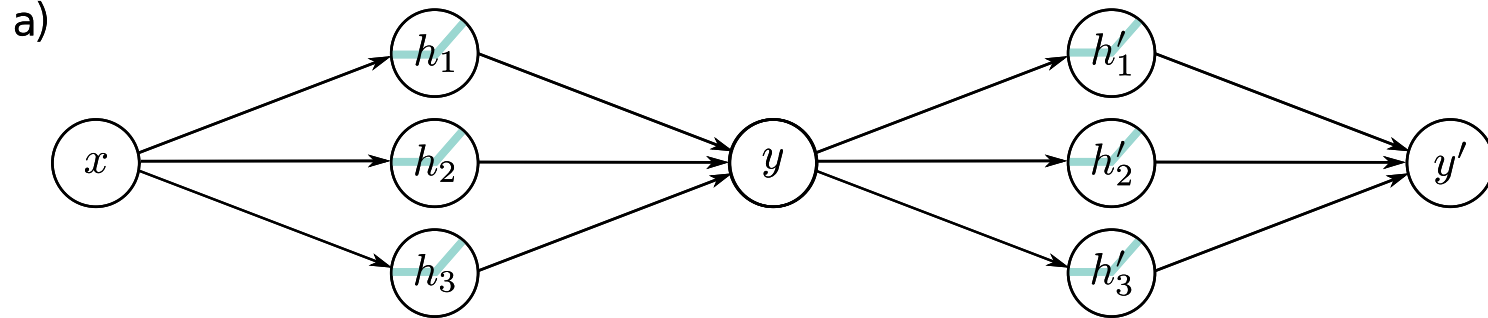




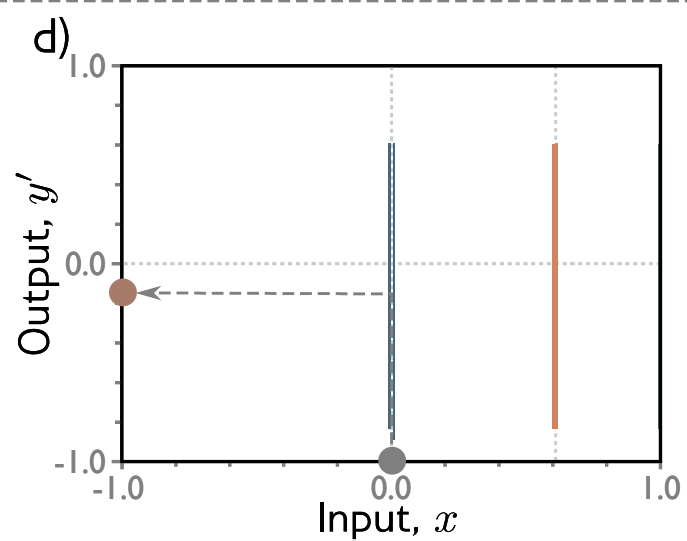
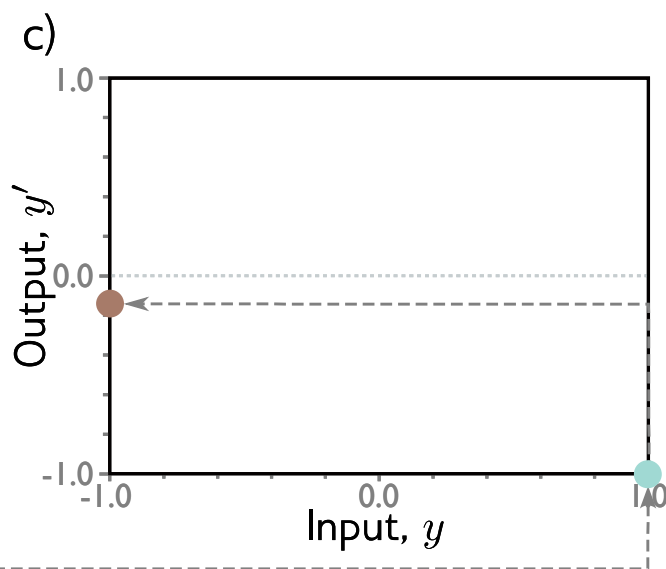
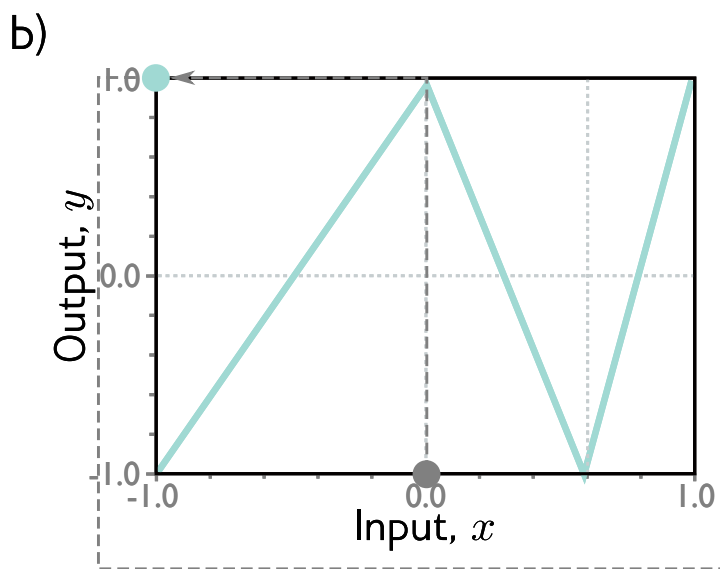
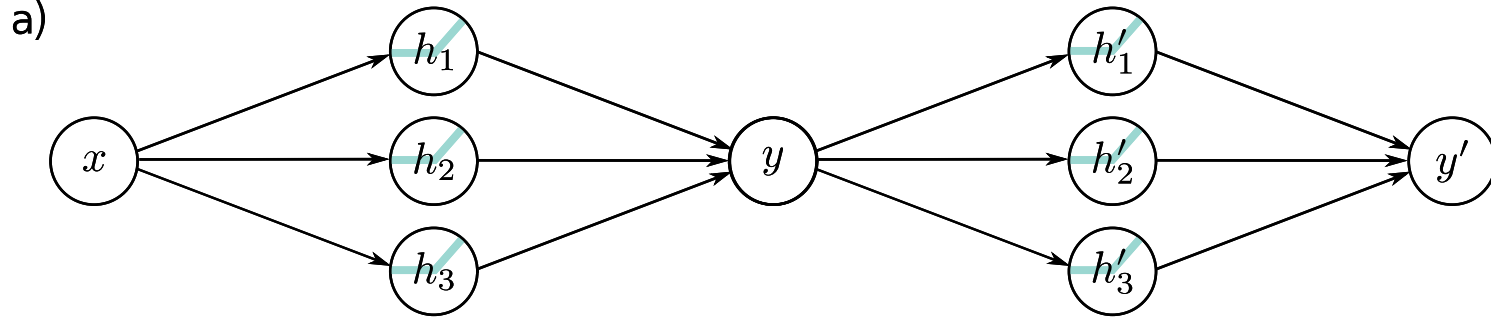


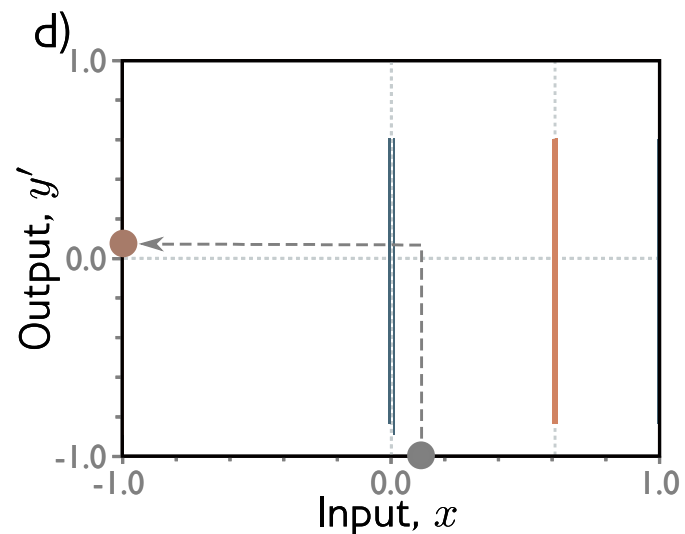
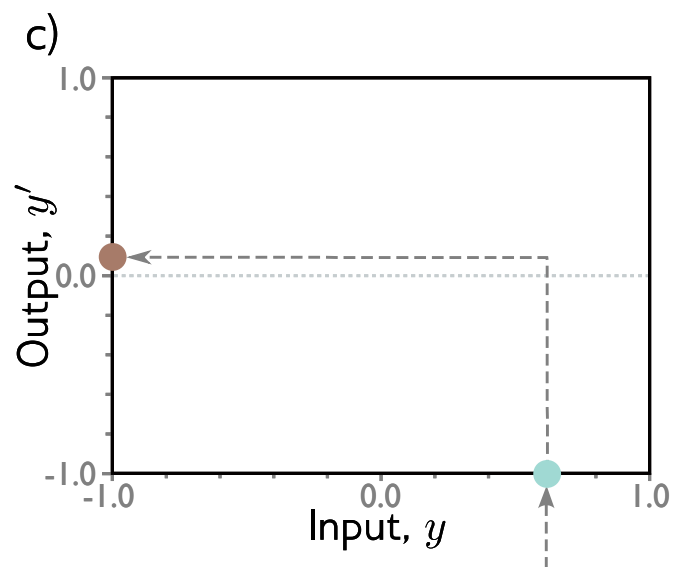
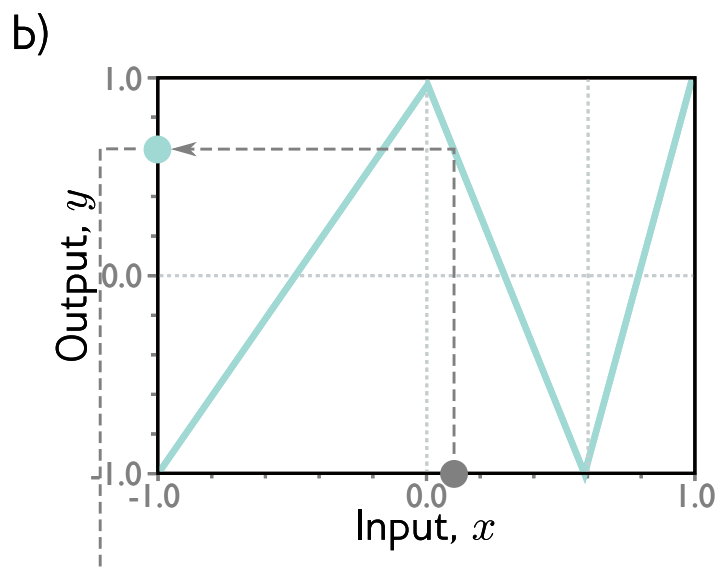
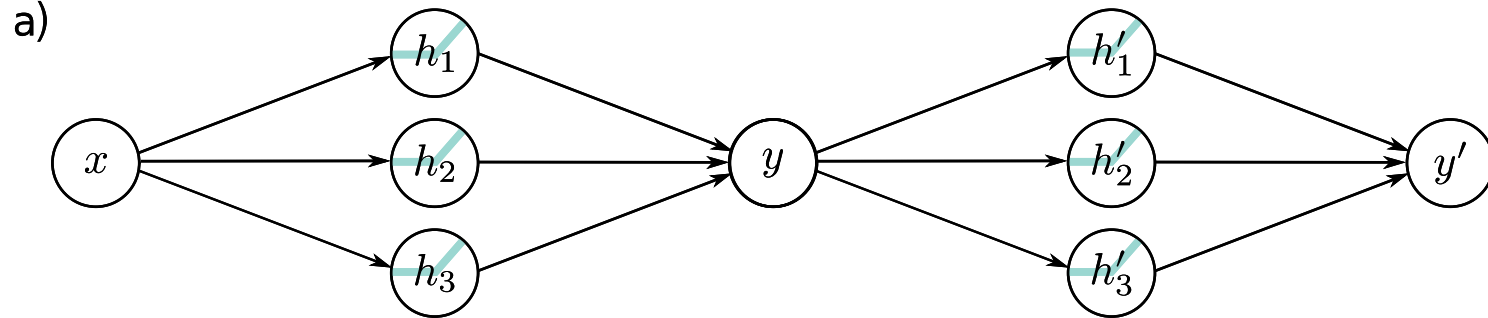


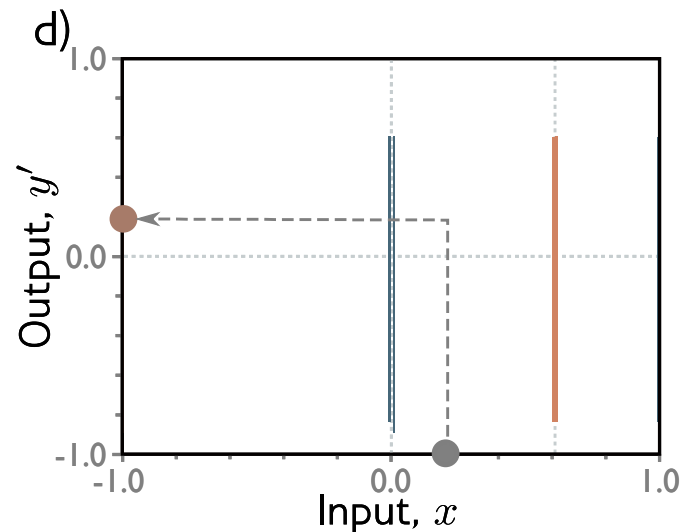
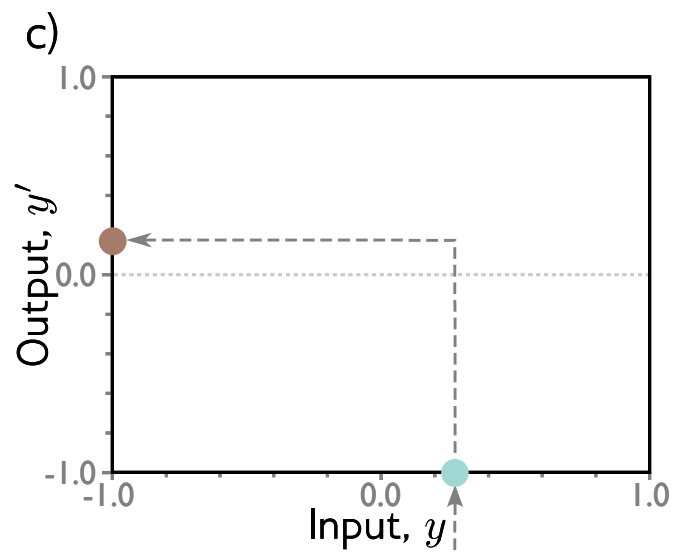
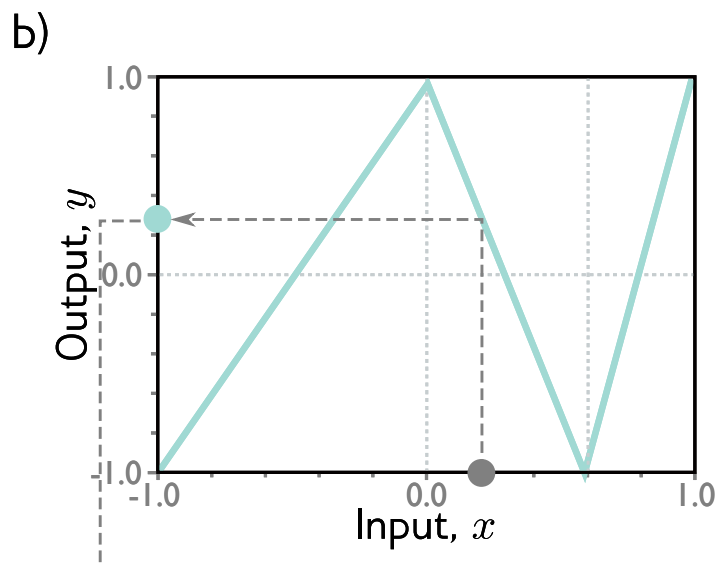
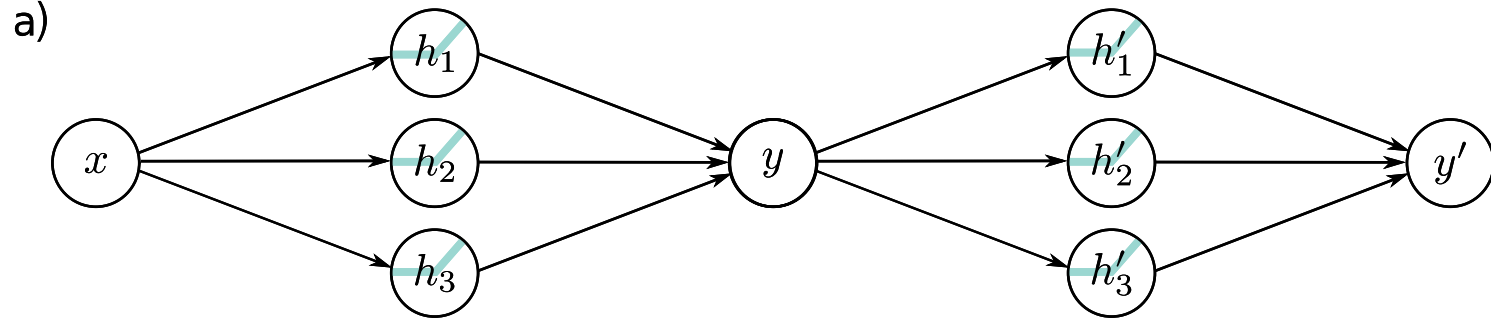


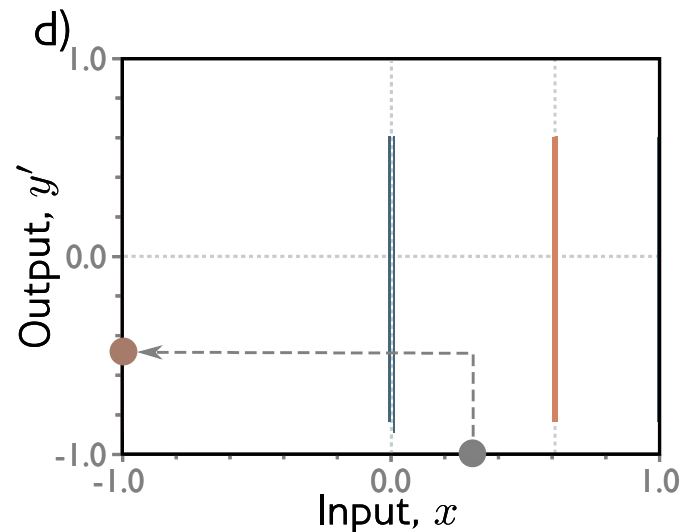
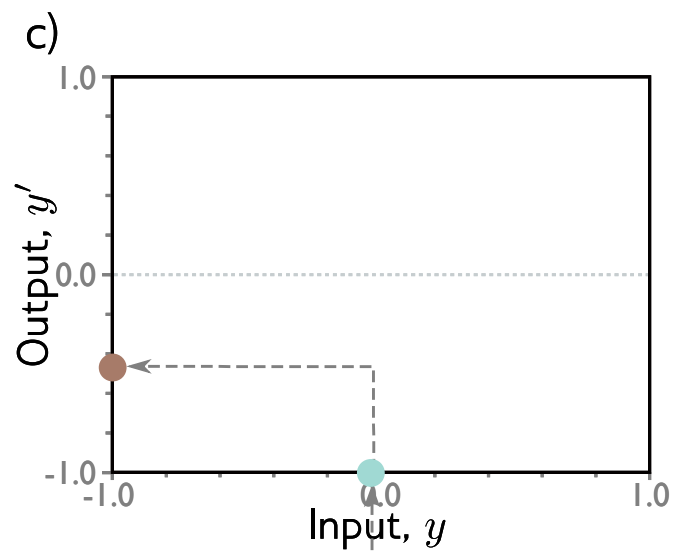
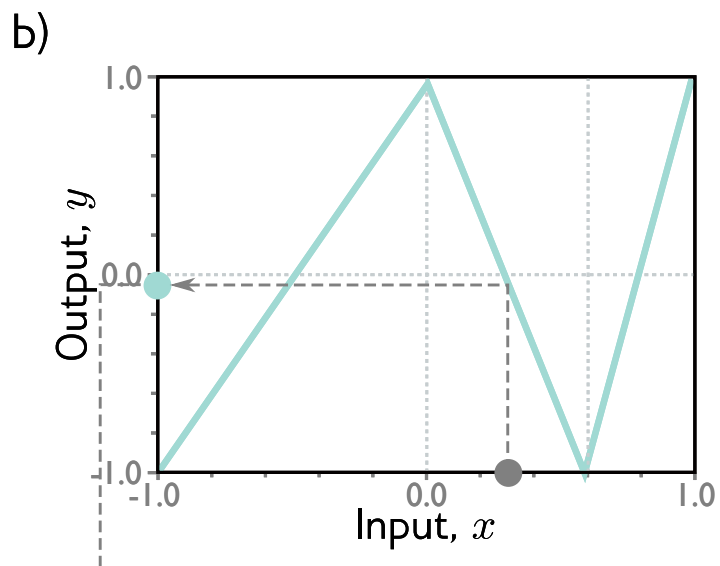
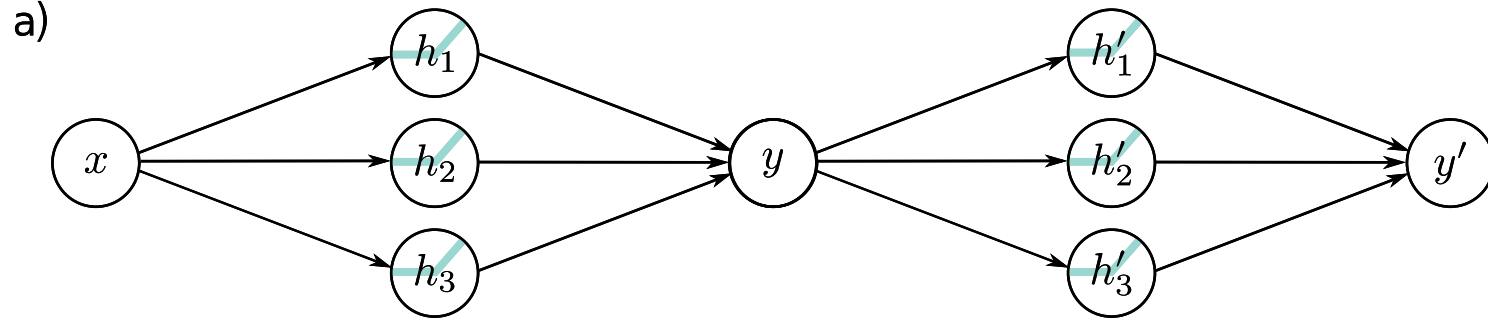


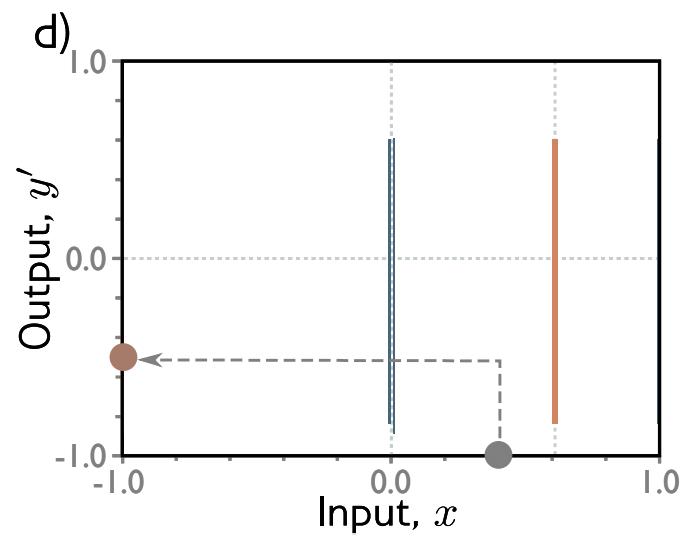
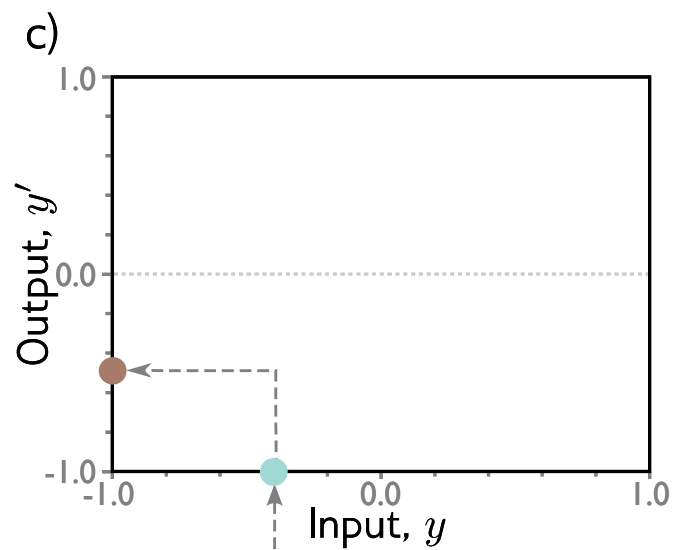
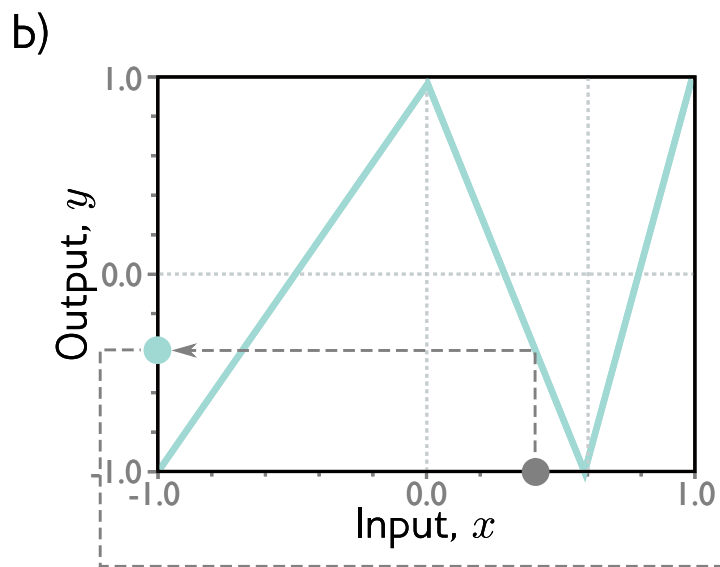
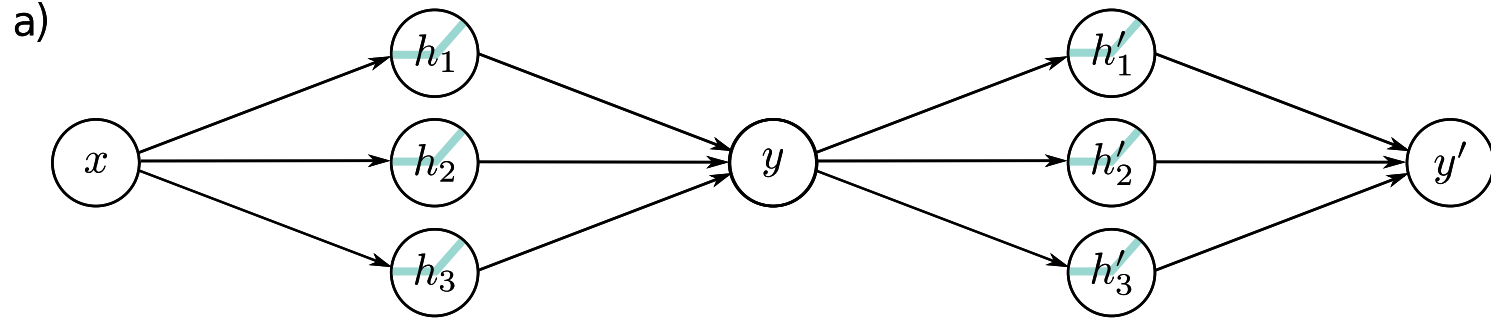


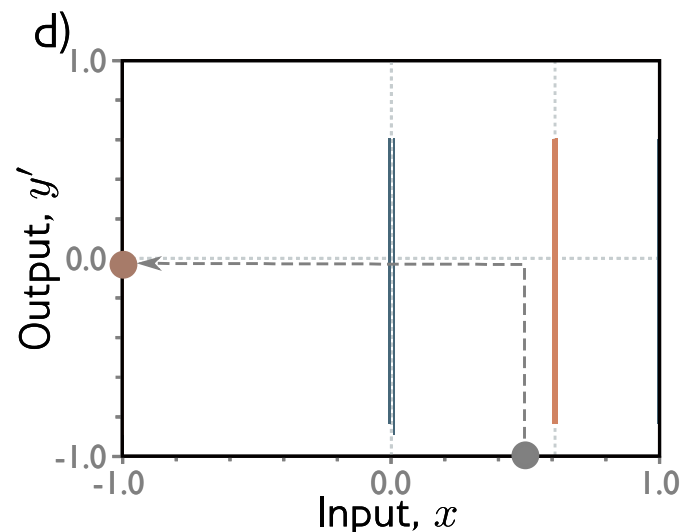
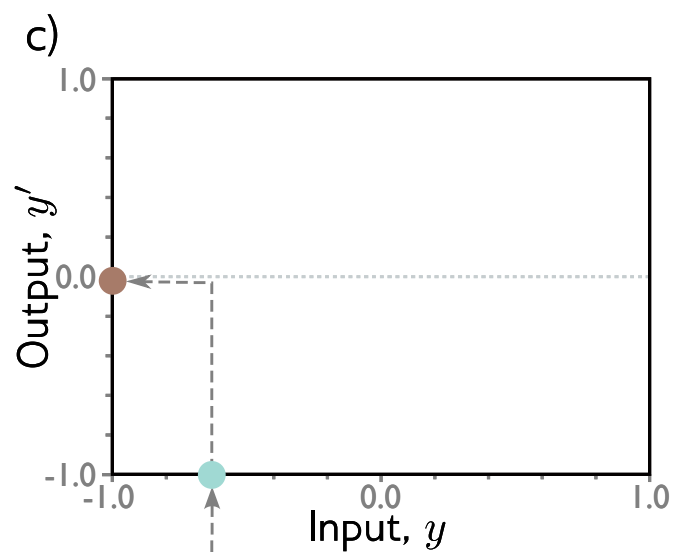
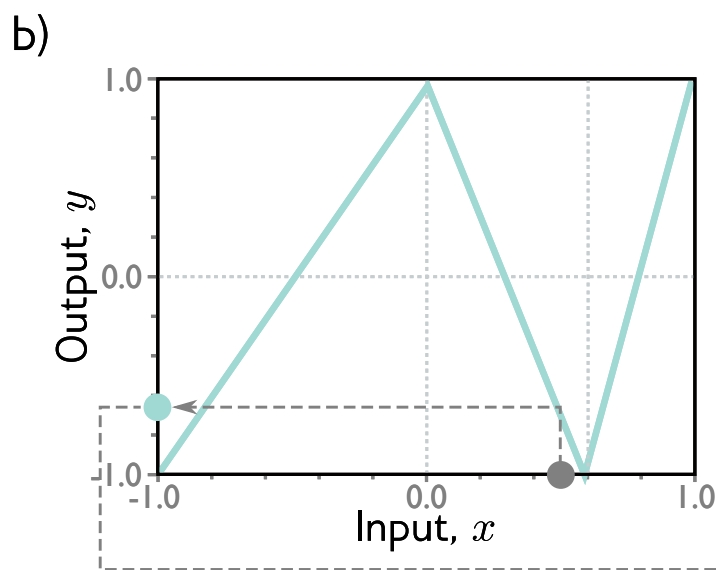
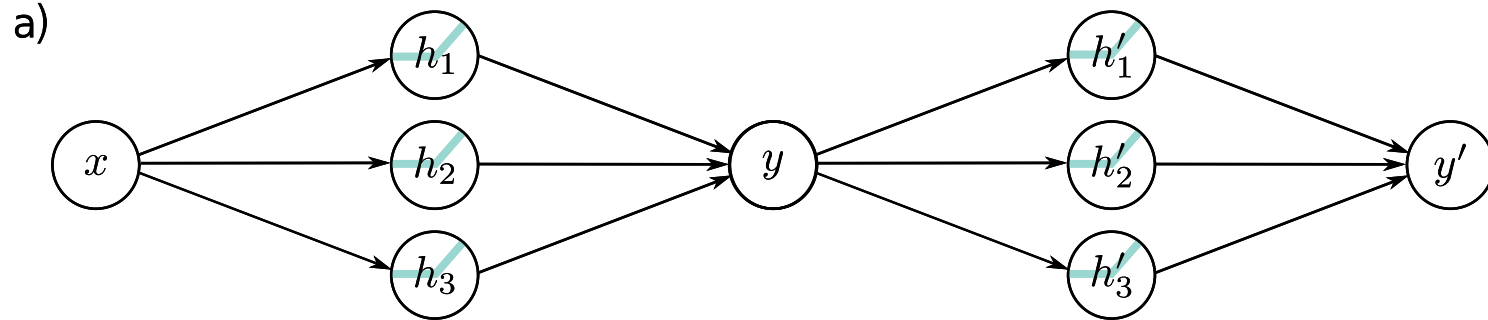


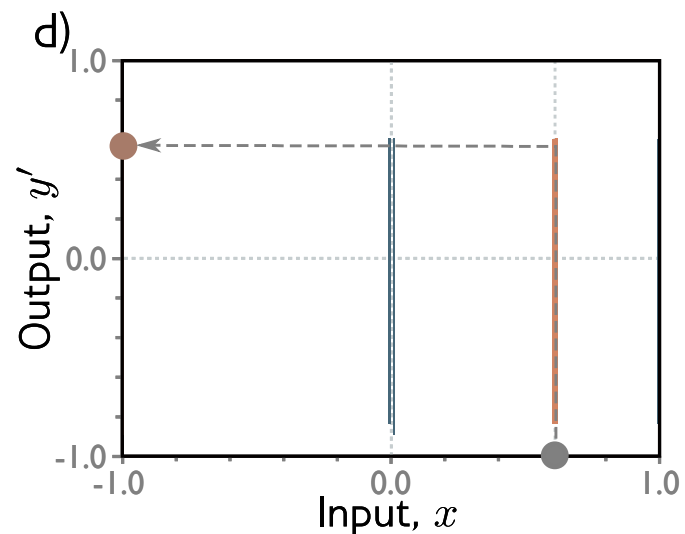
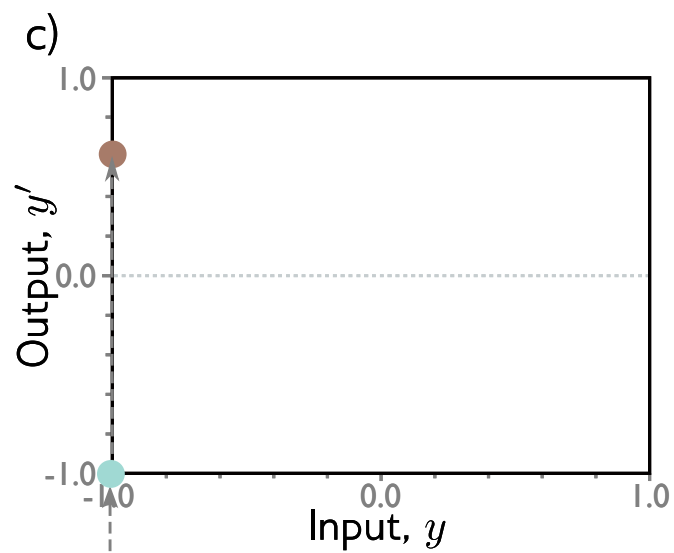
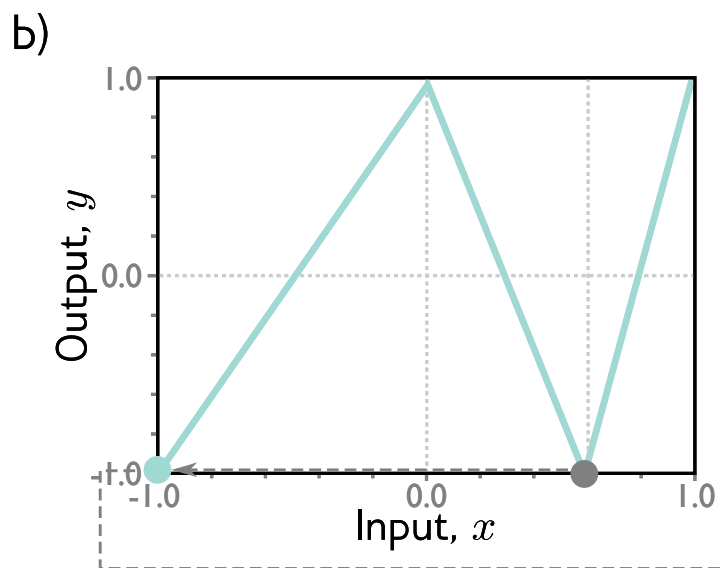
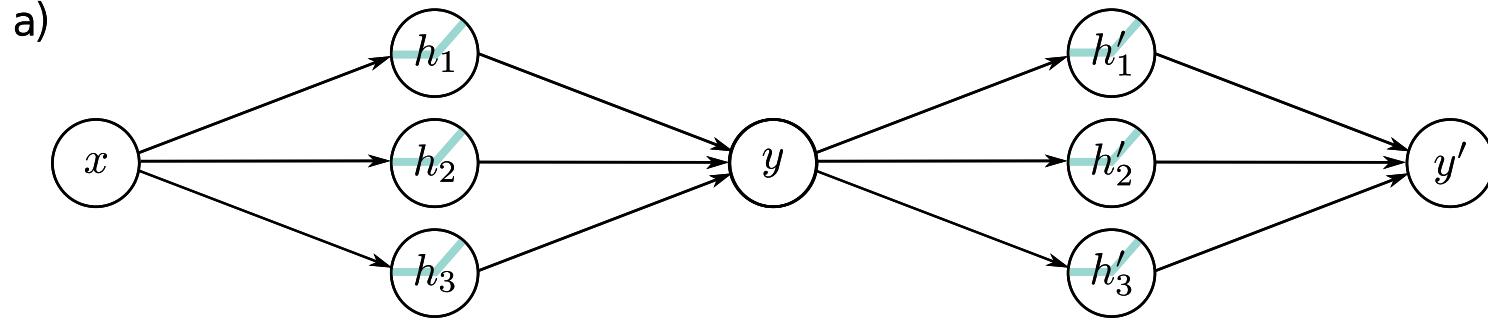


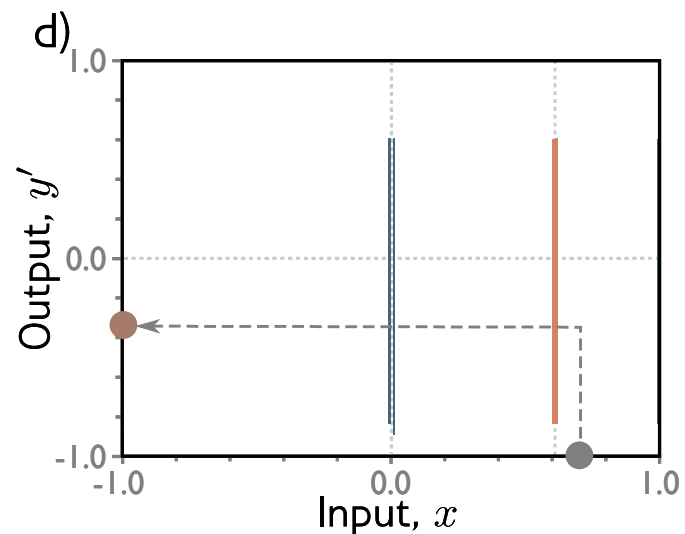
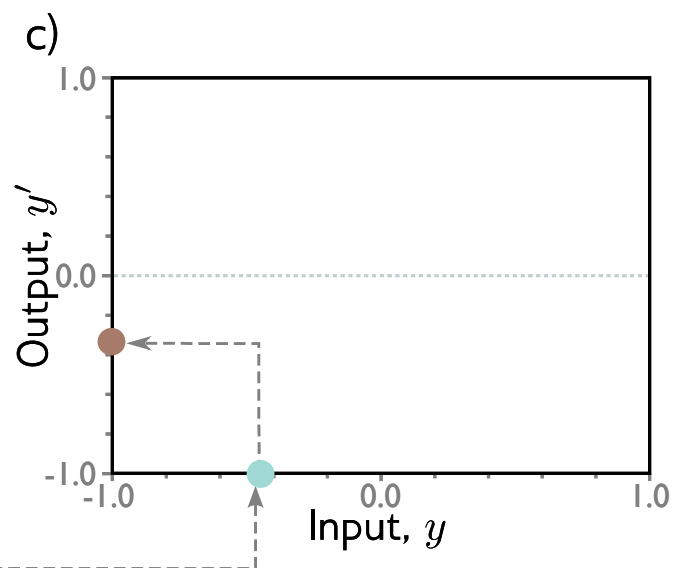
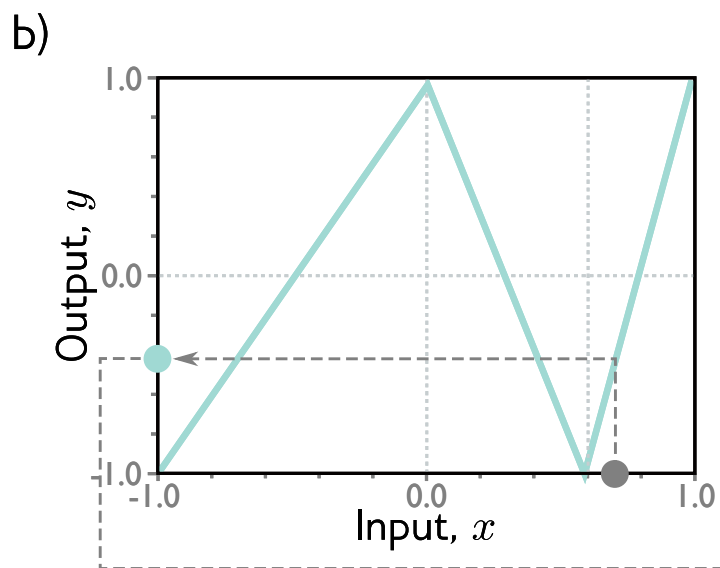
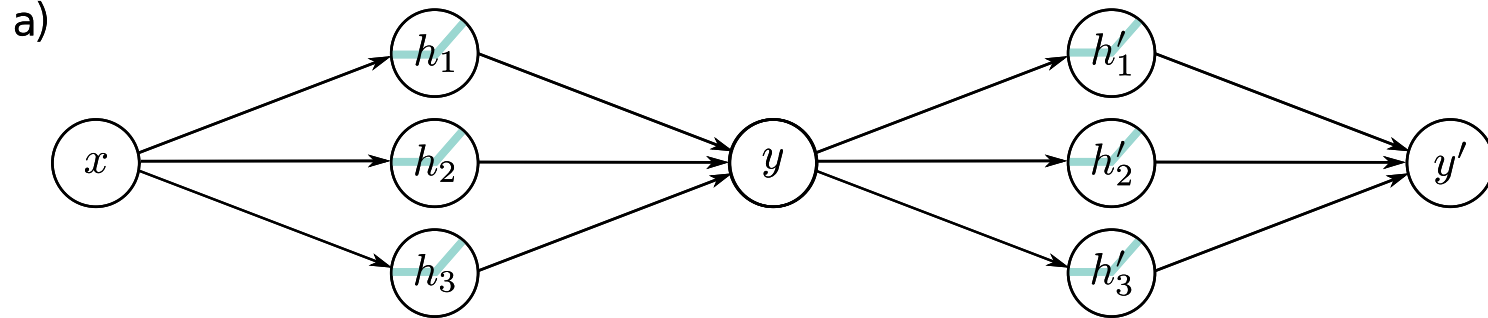




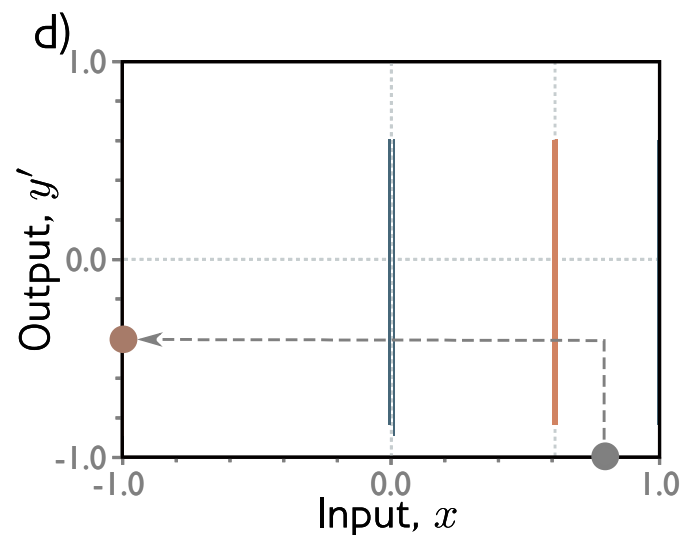
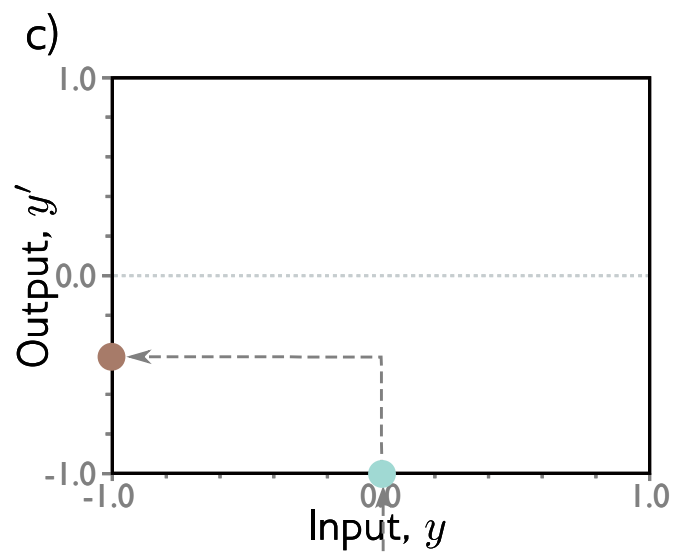
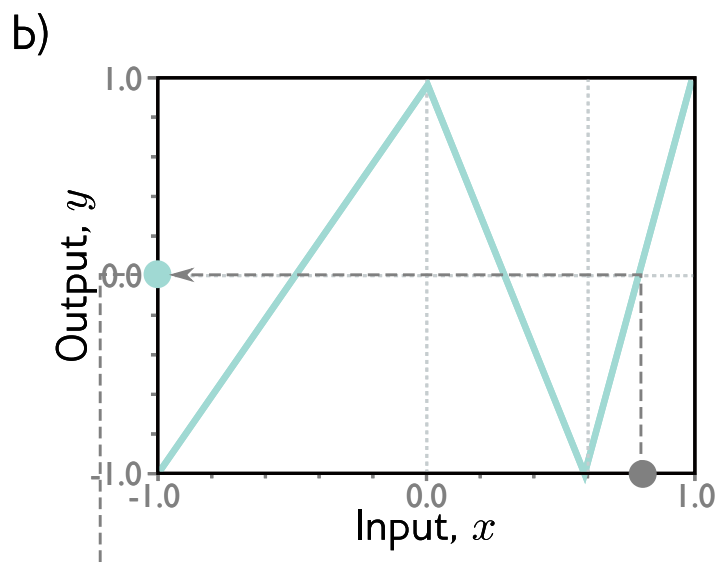
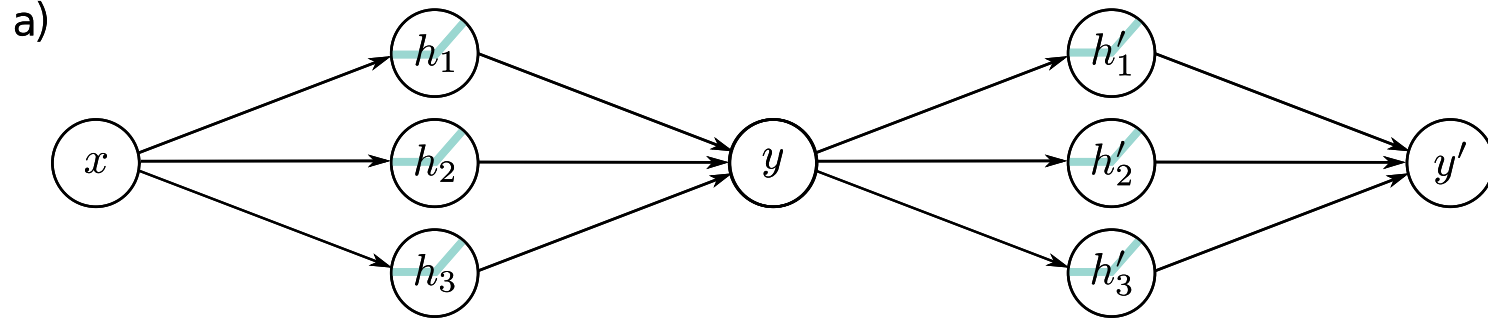


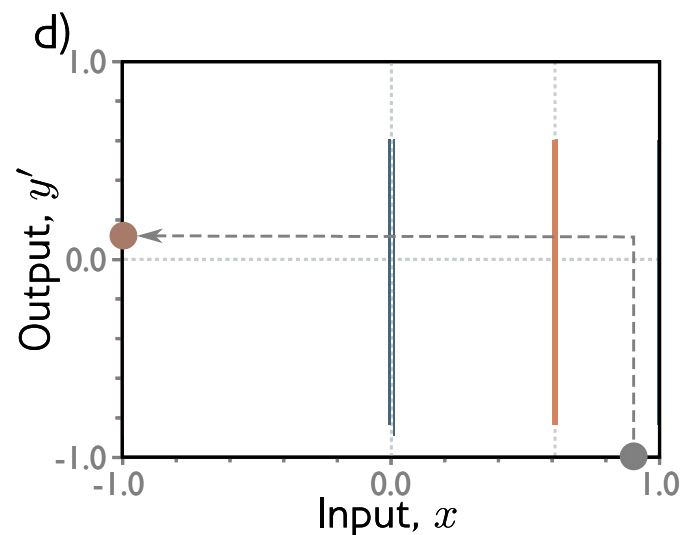
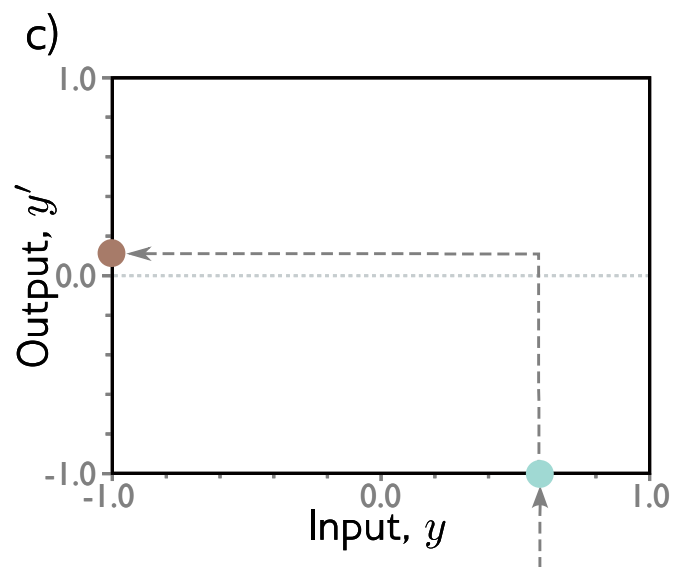
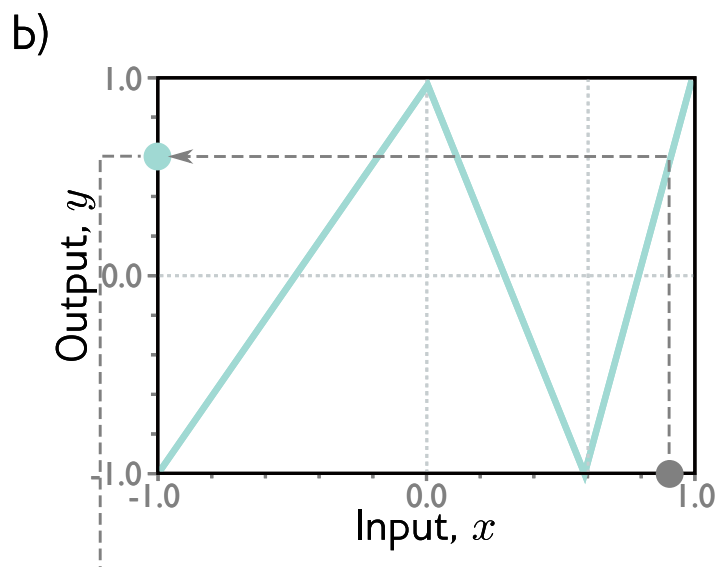
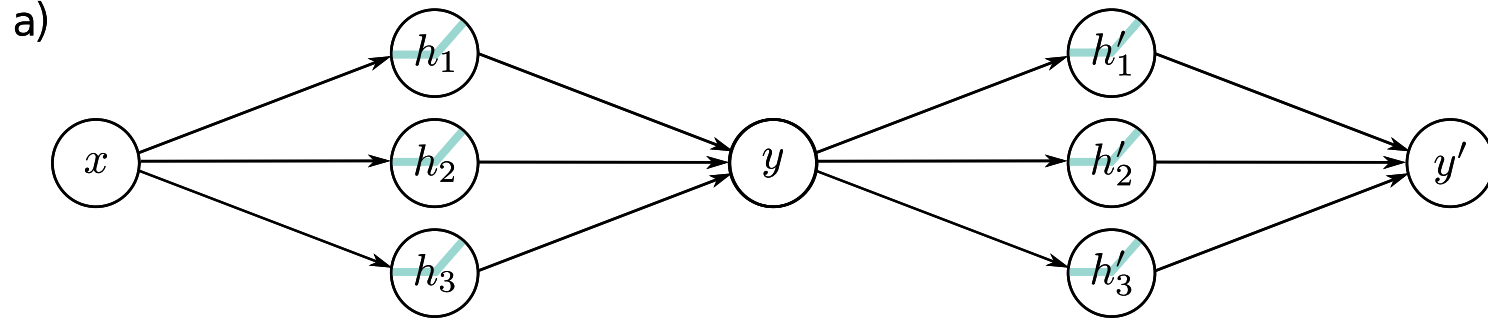




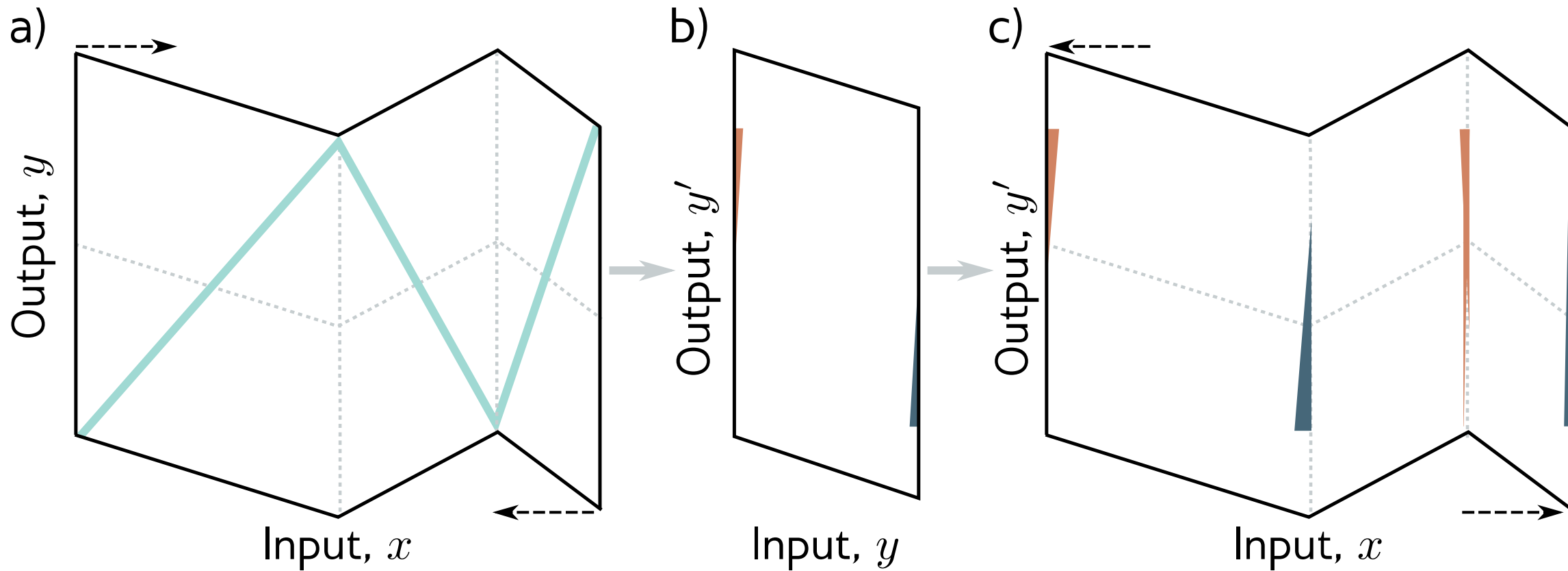




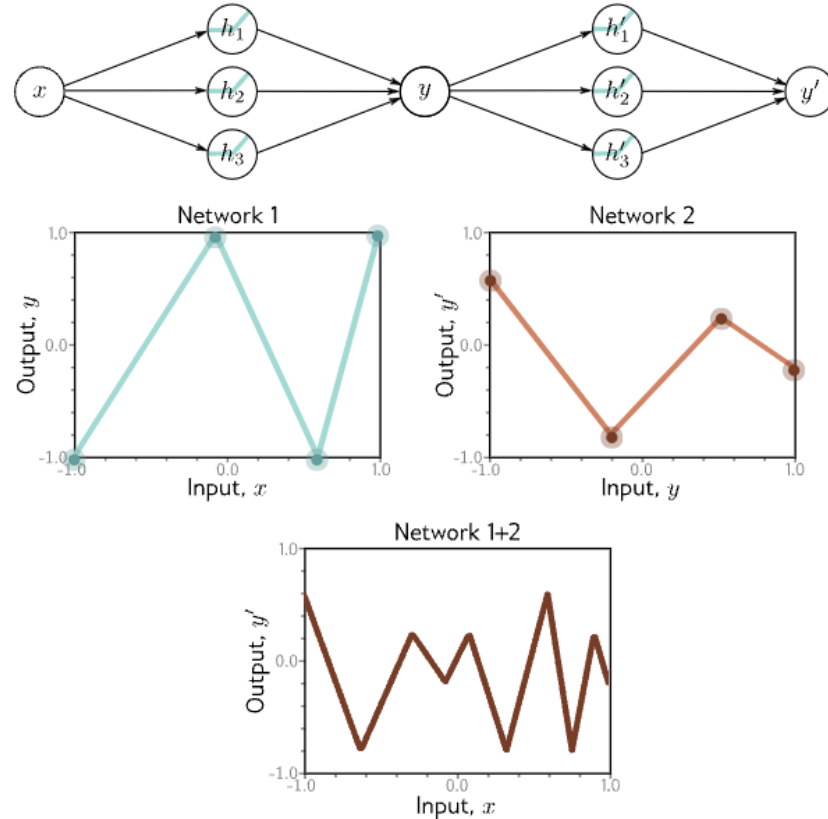




# “Folding analogy”



# Interactive Figure 4.1 – Concatenating Nets

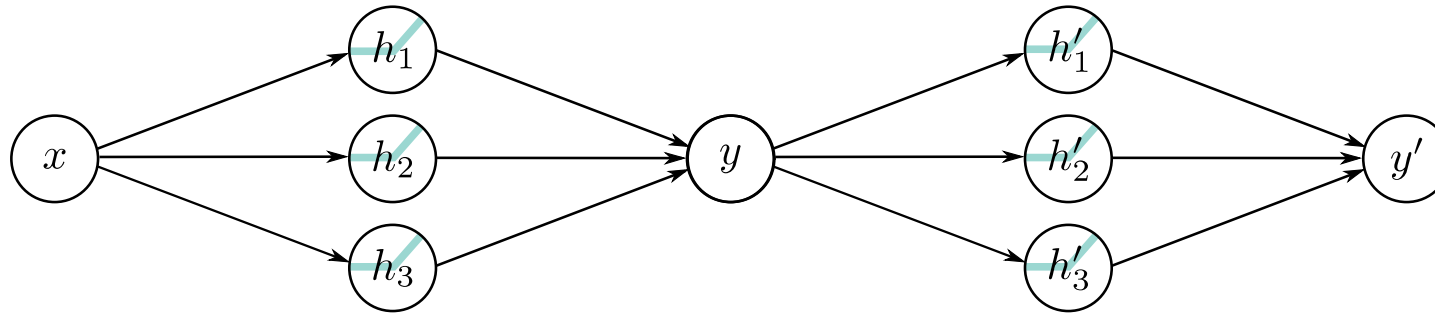


<https://udlbook.github.io/udlfigures/>

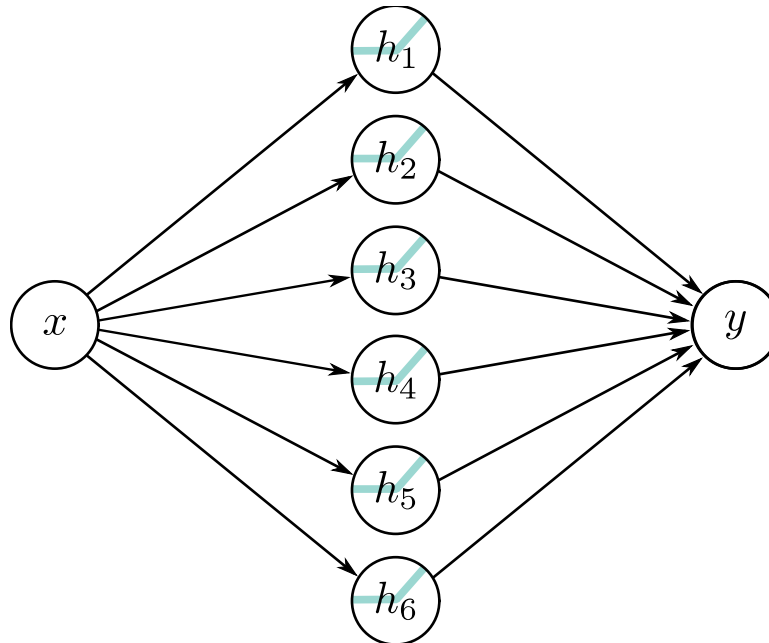
**Figure 3.8b** Composing two single-layer networks with three hidden units each. The output  $y$  of the first network constitutes the input to the second network. (Top left) The first network maps inputs  $x \in [-1, 1]$  to outputs  $y \in [-1, 1]$  to outputs using a function comprising three linear regions (fourth linear region is outside range of graph). (Top right) The second network defines a function comprising three linear regions that takes  $y$  and returns  $y'$ . (Bottom) The combined effect of these two functions when composed.

Manipulate the functions defined by the two shallow networks (using the circular handles) to see the effect of composing the functions.

# Comparing to shallow with six hidden units

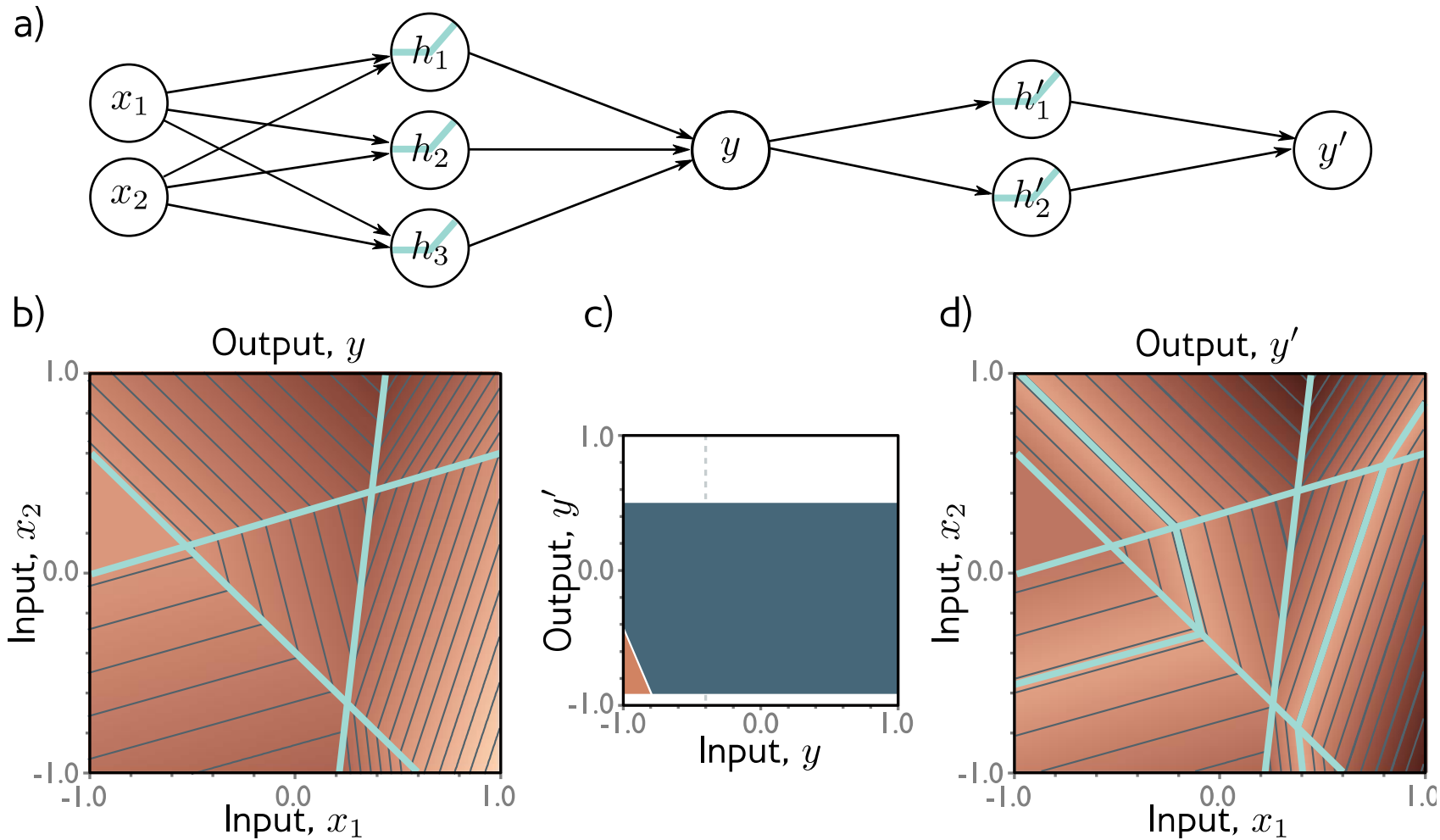


- 20 parameters
- (at least) 9 regions



- 19 parameters
- Max 7 regions

# Composing networks in 2D



# Deep neural networks

- Composing two networks
- Combining the two networks into one
- Hyperparameters
- Notation change and general case
- Shallow vs. deep networks

# Combine two networks into one

$\theta$  : theta  
 $\phi$  : phi

Let's start with 2 networks:

Network 1:  
(input is  $x$ )

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

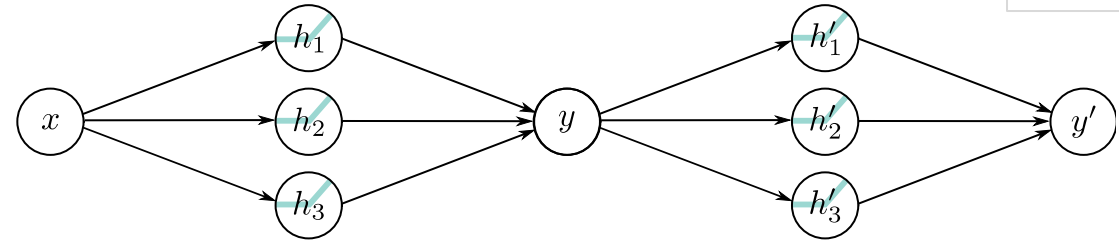
$$h_3 = a[\theta_{30} + \theta_{31}x]$$

Network 2:  
(input is  $y$ )

$$h'_1 = a[\theta'_{10} + \theta'_{11}y]$$

$$h'_2 = a[\theta'_{20} + \theta'_{21}y]$$

$$h'_3 = a[\theta'_{30} + \theta'_{31}y]$$



$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$



# Combine two networks into one

$\theta$  : theta  
 $\phi$  : phi

Let's start with 2 networks:

Network 1:  
(input is  $x$ )

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

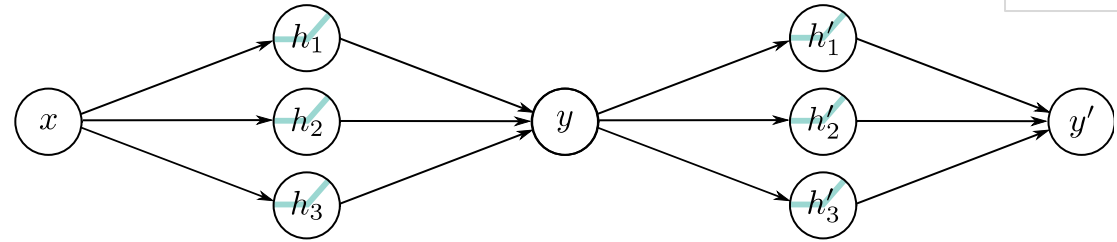
$$h_3 = a[\theta_{30} + \theta_{31}x]$$

Network 2:  
(input is  $y$ )

$$h'_1 = a[\theta'_{10} + \theta'_{11}y]$$

$$h'_2 = a[\theta'_{20} + \theta'_{21}y]$$

$$h'_3 = a[\theta'_{30} + \theta'_{31}y]$$



$$y = \phi_0 + \phi_1 h_1 + \phi_2 h_2 + \phi_3 h_3$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$

Substitute for  $y$  to get hidden units of second network in terms of first:

$$h'_1 = a[\theta'_{10} + \theta'_{11}y] = a[\theta'_{10} + \theta'_{11}\phi_0 + \theta'_{11}\phi_1 h_1 + \theta'_{11}\phi_2 h_2 + \theta'_{11}\phi_3 h_3]$$

$$h'_2 = a[\theta'_{20} + \theta'_{21}y] = a[\theta'_{20} + \theta'_{21}\phi_0 + \theta'_{21}\phi_1 h_1 + \theta'_{21}\phi_2 h_2 + \theta'_{21}\phi_3 h_3]$$

$$h'_3 = a[\theta'_{30} + \theta'_{31}y] = a[\theta'_{30} + \theta'_{31}\phi_0 + \theta'_{31}\phi_1 h_1 + \theta'_{31}\phi_2 h_2 + \theta'_{31}\phi_3 h_3]$$

# Create new variables: $\psi$ (psi)

$\theta$  : theta  
 $\phi$  : phi  
 $\psi$  : psi

Hidden units of 2<sup>nd</sup> network in terms of hidden units of first network.

$$\begin{aligned}h'_1 &= a[\theta'_{10} + \theta'_{11}y] &= a[\theta'_{10} + \theta'_{11}\phi_0 + \theta'_{11}\phi_1h_1 + \theta'_{11}\phi_2h_2 + \theta'_{11}\phi_3h_3] \\h'_2 &= a[\theta'_{20} + \theta'_{21}y] &= a[\theta'_{20} + \theta'_{21}\phi_0 + \theta'_{21}\phi_1h_1 + \theta'_{21}\phi_2h_2 + \theta'_{21}\phi_3h_3] \\h'_3 &= a[\theta'_{30} + \theta'_{31}y] &= a[\theta'_{30} + \theta'_{31}\phi_0 + \theta'_{31}\phi_1h_1 + \theta'_{31}\phi_2h_2 + \theta'_{31}\phi_3h_3]\end{aligned}$$

Collect and rename the variables for conciseness.

$$\begin{aligned}h'_1 &= a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3] \\h'_2 &= a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3] \\h'_3 &= a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]\end{aligned}$$

$\theta$  : theta  
 $\phi$  : phi  
 $\psi$  : psi

# We get a two-layer network

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

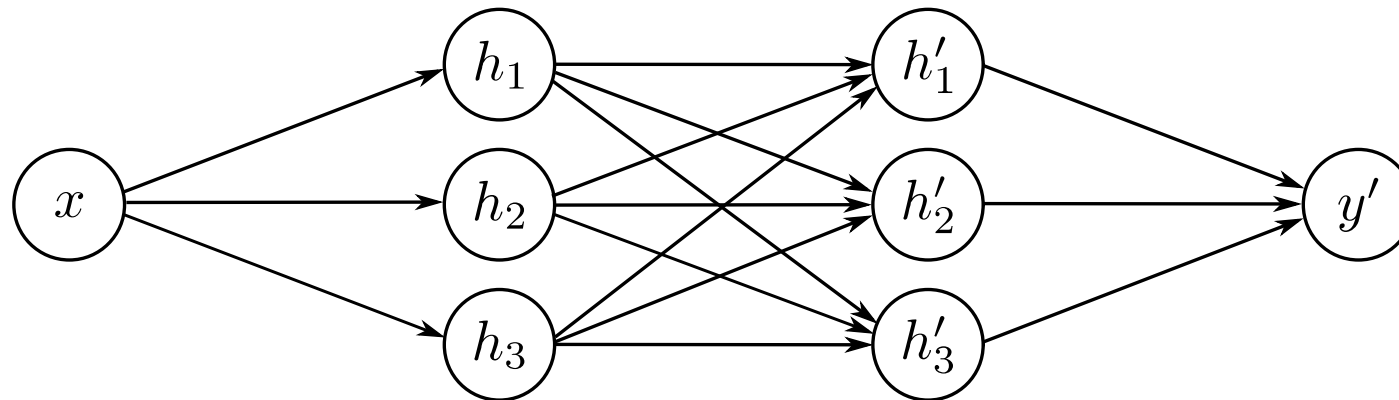
$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$



$\theta$  : theta  
 $\phi$  : phi  
 $\psi$  : psi

# Two-layer network as one equation

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$

---

$$\begin{aligned} y' = & \phi'_0 + \phi'_1 a[\psi_{10} + \psi_{11}a[\theta_{10} + \theta_{11}x] + \psi_{12}a[\theta_{20} + \theta_{21}x] + \psi_{13}a[\theta_{30} + \theta_{31}x]] \\ & + \phi'_2 a[\psi_{20} + \psi_{21}a[\theta_{10} + \theta_{11}x] + \psi_{22}a[\theta_{20} + \theta_{21}x] + \psi_{23}a[\theta_{30} + \theta_{31}x]] \\ & + \phi'_3 a[\psi_{30} + \psi_{31}a[\theta_{10} + \theta_{11}x] + \psi_{32}a[\theta_{20} + \theta_{21}x] + \psi_{33}a[\theta_{30} + \theta_{31}x]] \end{aligned}$$

# Remember shallow network with two outputs?

- 1 input, 4 hidden units, 2 outputs

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

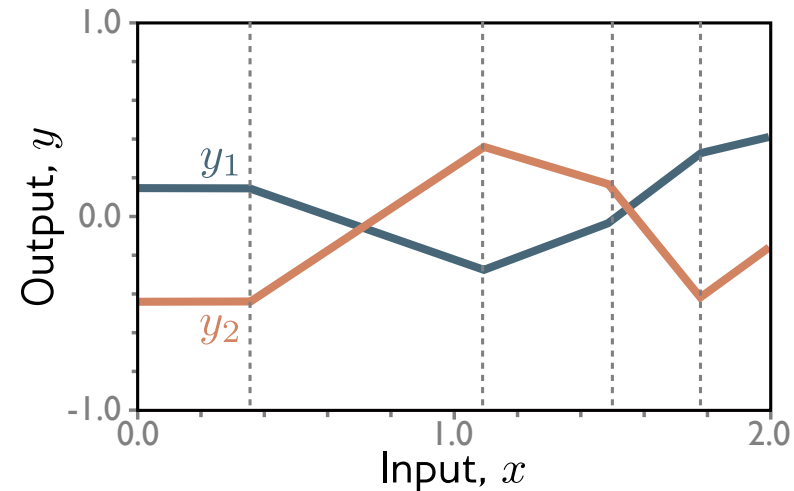
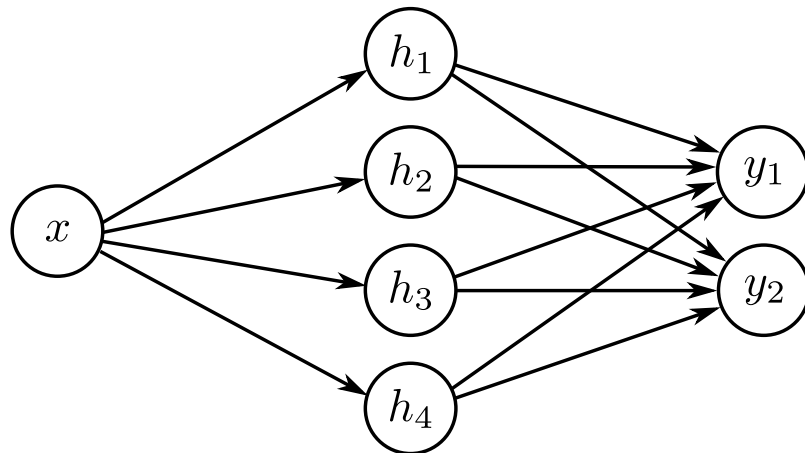
$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h_4 = a[\theta_{40} + \theta_{41}x]$$

$$y_1 = \phi_{10} + \phi_{11}h_1 + \phi_{12}h_2 + \phi_{13}h_3 + \phi_{14}h_4$$

$$y_2 = \phi_{20} + \phi_{21}h_1 + \phi_{22}h_2 + \phi_{23}h_3 + \phi_{24}h_4$$



# Networks as composing functions

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

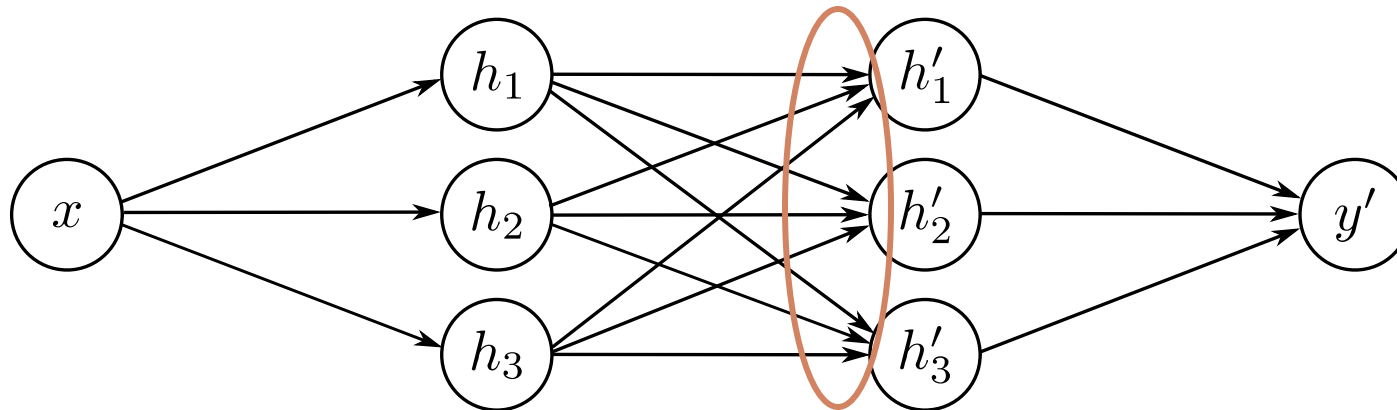
$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

Consider the pre-activations at the second hidden units  
At this point, it's a one--layer network with three outputs



# Networks as composing functions

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

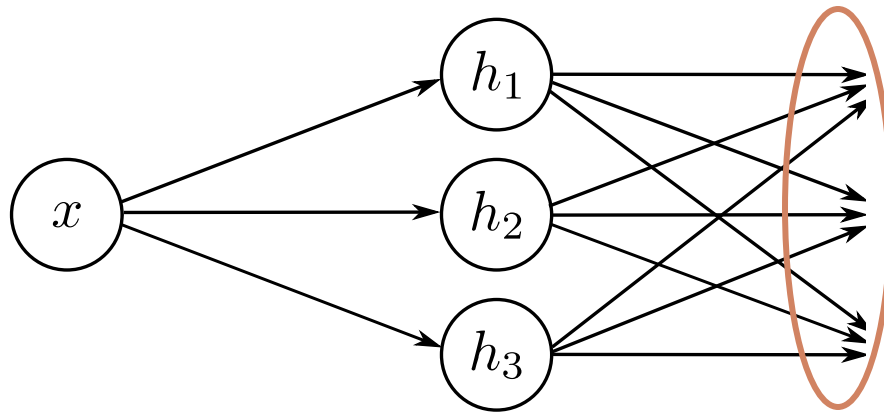
$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

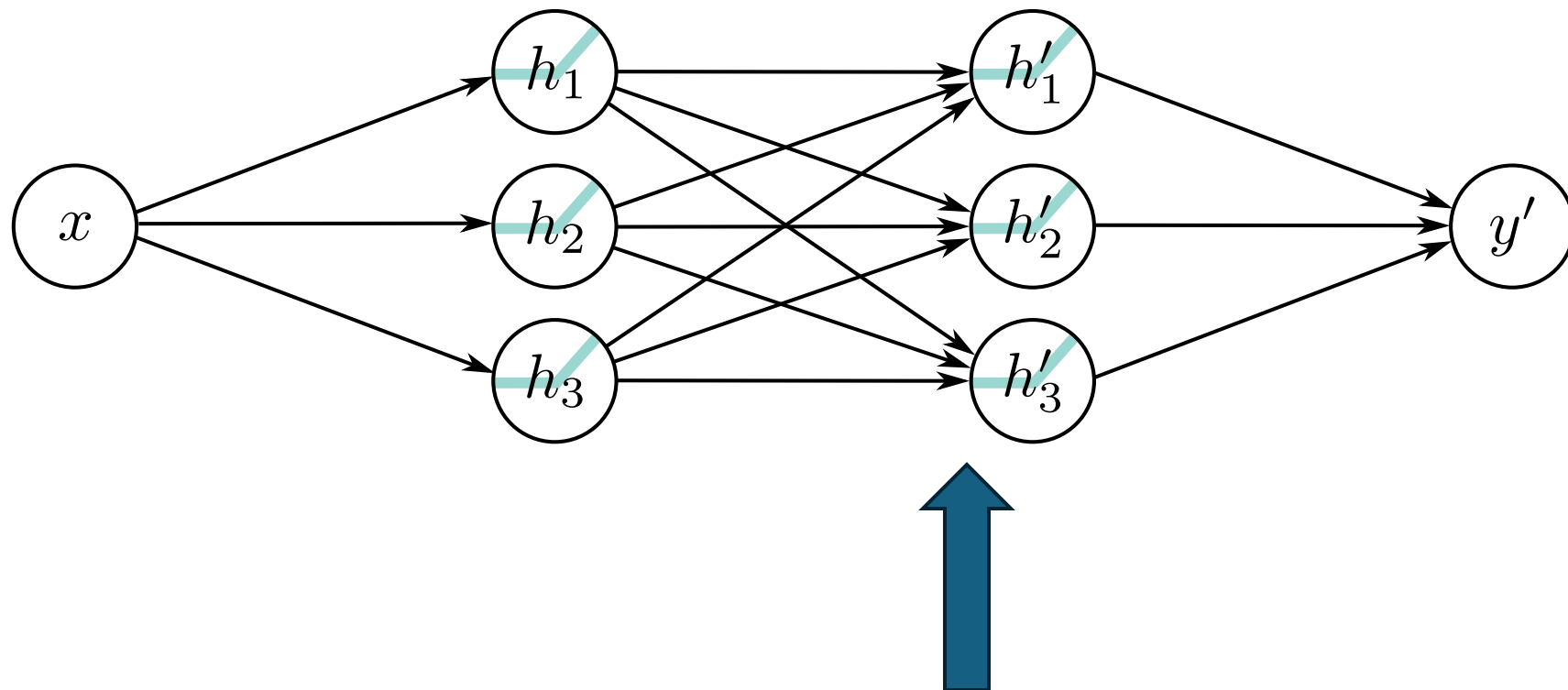
$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

Consider the pre-activations at the second hidden units  
At this point, it's a one--layer network with three outputs

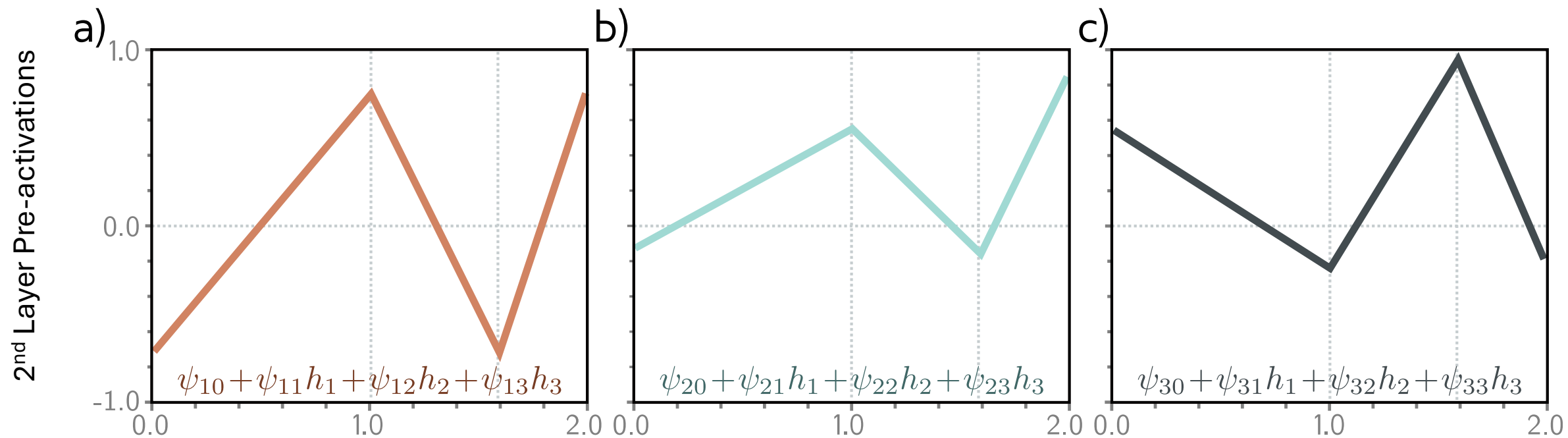
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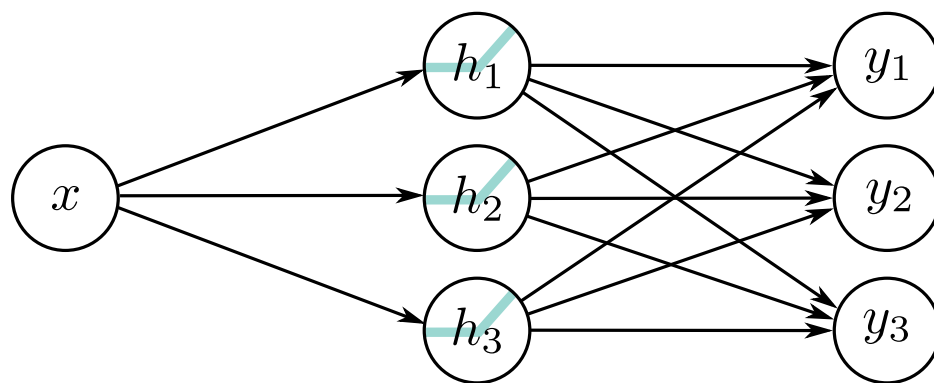


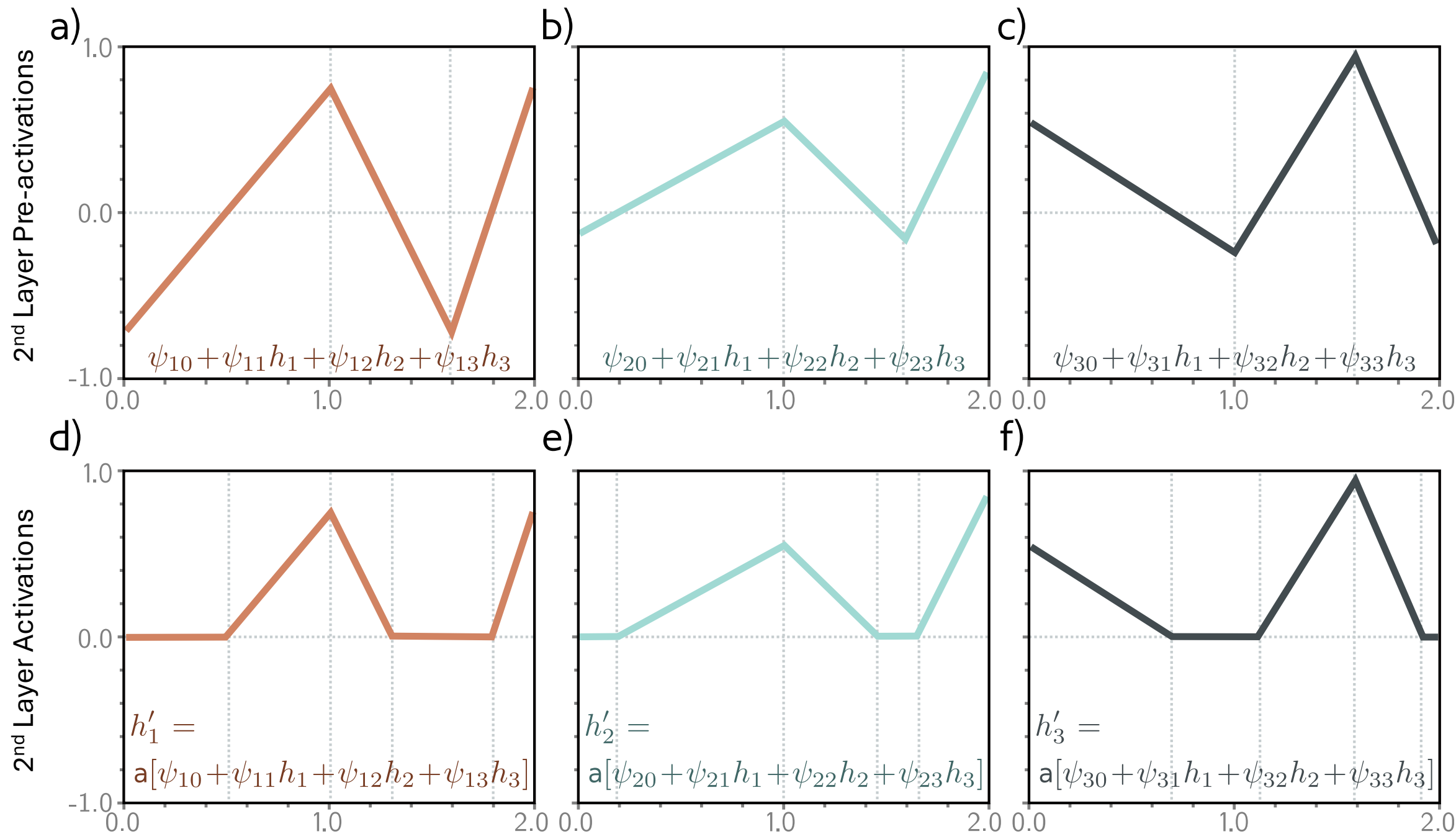
Let's walk through example activations starting with pre-activations to the 2<sup>nd</sup> layer.

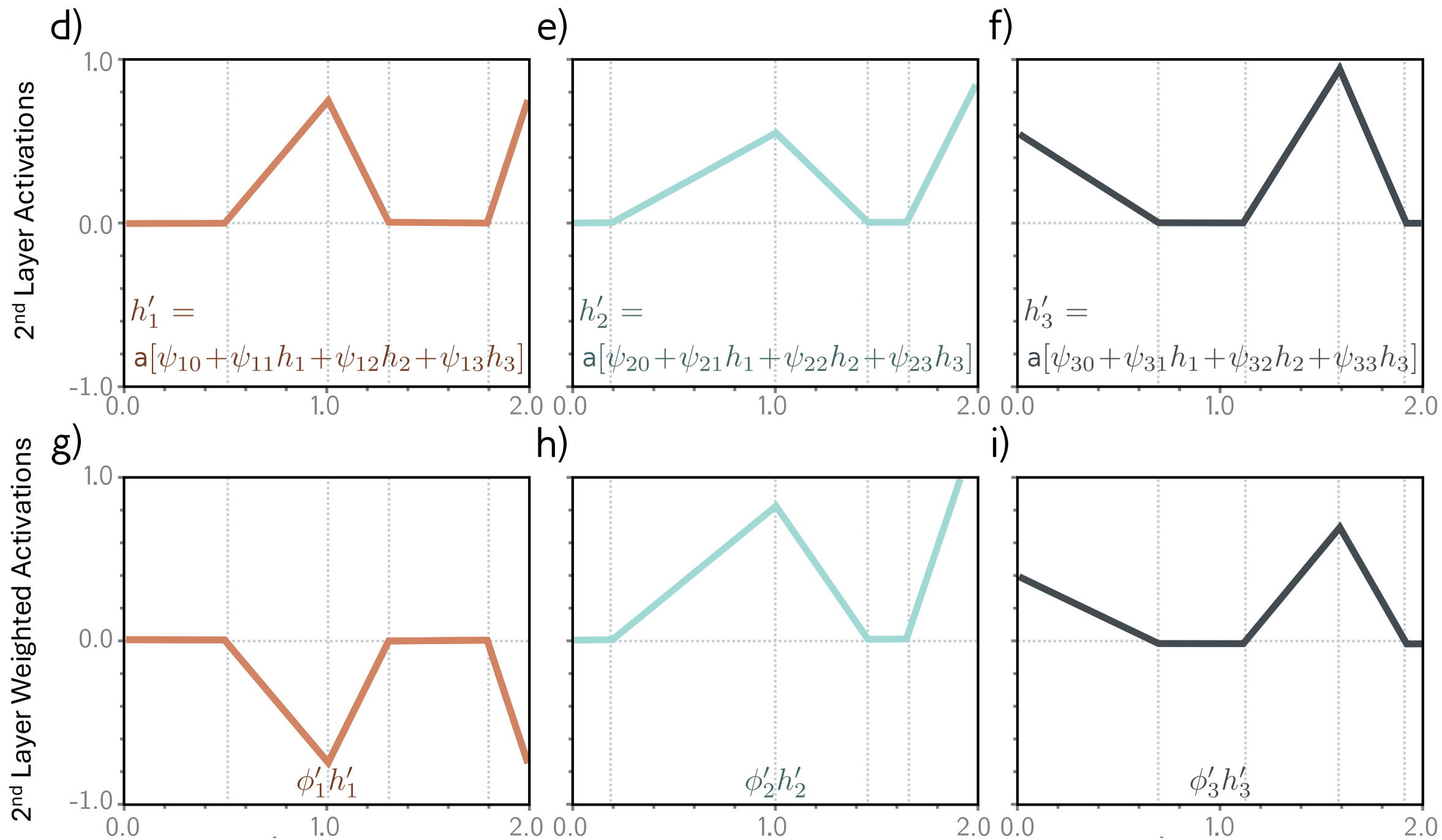


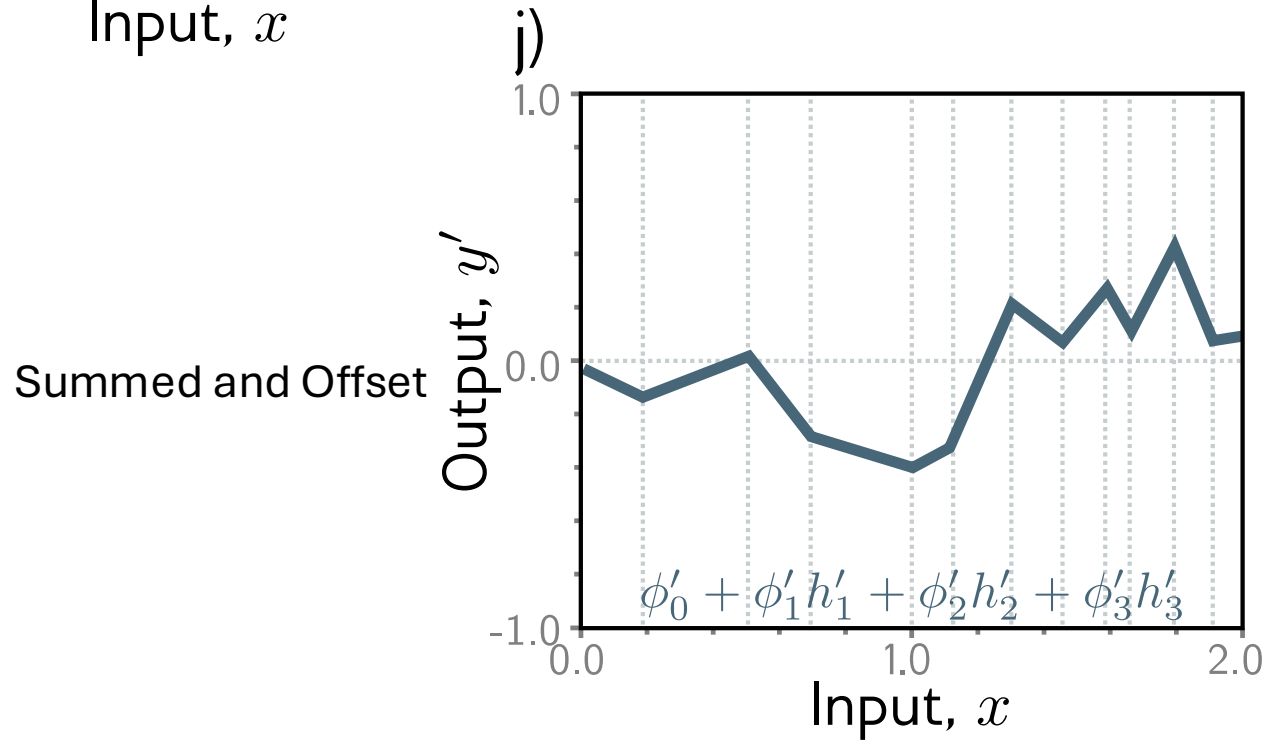
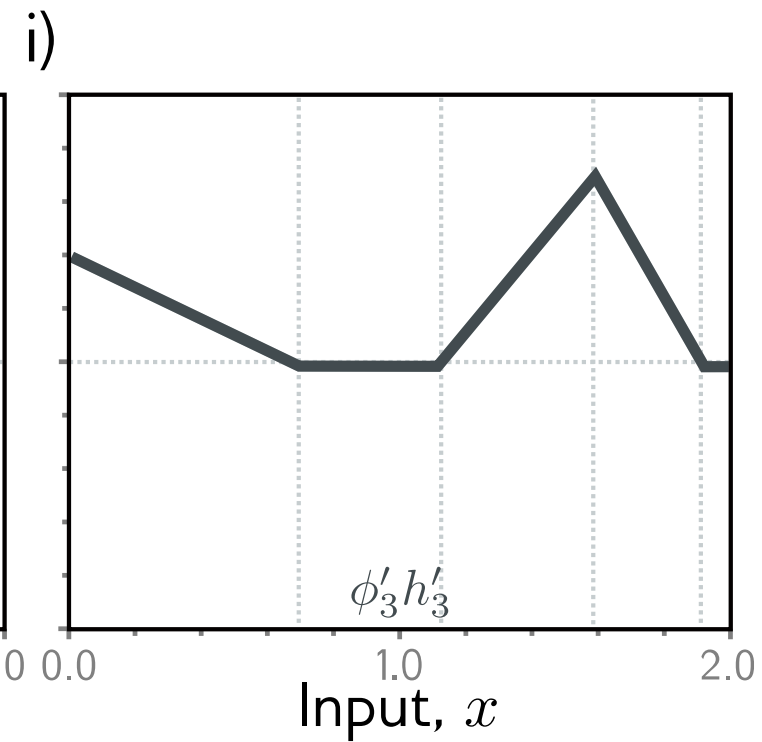
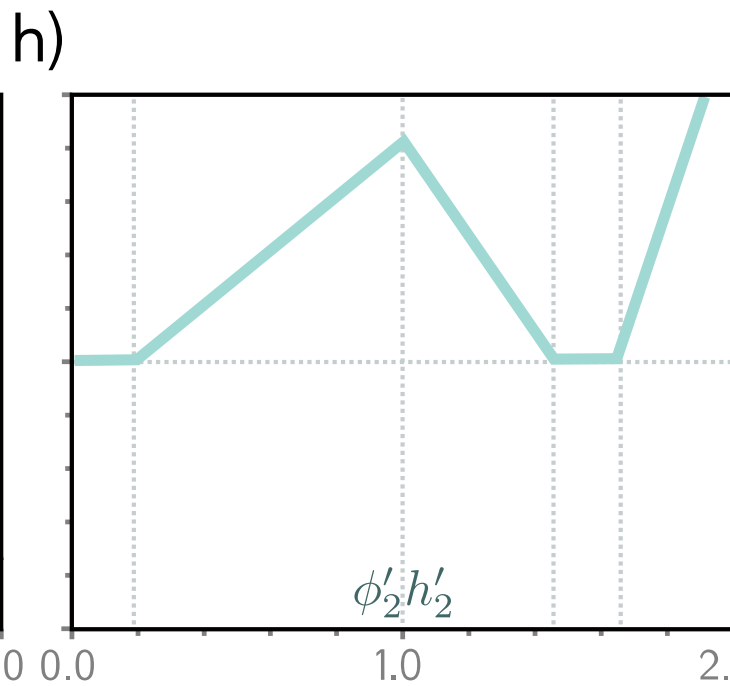
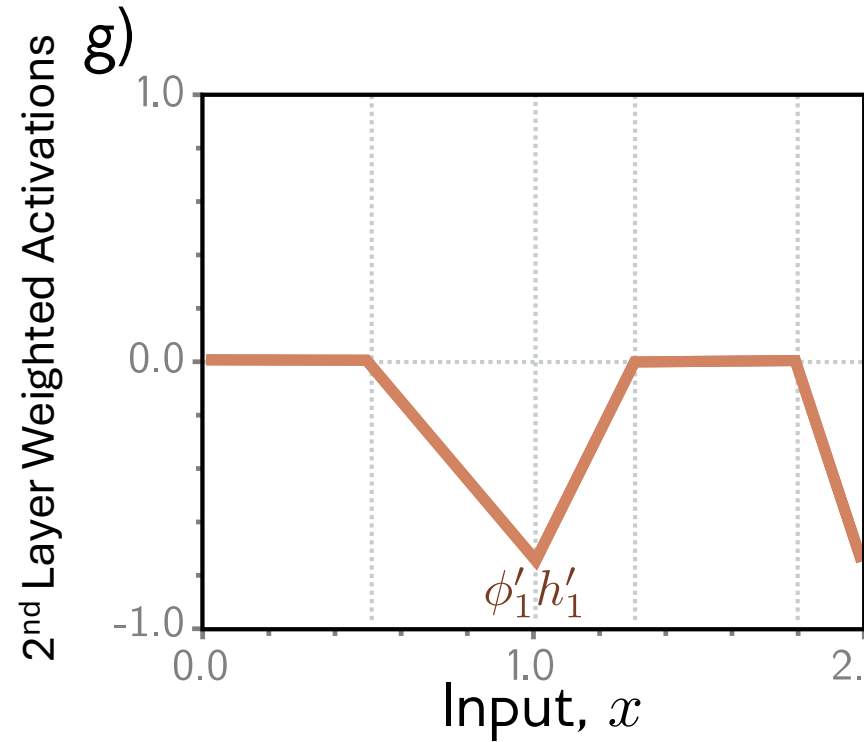


Like a shallow network with three hidden units and three outputs.









2<sup>nd</sup> Analogy:  
Create new functions  
which are clipped  
and recombined.

# Deep neural networks

- Composing two networks
- Combining the two networks into one
- Hyperparameters
- Notation change and general case
- Shallow vs. deep networks

# Hyperparameters

- K layers = depth of network
- $D_k$  hidden units per layer = width of network
- These are called hyperparameters – chosen before training the network
- Can try retraining with different hyperparameters – hyperparameter optimization or hyperparameter search
  - This can be either manual or automated (e.g. [Hyperparameter Tuning with Ray Tune](#))

# Deep neural networks

- Composing two networks
- Combining the two networks into one
- Hyperparameters
- Notation change and general case
- Shallow vs. deep networks

Propose 3 notation changes to be able to generalize to arbitrary deep neural networks.



# Notation change #1

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$

$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$

# Notation change #1

*Vector Notation*

$$h_1 = a[\theta_{10} + \theta_{11}x]$$

$$h_2 = a[\theta_{20} + \theta_{21}x]$$

$$h_3 = a[\theta_{30} + \theta_{31}x]$$



$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \theta_{10} \\ \theta_{20} \\ \theta_{30} \end{bmatrix} + \begin{bmatrix} \theta_{11} \\ \theta_{21} \\ \theta_{31} \end{bmatrix} x \right]$$

$$h'_1 = a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3]$$

$$h'_2 = a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3]$$

$$h'_3 = a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$

# Notation change #1

$$\begin{aligned}h_1 &= a[\theta_{10} + \theta_{11}x] \\h_2 &= a[\theta_{20} + \theta_{21}x] \\h_3 &= a[\theta_{30} + \theta_{31}x]\end{aligned}$$



$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \theta_{10} \\ \theta_{20} \\ \theta_{30} \end{bmatrix} + \begin{bmatrix} \theta_{11} \\ \theta_{21} \\ \theta_{31} \end{bmatrix} x \right]$$

*Vector Notation*

$$\begin{aligned}h'_1 &= a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3] \\h'_2 &= a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3] \\h'_3 &= a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]\end{aligned}$$



$$\begin{bmatrix} h'_1 \\ h'_2 \\ h'_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \psi_{10} \\ \psi_{20} \\ \psi_{30} \end{bmatrix} + \begin{bmatrix} \psi_{11} & \psi_{12} & \psi_{13} \\ \psi_{21} & \psi_{22} & \psi_{23} \\ \psi_{31} & \psi_{32} & \psi_{33} \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} \right]$$

*Vector & Matrix Notation*

# Notation change #1

$$\begin{aligned}h_1 &= a[\theta_{10} + \theta_{11}x] \\h_2 &= a[\theta_{20} + \theta_{21}x] \\h_3 &= a[\theta_{30} + \theta_{31}x]\end{aligned}$$



$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \theta_{10} \\ \theta_{20} \\ \theta_{30} \end{bmatrix} + \begin{bmatrix} \theta_{11} \\ \theta_{21} \\ \theta_{31} \end{bmatrix} x \right]$$

$$\begin{aligned}h'_1 &= a[\psi_{10} + \psi_{11}h_1 + \psi_{12}h_2 + \psi_{13}h_3] \\h'_2 &= a[\psi_{20} + \psi_{21}h_1 + \psi_{22}h_2 + \psi_{23}h_3] \\h'_3 &= a[\psi_{30} + \psi_{31}h_1 + \psi_{32}h_2 + \psi_{33}h_3]\end{aligned}$$



$$\begin{bmatrix} h'_1 \\ h'_2 \\ h'_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \psi_{10} \\ \psi_{20} \\ \psi_{30} \end{bmatrix} + \begin{bmatrix} \psi_{11} & \psi_{12} & \psi_{13} \\ \psi_{21} & \psi_{22} & \psi_{23} \\ \psi_{32} & \psi_{32} & \psi_{33} \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} \right]$$

$$y' = \phi'_0 + \phi'_1 h'_1 + \phi'_2 h'_2 + \phi'_3 h'_3$$



$$y' = \phi'_0 + \begin{bmatrix} \phi'_1 & \phi'_2 & \phi'_3 \end{bmatrix} \begin{bmatrix} h'_1 \\ h'_2 \\ h'_3 \end{bmatrix}$$

# Notation change #2

## Notation Reminder

$x, \psi$  : normal lower case -- scalar

$\mathbf{x}, \boldsymbol{\psi}$  : bold face lower case -- vector

$\mathbf{X}, \boldsymbol{\Psi}$  : bold face upper case -- matrix

$$\begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \theta_{10} \\ \theta_{20} \\ \theta_{30} \end{bmatrix} + \begin{bmatrix} \theta_{11} \\ \theta_{21} \\ \theta_{31} \end{bmatrix} x \right] \longrightarrow \mathbf{h} = \mathbf{a}[\boldsymbol{\theta}_0 + \boldsymbol{\theta}_1 x]$$

$$\begin{bmatrix} h'_1 \\ h'_2 \\ h'_3 \end{bmatrix} = \mathbf{a} \left[ \begin{bmatrix} \psi_{10} \\ \psi_{20} \\ \psi_{30} \end{bmatrix} + \begin{bmatrix} \psi_{11} & \psi_{12} & \psi_{13} \\ \psi_{21} & \psi_{22} & \psi_{23} \\ \psi_{31} & \psi_{32} & \psi_{33} \end{bmatrix} \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix} \right] \longrightarrow \mathbf{h}' = \mathbf{a}[\boldsymbol{\psi}_0 + \boldsymbol{\Psi} \mathbf{h}]$$

$$y' = \phi'_0 + [\phi'_1 \quad \phi'_2 \quad \phi'_3] \begin{bmatrix} h'_1 \\ h'_2 \\ h'_3 \end{bmatrix} \longrightarrow y' = \phi'_0 + \boldsymbol{\phi}'^T \mathbf{h}'$$

$\omega$  : omega  
 $\Omega$  : Omega

## Notation change #3

$\mathbf{h} = \mathbf{a} [\boldsymbol{\theta}_0 + \boldsymbol{\theta}x]$	$\longrightarrow$	$\mathbf{h}_1 = \mathbf{a} [\boldsymbol{\beta}_0 + \boldsymbol{\Omega}_0 \mathbf{x}]$
$\mathbf{h}' = \mathbf{a} [\boldsymbol{\psi}_0 + \boldsymbol{\Psi} \mathbf{h}]$	$\longrightarrow$	$\mathbf{h}_2 = \mathbf{a} [\boldsymbol{\beta}_1 + \boldsymbol{\Omega}_1 \mathbf{h}_1]$
$y = \phi'_0 + \phi' \mathbf{h}'$	$\longrightarrow$	$y = \beta_2 + \boldsymbol{\Omega}_2 \mathbf{h}_2$

$\omega$  : omega  
 $\Omega$  : Omega

## Notation change #3

$$\mathbf{h} = \mathbf{a} [\boldsymbol{\theta}_0 + \boldsymbol{\theta}x]$$

Bias vector

Weight matrix

$$\mathbf{h}_1 = \mathbf{a} [\boldsymbol{\beta}_0 + \boldsymbol{\Omega}_0 \mathbf{x}]$$

$$\mathbf{h}' = \mathbf{a} [\boldsymbol{\psi}_0 + \boldsymbol{\Psi} \mathbf{h}]$$

$$\mathbf{h}_2 = \mathbf{a} [\boldsymbol{\beta}_1 + \boldsymbol{\Omega}_1 \mathbf{h}_1]$$

$$y = \phi'_0 + \phi' \mathbf{h}'$$

$$y = \beta_2 + \boldsymbol{\Omega}_2 \mathbf{h}_2$$

# General equations for deep network

$$\mathbf{h}_1 = \mathbf{a}[\boldsymbol{\beta}_0 + \boldsymbol{\Omega}_0 \mathbf{x}]$$

$$\mathbf{h}_2 = \mathbf{a}[\boldsymbol{\beta}_1 + \boldsymbol{\Omega}_1 \mathbf{h}_1]$$

$$\mathbf{h}_3 = \mathbf{a}[\boldsymbol{\beta}_2 + \boldsymbol{\Omega}_2 \mathbf{h}_2]$$

$$\vdots$$

$$\mathbf{h}_K = \mathbf{a}[\boldsymbol{\beta}_{K-1} + \boldsymbol{\Omega}_{K-1} \mathbf{h}_{K-1}]$$

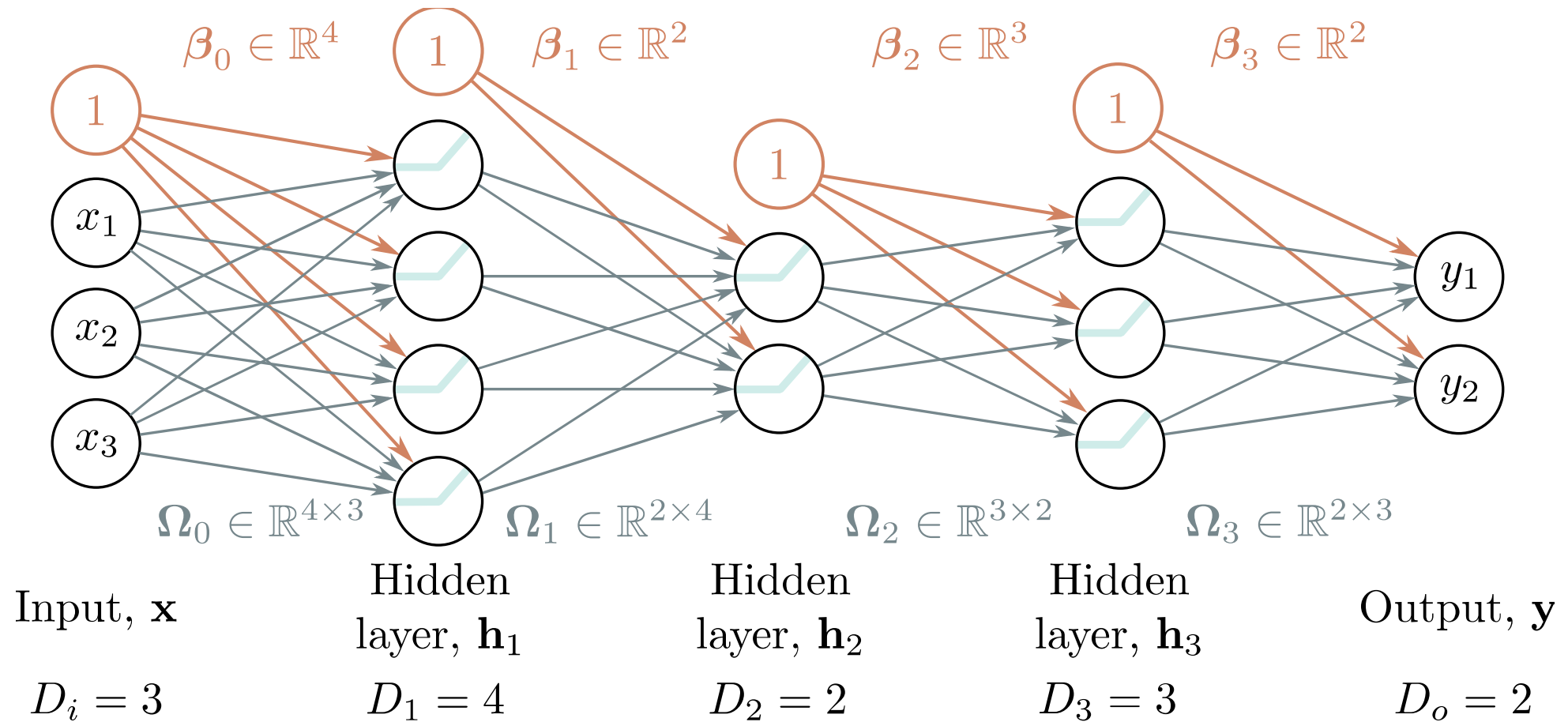
$$\mathbf{y} = \boldsymbol{\beta}_K + \boldsymbol{\Omega}_K \mathbf{h}_K,$$

---

$$\mathbf{y} = \boldsymbol{\beta}_K + \boldsymbol{\Omega}_K \mathbf{a} \left[ \boldsymbol{\beta}_{K-1} + \boldsymbol{\Omega}_{K-1} \mathbf{a} \left[ \dots \boldsymbol{\beta}_2 + \boldsymbol{\Omega}_2 \mathbf{a} \left[ \boldsymbol{\beta}_1 + \boldsymbol{\Omega}_1 \mathbf{a} \left[ \boldsymbol{\beta}_0 + \boldsymbol{\Omega}_0 \mathbf{x} \right] \dots \right] \right] \right]$$



# Example



# Deep neural networks


- Composing two networks
- Combining the two networks into one
- Hyperparameters
- Notation change and general case
- Shallow vs. deep networks

# Shallow vs. deep networks

The best results are created by deep networks with many layers.

- 50-1000 layers for most applications
- Best results in

- Computer vision
- Natural language processing
- Graph neural networks
- Generative models
- Reinforcement learning



All use deep networks.  
But why?

# Shallow vs. deep networks

1. Ability to approximate different functions?

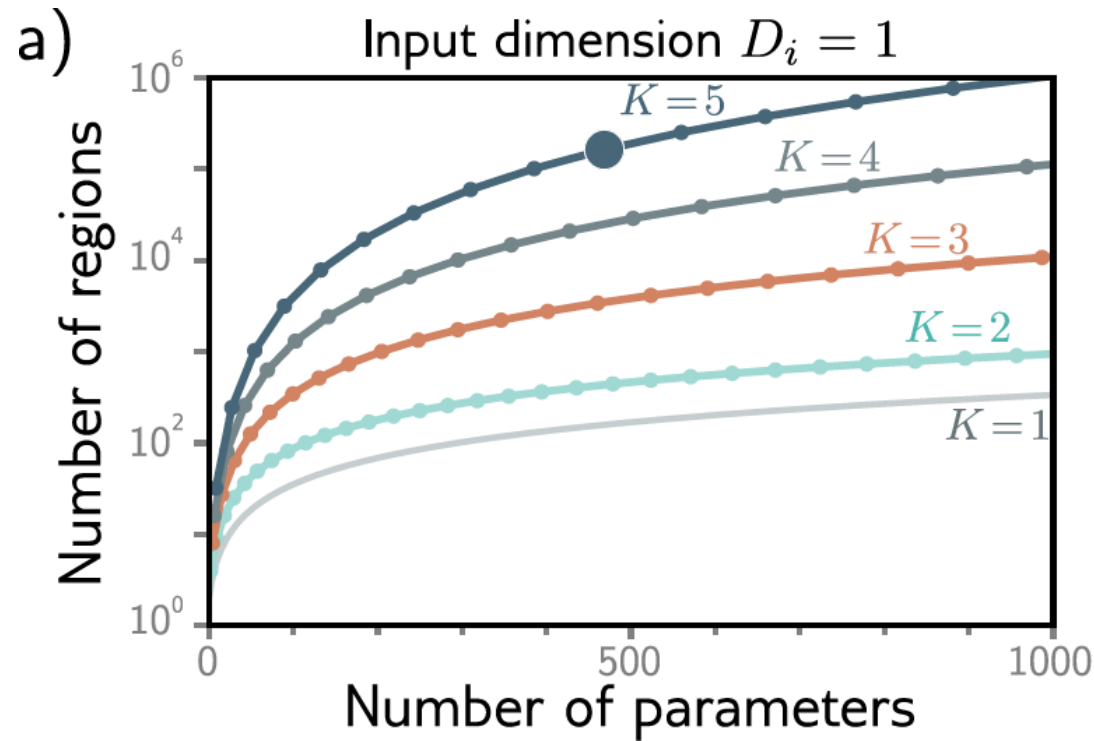
Both obey the universal approximation theorem.

Argument: One layer is enough, and for deep networks could arrange for the other layers to compute the identity function.

# Shallow vs. deep networks

2. Number of linear regions per parameter

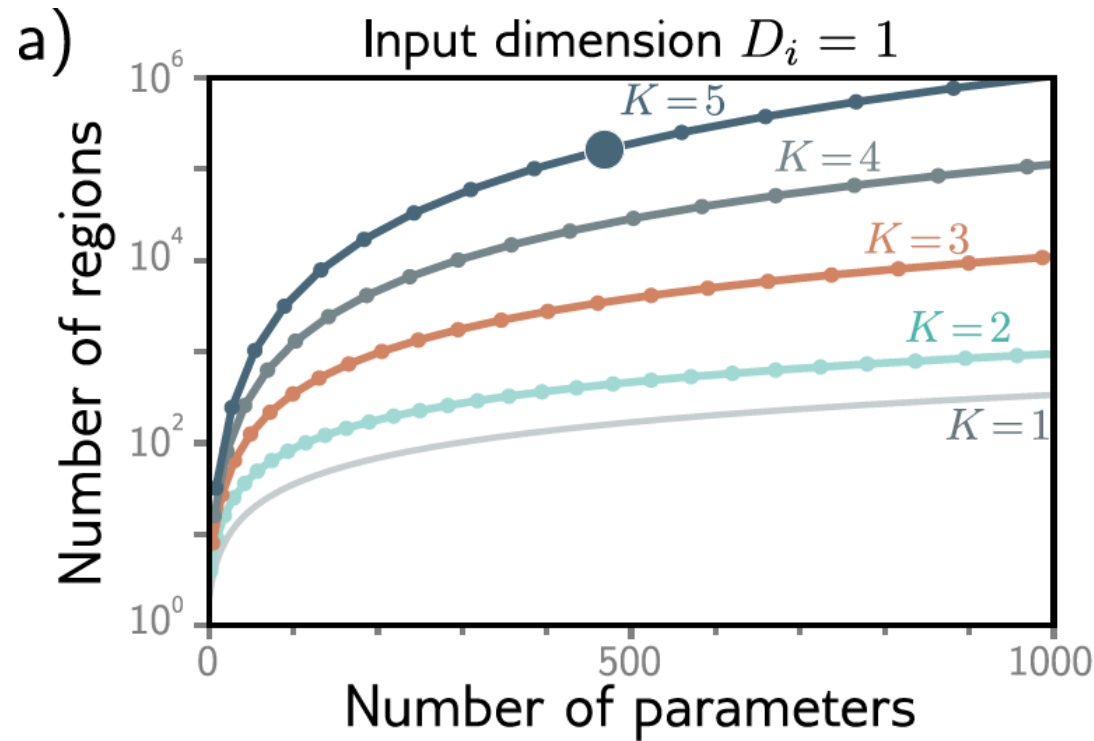
# Number of linear regions per parameter



Each small dot is  
an additional  
hidden unit per  
layer.

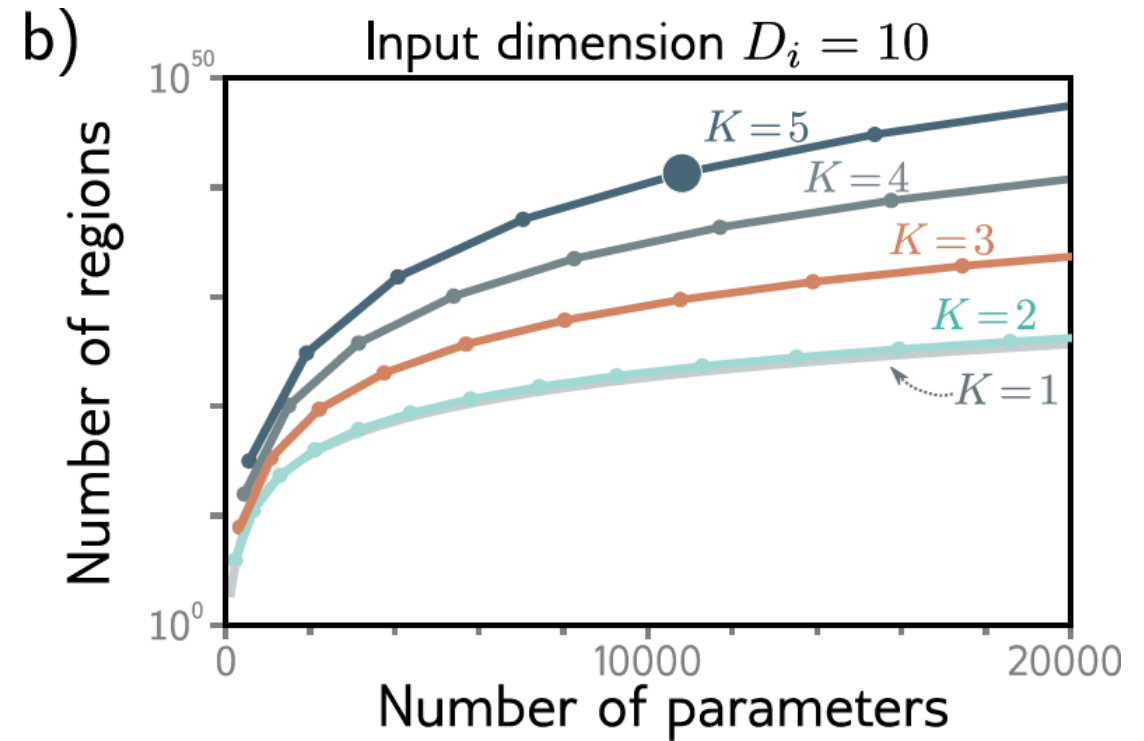
●  $K = 5$  layers  
10 hidden units per layer  
471 parameters  
161,501 linear regions

# Number of linear regions per parameter



Each small dot is an additional hidden unit per layer.

● 5 layers  
10 hidden units per layer  
471 parameters  
161,501 linear regions



Each small dot is an additional 10 hidden units per layer.

● 5 layers  
50 hidden units per layer  
10,801 parameters  
>  $10^{40}$  linear regions

# Shallow vs. deep networks

## 2. Number of linear regions per parameter

- Deep networks create many more regions per parameters
- But there are dependencies between them
  - Think of folding example
  - Perhaps similar symmetries in real-world functions? Unknown



# Shallow vs. Deep Networks

## 3. Depth efficiency

- There are some functions that require a shallow network with exponentially more hidden units than a deep network to achieve an equivalent approximation
- This is known as the **depth efficiency** of deep networks
- But do the real-world functions we want to approximate have this property? Unknown.

# Shallow vs. Deep Networks

## 4. Large structured networks

- Think about images as input – might be 1M pixels
- Fully connected works not practical
- Answer is to have weights that only operate locally, and share across image
- This leads to **convolutional networks**
- Gradually integrate information from across the image – needs multiple layers

# Shallow vs. Deep Networks

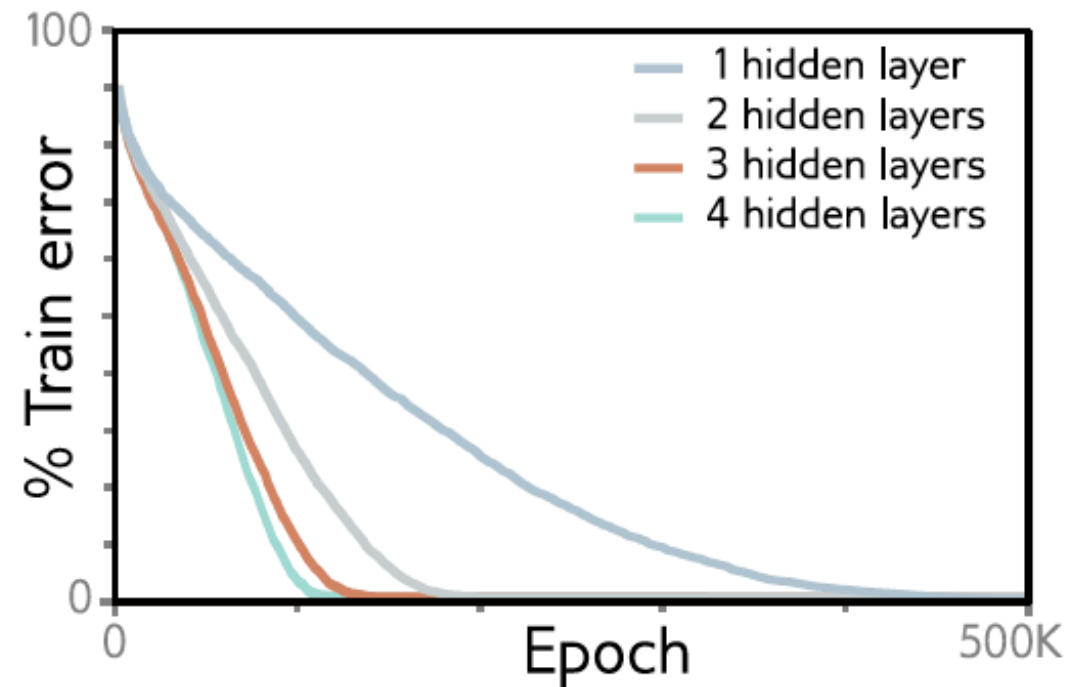
## 5. Fitting and generalization

- Fitting of deep models seems to be easier up to about 20 layers
- Then needs various tricks to train deeper networks, so (in vanilla form), fitting becomes harder
- Generalization is good in deep networks. Why?

# Shallow vs. Deep Networks

## 5. Fitting and generalization

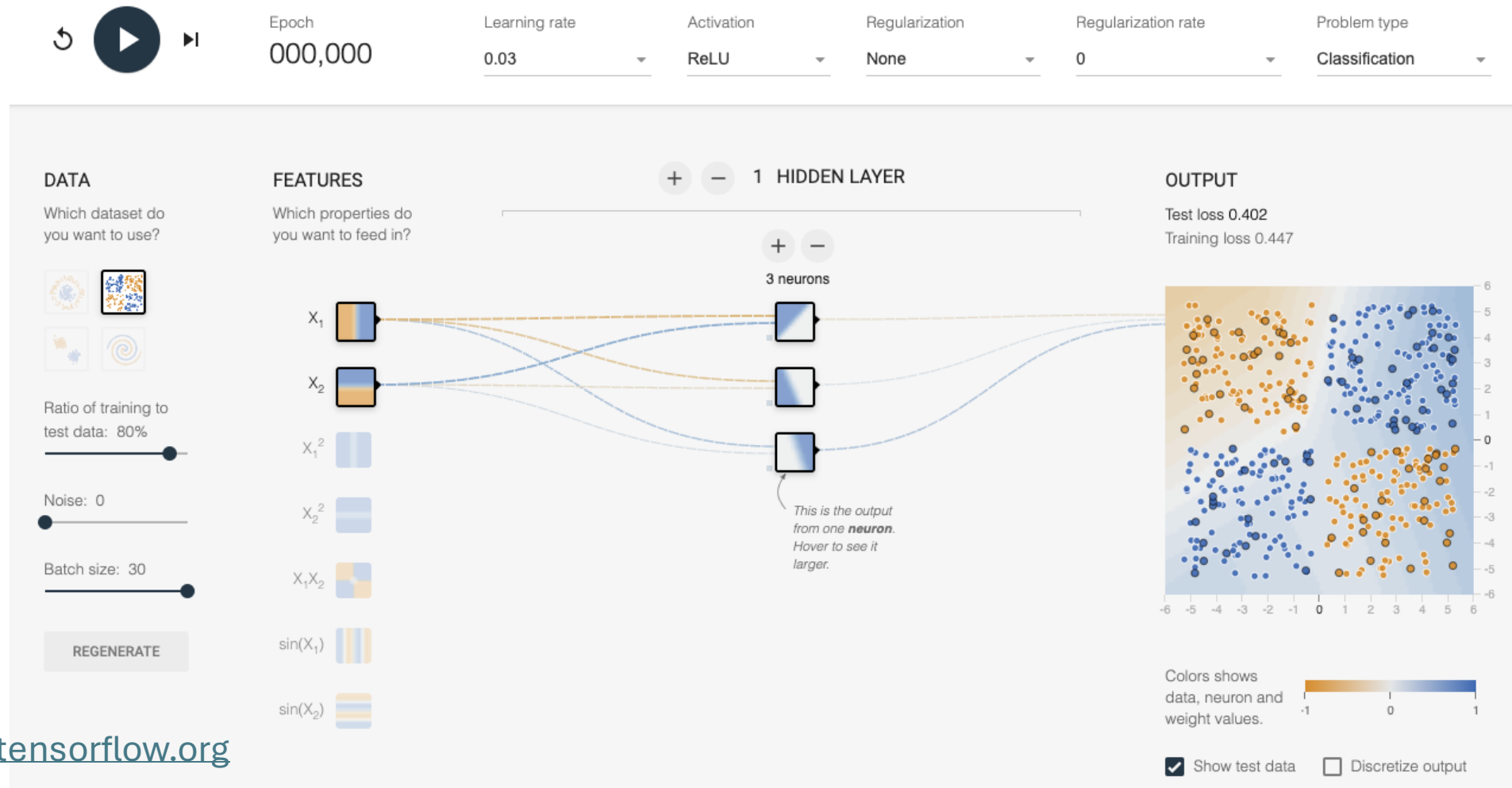
**Figure 20.2** MNIST-1D training. Four fully connected networks were fit to 4000 MNIST-1D examples with random labels using full batch gradient descent, He initialization, no momentum or regularization, and learning rate 0.0025. Models with 1,2,3,4 layers had 298, 100, 75, and 63 hidden units per layer and 15208, 15210, 15235, and 15139 parameters, respectively. All models train successfully, but deeper models require fewer epochs.



# Tensorflow Playground Example?

- Try 2 inputs, 3 hidden units, 1 output
- You can inspect and/or edit weights and biases

Do you ever get stuck in local minima?  
Are you getting the expected number of regions?



# Where are we going?

- We have defined families of very flexible networks that map multiple inputs to multiple outputs
- Now we need to train them
  - How to choose loss functions for different types of targets (Read Ch. 5)
  - How to find minima of the loss function
  - How to do this efficiently with deep networks
- Then how do we evaluate them?