

# Deep Learning for Data Science DS 542

https://dl4ds.github.io/fa2025/

**Gradient Descent** 



#### Announcements

- Re: discussion deadlines are moving to 11:59pm on the day of discussion.
  - Why? The practice is more important than the timing.
  - Still targeting  $\leq 30$  minutes to do, but more time if you need/want it.
- Shared Compute Cluster (SCC) Tutorial next Monday.
  - Please bring your laptop to class.
  - No graded exercise, but will be walking through account setup.

# Plan for Today

- Loss functions for multiclass classification (spillover)
- Example of gradient descent
- Basics of gradient descent
- Gradient descent as a statistical process
- Challenges with gradient descent

# Loss Function for Regression

If you recast regression as

- 1. Predicting the mean of a normal distribution with a fixed variance and
- 2. Optimize output for maximum likelihood,

Then the optimization is equivalent to optimizing with least squared errors  $(L_2)$  as your loss function.

# Loss Function for Binary Classification

If you are modeling a binary classification problem,

- 1. The sigmoid function is handy to map arbitrary "scores" into probabilities, so
- 2. Your loss function is equivalent to

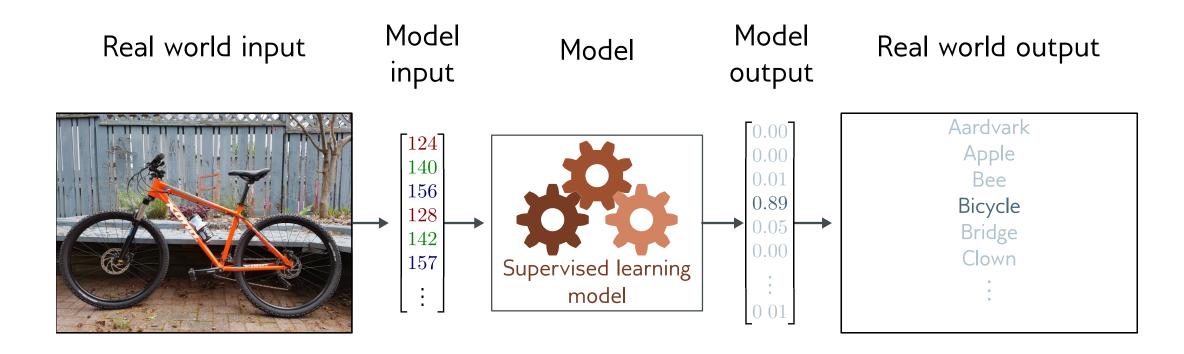
$$L[\phi] = \sum_{i} -(1 - y_i) \log[1 - \text{sig}[f[x_i | \phi]] - y_i \log[\text{sig}[f[x_i | \phi]]]$$

# Conceptualizing the Binary Loss Function

$$L[\phi] = \sum_{i} -(1 - y_i) \log[1 - \text{sig}[f[x_i | \phi]] - y_i \log[\text{sig}[f[x_i | \phi]]]$$

$$L[\phi] = \sum_{i} -(1 - y_i) \log \Pr[y_i = 0 | x_i] - y_i \log \Pr[y_i = 1 | x_i]$$

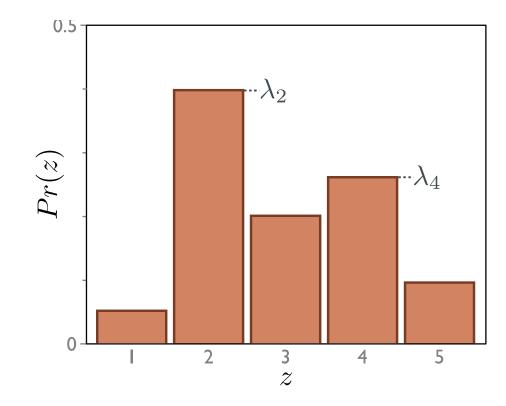
$$L[\phi] = \sum_{i} -\log \Pr[y_i | x_i]$$



Goal: predict which of K classes  $y \in \{1, 2, ..., K\}$  the input x belongs to.

- 1. Choose a suitable probability distribution  $Pr(\mathbf{y}|\boldsymbol{\theta})$  that is defined over the domain of the predictions  $\mathbf{y}$  and has distribution parameters  $\boldsymbol{\theta}$ .
- Domain:  $y \in \{1, 2, ..., K\}$
- Categorical distribution
- K parameters  $\lambda_k \in [0,1]$
- $\sum_k \lambda_k = 1$

$$Pr(y=k)=\lambda_k$$



2. Set the machine learning model  $\mathbf{f}[\mathbf{x}, \boldsymbol{\phi}]$  to predict one or more of these parameters so  $\boldsymbol{\theta} = \mathbf{f}[\mathbf{x}, \boldsymbol{\phi}]$  and  $Pr(\mathbf{y}|\boldsymbol{\theta}) = Pr(\mathbf{y}|\mathbf{f}[\mathbf{x}, \boldsymbol{\phi}])$ .

#### Problem:

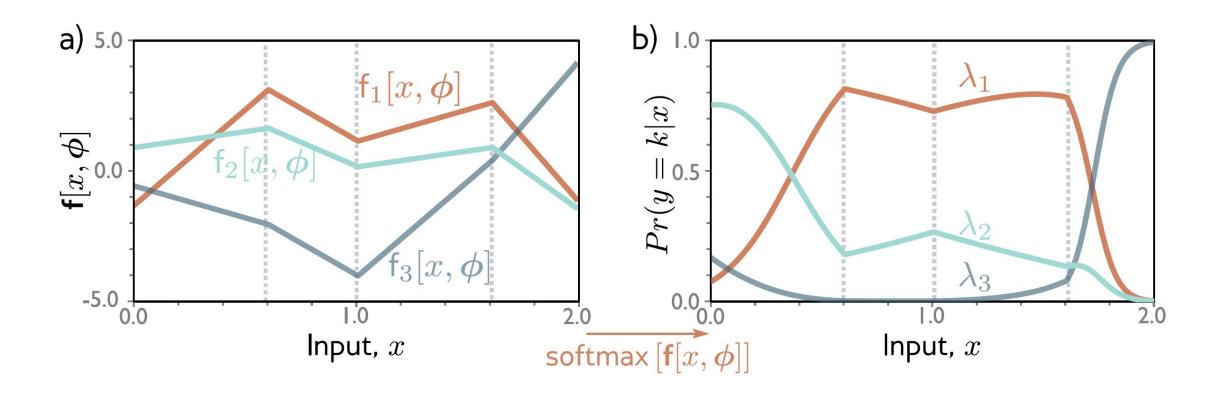
- Output of neural network can be anything
- Parameters  $\lambda_k \in [0,1]$ , sum to one

$$\operatorname{softmax}_{k}[\mathbf{z}] = \frac{\exp[z_{k}]}{\sum_{k'=1}^{K} \exp[z_{k'}]}$$

#### Solution:

 Pass through function that maps "anything" to [0,1] and sums to one

$$Pr(y = k|\mathbf{x}) = \operatorname{softmax}_k[\mathbf{f}[\mathbf{x}, \boldsymbol{\phi}]]$$



$$Pr(y = k|\mathbf{x}) = \operatorname{softmax}_k[\mathbf{f}[\mathbf{x}, \boldsymbol{\phi}]]$$

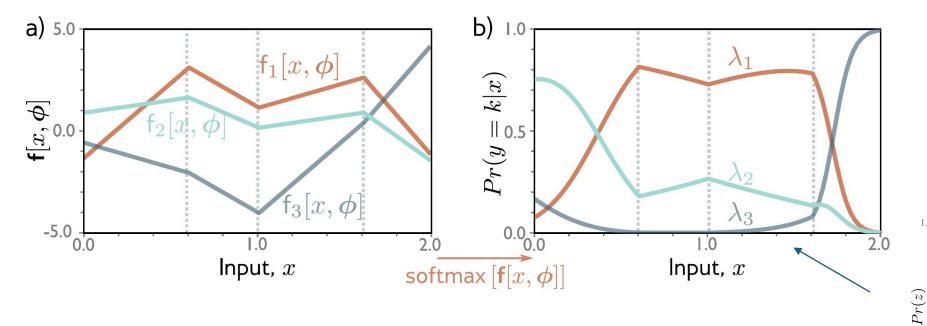
3. To train the model, find the network parameters  $\phi$  that minimize the negative log-likelihood loss function over the training dataset pairs  $\{\mathbf{x}_i, \mathbf{y}_i\}$ :

$$\hat{\boldsymbol{\phi}} = \underset{\boldsymbol{\phi}}{\operatorname{argmin}} \left[ L[\boldsymbol{\phi}] \right] = \underset{\boldsymbol{\phi}}{\operatorname{argmin}} \left[ -\sum_{i=1}^{I} \log \left[ Pr(\mathbf{y}_i | \mathbf{f}[\mathbf{x}_i, \boldsymbol{\phi}]) \right] \right]. \tag{5.7}$$

$$L[\boldsymbol{\phi}] = -\sum_{i=1}^{I} \log \left[ \operatorname{softmax}_{y_i} \left[ \mathbf{f} \left[ \mathbf{x}_i, \boldsymbol{\phi} \right] \right] \right]$$
 softmax<sub>k</sub>[\mathbf{z}] = \frac{\exp[z\_k]}{\sum\_{k'=1}^{K} \exp[z\_{k'}]}

$$= -\sum_{i=1}^{I} \mathrm{f}_{y_i} \left[ \mathbf{x}_i, \boldsymbol{\phi} \right] - \log \left[ \sum_{k=1}^{K} \exp \left[ \mathrm{\ f}_k \left[ \mathbf{x}_i, \boldsymbol{\phi} \right] \right] \right]$$

4. To perform inference for a new test example  $\mathbf{x}$ , return either the full distribution  $Pr(\mathbf{y}|\mathbf{f}[\mathbf{x},\hat{\boldsymbol{\phi}}])$  or the maximum of this distribution.



Choose the class with the largest probability We also get probability or "confidence"

# Any questions?

# Multiple outputs

• Treat each output  $y_d$  as independent:

$$Pr(\mathbf{y}|\mathbf{f}[\mathbf{x}_i, \boldsymbol{\phi}]) = \prod_d Pr(y_d|\mathbf{f}_d[\mathbf{x}_i, \boldsymbol{\phi}])$$

where  $\mathbf{f}_d[\mathbf{x}, \phi]$  is the  $d^{th}$  set of network outputs

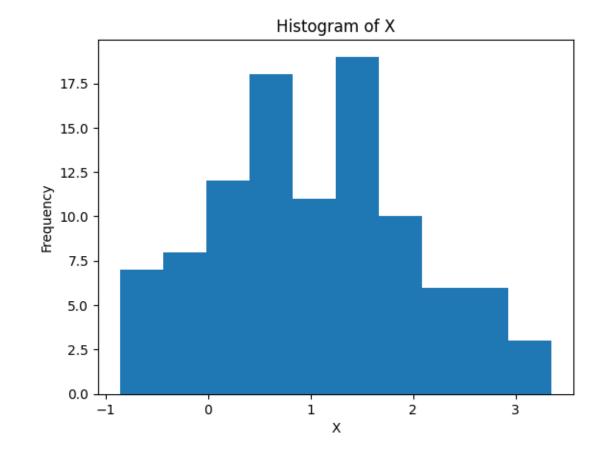
Negative log likelihood becomes sum of terms:

$$L[\boldsymbol{\phi}] = -\sum_{i=1}^{I} \log \left[ Pr(\mathbf{y}|\mathbf{f}[\mathbf{x}_i, \boldsymbol{\phi}]) \right] = -\sum_{i=1}^{I} \sum_{d} \log \left[ Pr(y_{id}|\mathbf{f}_d[\mathbf{x}_i, \boldsymbol{\phi}]) \right]$$

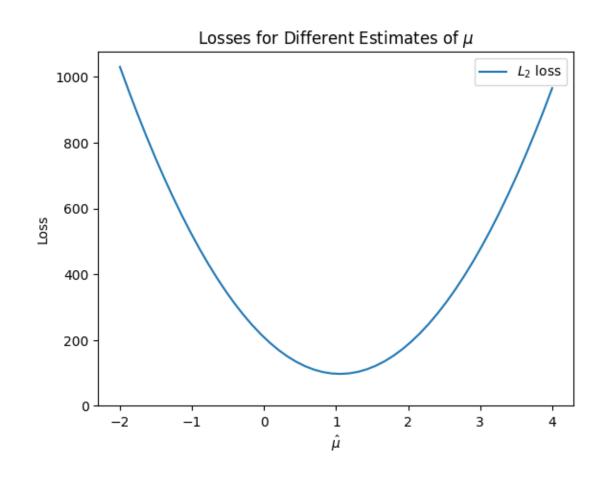
# Any questions?

# An Example of Gradient Descent

- X is 100 samples from a normal distribution.
  - What were the parameters of that normal distribution?
  - What was the mean of that normal distribution?



# Visualizing Gradient Descent



#### **Basics of Gradient Descent**

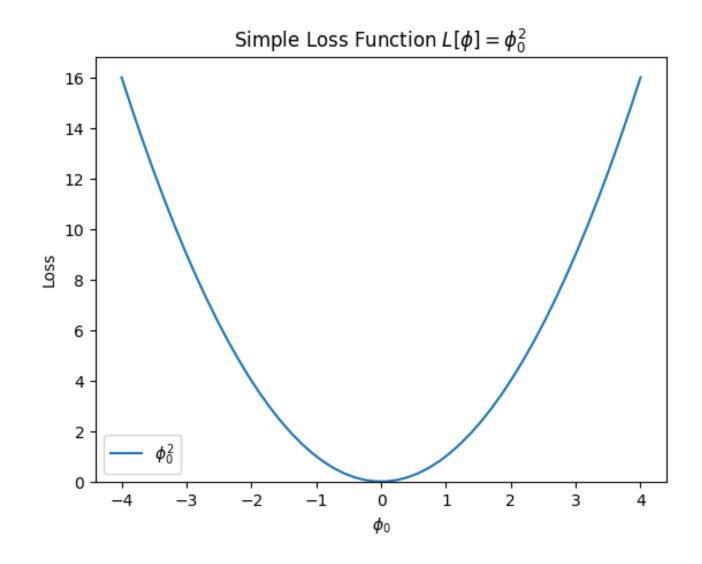
- Given current set of parameters  $\phi_t$ ,
  - Calculate all partial derivatives  $\frac{\partial L[\phi]}{\partial \phi_i}$  based on current parameters  $\phi_t$ .
  - The vector of these  $\frac{\partial L[\phi]}{\partial \phi_i}$  is the gradient of the loss function  $\nabla L[\phi]$ .
  - Update  $\phi_{t+1} = \phi_t \alpha \nabla L[\phi]$

where  $\alpha$  is the learning rate.

# What should the learning rate be?

• Try  $\alpha = 1$ .

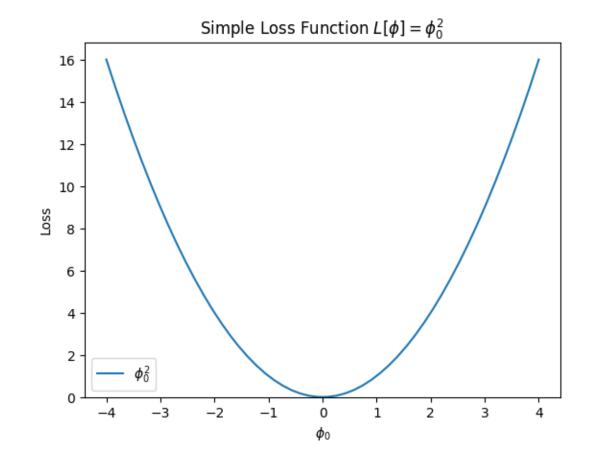
- Too small, and it takes many steps to get close.
- Too big, and it overshoots.



# Convex Loss Functions

 Generally, a lot easier to optimize...

 With gradient descent, main issue is not overshooting minimum too much.



#### Non-Convex Loss Functions

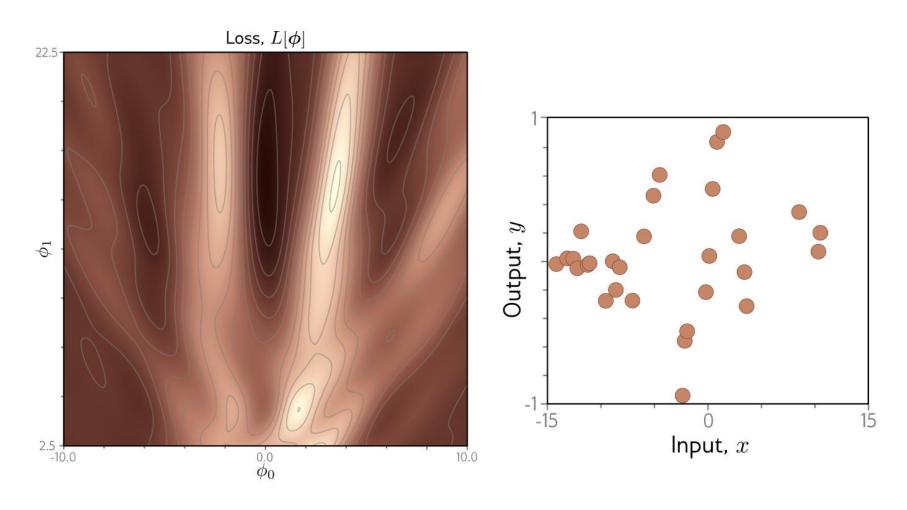
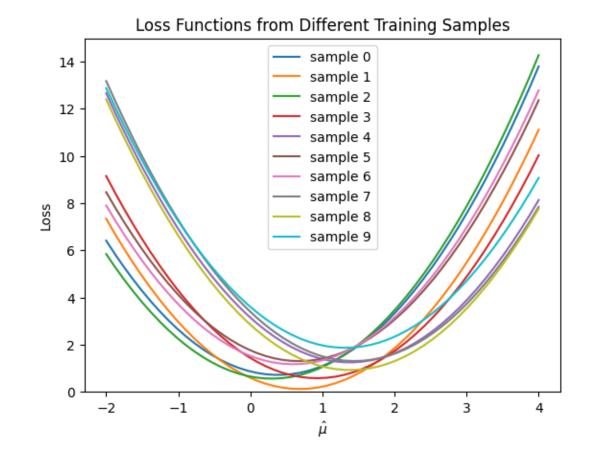


Image Source: Understanding Deep Learning, via https://udlbook.github.io/udlfigures/

# Any questions?

### Gradient Descent as a Statistical Process

- Our training data is a sample of the whole population.
  - Different training samples yield different training loss functions.



# Loss Functions for Different Training Samples

• If we collect different training data sets, will we get different models?

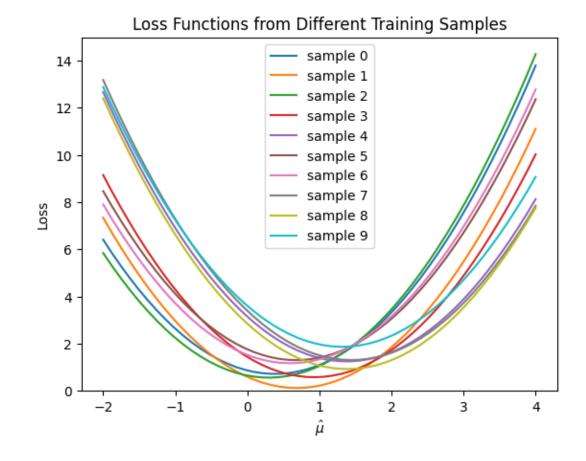
# Loss Functions for Samples of the Training Set

• If we sample the training data, will we get different models?

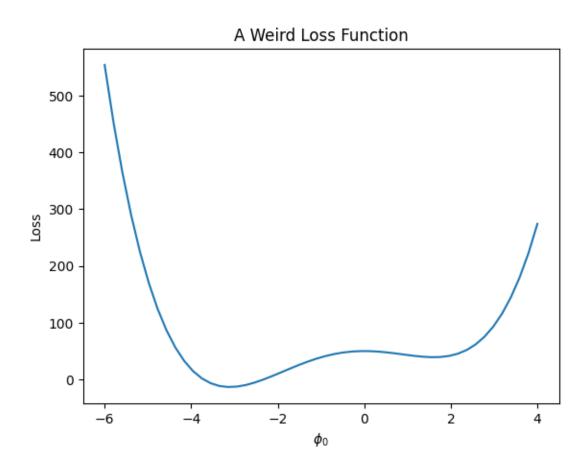
# Comparing Models with Different Training Samples

 How far apart are the models of these samples?

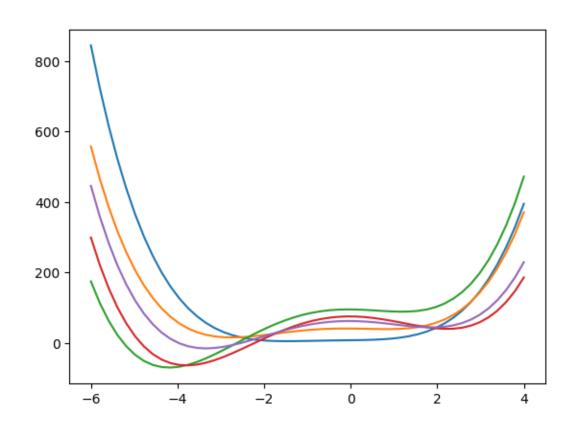
 Where do they agree and disagree?



### A Weird Loss Function



# Local Minima vs Samples of the Training Set



#### Stochastic Gradient Descent

Idea: Run gradient descent with "mini batches" instead of the full training set.

- E.g. pick a random partition of data into 10 equal-sized batches.
- One epoch = running through all the data once.
  - Vanilla gradient → one parameter update.
  - Stochastic gradient descent → one parameter update per mini batch.

# Variation in Sampled Gradients

- Expected mini batch gradient = whole training set gradient.
  - On average, they agree.
  - But with noise from sampling.

- But remember, just taking one step with each mini batch.
  - Not optimizing to mini batch minimum loss.

#### Local Minima vs Stochastic Gradient Descent

 When far from a local minima, mini batches tend to agree on gradient direction.

- When close to a local minima, mini batches disagree more.
  - Sampling noise.
  - Explore the flat area around the minima.

# Speed of Stochastic Gradient Descent

How fast is this compared to vanilla gradient descent?

# Any questions?

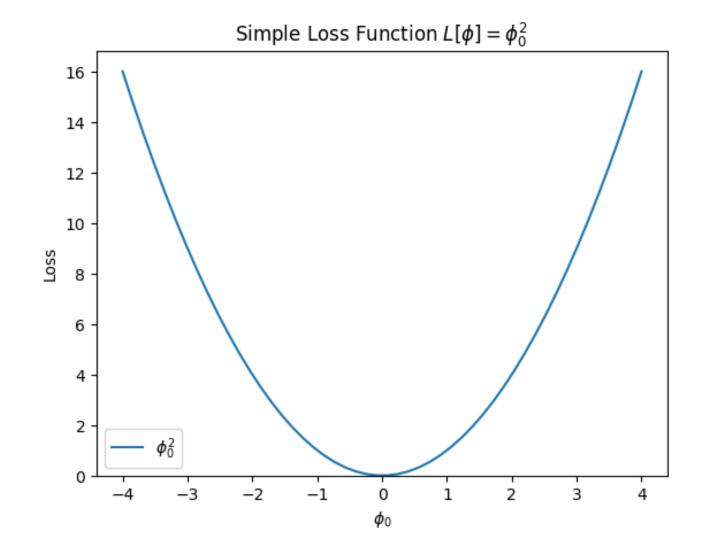
# Gradient Descent as a Universal Algorithm

What's the catch?

# How do we pick Learning Rate?

• Remember,  $\alpha = 1$  gives an infinite loop.

Also, be impatient.



# Really Bad Linear Regression

• 
$$f(x) = f_1\left(f_2\left(f_3(f_4(x))\right)\right)$$

$$\bullet f_1(x) = a_1 x + b_1$$

$$\bullet f_2(x) = a_2 x + b_2$$

• 
$$f_3(x) = a_3x + b_3$$

• 
$$f_4(x) = a_4 x + b_4$$

# Really Bad Linear Regression (part 2)

• 
$$f(x) = f_1\left(f_2\left(f_3(f_4(x))\right)\right)$$

$$\bullet f_1(x) = a_1 x + b_1$$

$$\bullet f_2(x) = a_2 x + b_2$$

$$\bullet f_3(x) = a_3 x + b_3$$

$$\bullet f_4(x) = a_4 x + b_4$$

• Initialize all parameters to zero.

What are the gradients?

# Really Bad Linear Regression (part 3)

• 
$$f(x) = f_1\left(f_2\left(f_3(f_4(x))\right)\right)$$

$$\bullet f_1(x) = a_1 x + b_1$$

$$\bullet f_2(x) = a_2 x + b_2$$

$$\bullet f_3(x) = a_3 x + b_3$$

$$\bullet f_4(x) = a_4 x + b_4$$

• Initialize all parameters to 100.

What are the gradients?

# Really Bad Linear Regression (part 4)

• 
$$f(x) = f_1\left(f_2\left(f_3(f_4(x))\right)\right)$$

$$\bullet f_1(x) = a_1 x + b_1$$

$$\bullet f_2(x) = a_2 x + b_2$$

• 
$$f_3(x) = a_3 x + b_3$$

$$\bullet f_4(x) = a_4 x + b_4$$

 We will see both these problems with neural networks if we use the wrong initialization.

# Any questions?